

## ETHERNET SHIELDS V2

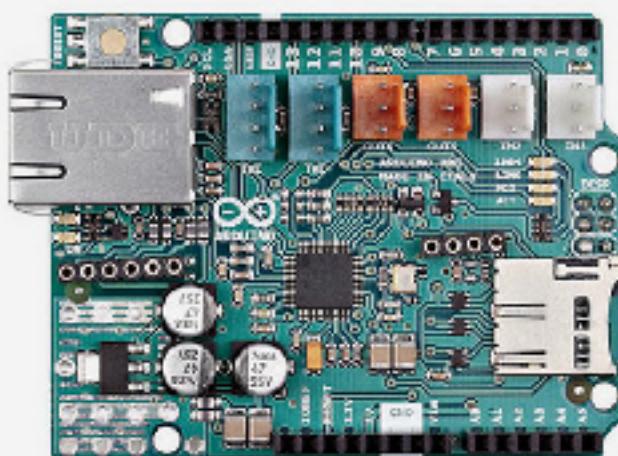
### 0-Settings of AdvancedHMI:

I used AdvancedHMI to check the Modbus TCP communication. The pushbutton has the address 40010 (Mb[9] register on Arduino board) and light on pin D7 on Arduino board. The digitalPanelmeter has the address 40011 (Mb[10] register on Arduino board). The Ethernet shield has the IP Address 192.168.1.144, MSK /24, GTW 192.168.1.1.



### 1-Arduino Ethernet shield V2 based on W5500

On the site : <https://www.arduino.cc/en/Main/ArduinoEthernetShieldV2>



Arduino Ethernet  
Shield V2

The Arduino Ethernet Shield 2 connects your  
Arduino board to the internet

GETTING STARTED

The library to use: <https://www.arduinolibraries.info/libraries/ethernet2>

# Ethernet2

Enables network connection (local and Internet) using W5100 based ethernet shields.

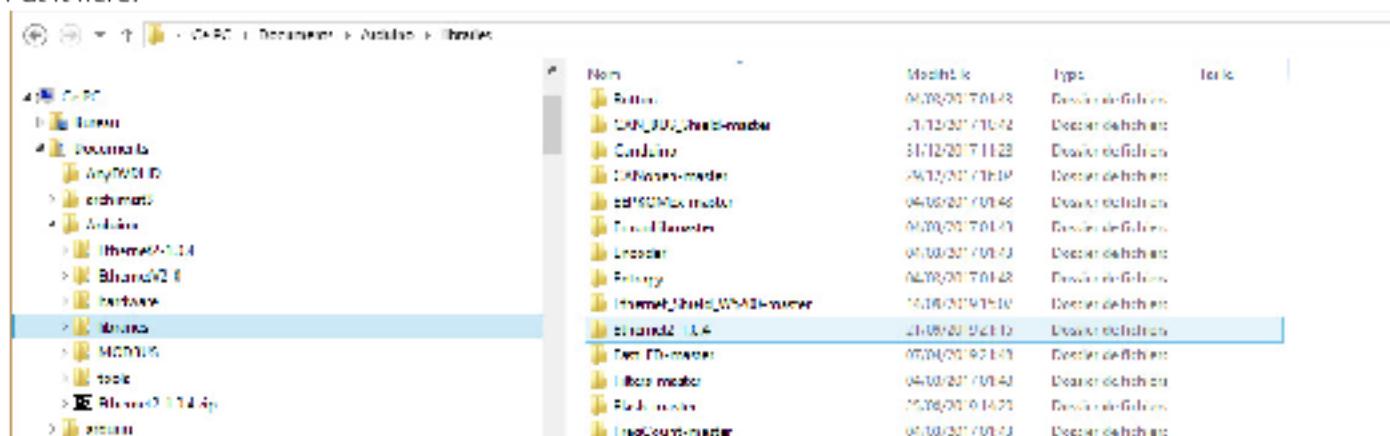
Author	Various
Maintainer	Adarull
Website	<a href="https://github.com/adarull/Ethernet2">https://github.com/adarull/Ethernet2</a>
Category	Communication
License	NOASSERTION
Library Type	Contributed
Architectures	Any

With this library you can use W5100 based Ethernet shields, such as the Arduino Ethernet Shield v2 to connect to Internet, but not older W5100 based shields. The library provides both Client and server functions like the library provides you to connect to a local network over with DHCP and to resolve DNS.

