

# Alpha Helix – Rotation Angle Formula Breakdown

Original Formula

$$3 * \cos(\text{Rotation Angle}) = 1 - 4 * \left[ \cos \left[ \frac{\text{Dihedral Angle \#1} + \text{Dihedral Angle \#2}}{2} \right] \right]^2$$

## Modified Formula for the Python Program

$$\text{Rotation Angle} = \arccos \left[ \frac{1 - 4 * \left[ \cos \left[ \frac{\text{Dihedral Angle \#1} + \text{Dihedral Angle \#2}}{2} \right] \right]^2}{3} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \frac{1 - 4 * \left[ \cos \left[ \frac{\text{AngleOnePlusAngleTwoOverTwo}}{2} \right] \right]^2}{3} \right]$$

Convert to radians so that math.cos(x) can calculate it!

$$\text{TopInRadians} = \text{math.radians} \left[ \frac{\text{AngleOnePlusAngleTwoOverTwo}}{2} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \frac{1 - 4 * \left[ \cos \left[ \text{TopInRadians} \right] \right]^2}{3} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \frac{1 - 4 * \text{CosineOfTop}^2}{3} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \frac{1 - 4 * \text{CosineOfTopSquared}}{3} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \frac{1 - \text{FourTimesCosineSquared}}{3} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \frac{\text{OneMinusFourTimesCosineSquared}}{3} \right]$$

$$\text{Rotation Angle} = \arccos \left[ \text{DividedBy3} \right]$$

$$\text{ArccosInRadians} = \text{acos} \left[ \text{DividedBy3} \right]$$

$$\text{Rotation Angle} = \left[ \text{math.degrees}(\text{ArccosInRadians}) \right]$$