

on start

- set Servo Angle to 0
- radio set group 1
- Motor M1 dir CCW speed 255
- set toggle to 0

forever

- set Vbat to analog read pin P0
- show number analog read pin P0
- if Vbat ≤ 920 and toggle = 0 then
 - Motor stop M1
 - set toggle to 1
- if Vbat > 970 and toggle = 1 then
 - Motor M1 dir CCW speed 255
 - set toggle to 0

on radio received name value

- if name = "steer" and value > 0 then
 - Servo S1 degree value
 - show leds
 - clear screen
- else if name = "steer" and value < 0 then
 - Servo S1 degree value
 - show leds
 - clear screen