## Downloads

Filename	Release Date	File Size
Ethernet2-1.0.4.zip	2017-02-20	64.44 KB
Ethernet2-1.0.3.zip	2016-11-23	64.38 KB
Ethernet2-1.0.2.zip	2016-08-30	63.61 KB
Ethernet2-1.0.1.zip	2016-06-23	63.61 KB
Ethernet2-1.0.0.zip	2016-05-27	63.60 KB

Put it here:



Modify the modbus lib like this: change in modbus.h

Available in <https://github.com/luizcantoni/modbus>

Take a look at: <http://blog.industrialshields.com/en/modbus-tcpip-library-for-arduino-based-plcs/>

```
13 // This library is free software; you can redistribute it and/or
14 // modify it under the terms of the GNU General Public License
15 // as published by the Free Software Foundation; either version 2
16 // of the License, or (at your option) any later version.
17 //
18 // This library is distributed in the hope that it will be useful,
19 // but WITHOUT ANY WARRANTY; without even the implied warranty of
20 // MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the GNU
21 // General Public License for more details.
22 //
23 // You should have received a copy of the GNU General Public License
24 // along with this program. If not, see <http://www.gnu.org/licenses/>.
25 */
26
27 //#define NDEBUG
28
29 // For Arduino 0012
30 // #include "WProgram.h"
31 // For Arduino 1.0
32 #include "Arduino.h"
33
34 #include <CRPT.h>
35 //#include <Ethernet.h>
36 //fromone<Ethernet2.h>
37 //#include <EthernetLV2.h>
38
39 #ifndef Modbus_h
40 #define Modbus_h
41
42 #define MAX_R 120 //Max 16 bit registers for Modbus is 120
43 #define MAX_N_4_120 //Max write for Modbus is 2^4 = 16 need check using so here use multiple of 8
44 #define HB_PORT 502
45
```

The example of sketch:

```
#include <SPI.h>
#include <Ethernet2.h>

#include "Modbus.h"

Modbus Mb;
//Function codes 1(read coils), 3(read registers), 5(write coil), 6(write register)
//signed int Mb.R[0] to 128| and bool Mb.C[0] to 128| MB N R MB N C
//Port 502 (defined in Modbus.h) MB_PORT

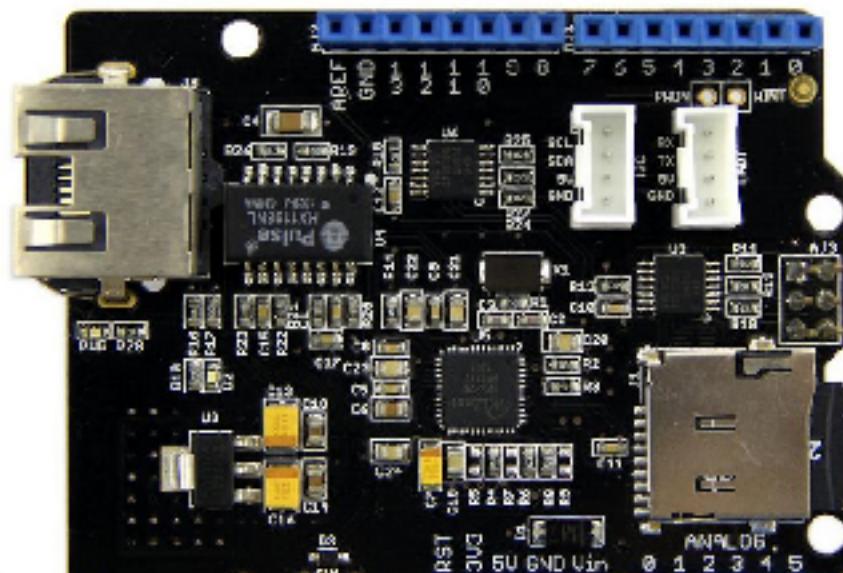
void setup()
{
    uint8_t mac[] = { 0x5E, 0xCF, 0xF, 0x86, 0x4D, 0xF1 };
    uint8_t ip[] = { 192, 168, 1, 144 };
    uint8_t gateway[] = { 192, 168, 1, 1 };
    uint8_t subnet[] = { 255, 255, 255, 0 };
    Ethernet.begin(mac, ip, gateway, subnet);
    //Avoid pins 4,10,11,12,13 when using ethernet shield
    delay(5000);
    Serial.begin(9600);
    pinMode(7, OUTPUT);
}

void loop()
{
    Mb.Suz();
    /*
     *Analog inputs I-1023
    Mb.R[40] = analogRead(A0); //pin AC to Mb.R[0]
    Mb.R[41] = analogRead(A1);
    Mb.R[42] = analogRead(A2);
    Mb.R[43] = analogRead(A3);
    Mb.R[44] = analogRead(A4);
    Mb.R[45] = 6666; //analogRead(A5);
    //Analog outputs 0-255
    analogWrite(6, Mb.R[100]); //pin ~6 from Mb.R[6]
    */
    //Digital inputs
    //Mb.R[47] = digitalRead(24); //pin 7 to Mb.C[7]
    //Mb.R[47] = 1024; //pin 7 to Mb.C[7]
    //Mb.R[5] = digitalRead(10);
    digitalWrite(0, Mb.R[91]);
    Mb.R[10] = 4385;
}
```

2-Arduino Ethernet shield V2.0 Seeeduino based on W5200

On the siwebsite: [http://wiki.seeedstudio.com/Ethernet\\_Shield\\_V2.0/](http://wiki.seeedstudio.com/Ethernet_Shield_V2.0/)

## Ethernet Shield v2.0

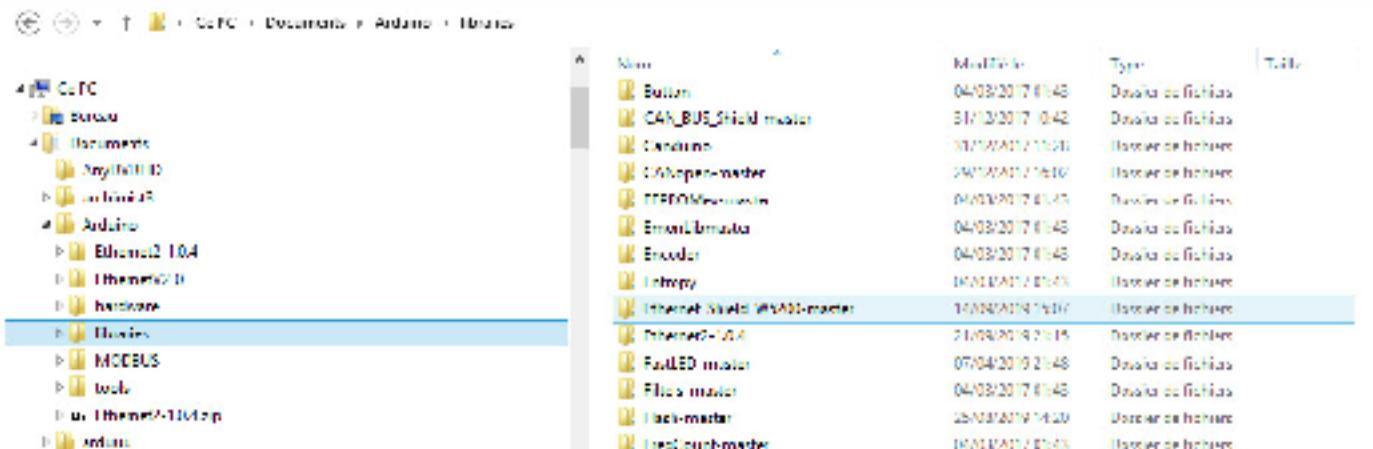


The library to use: [https://github.com/Seeed-Studio/Ethernet\\_Shield\\_W5200](https://github.com/Seeed-Studio/Ethernet_Shield_W5200)

A screenshot of a GitHub repository page. The URL in the address bar is 'https://github.com/ISeeed-Studio/ethernet\_shield\_WS2800'. The page title is 'ISeeed-Studio / ethernet\_shield\_WS2800'. Below the title, there are tabs for 'Code', 'Issues', 'Pull requests', 'Topics', 'Actions', 'Settings', and 'Merge pull requests'. A large central banner features the text 'Join GitHub today' with a green 'Sign up' button. To the right of the banner, there is a 'Compare' button. At the bottom of the page, there is a 'Clone or download' section with options for 'HTTPS', 'SSH', and 'Git'. The main content area is currently empty.

Some studies [there] think it's a theory. <https://www.ncbi.nlm.nih.gov/pmc/>

Put it here:



Modify the mudbus lib like this: change in mudbus.h

Available in <https://github.com/luiscantoni/mudbus>

```
10 // This file is part of the Arduino Mudbus library.
11 // You should have received a copy of the GNU General Public License
12 // along with this program. If not, see https://www.gnu.org/licenses/.
13 */
14
15 // If you are using the Arduino Uno
16 // #include "WProgram.h"
17 // For Arduino 0022
18 // #include "WProgram.h"
19 // For Arduino 1.0
20 // #include "Arduino.h"
21
22 // #include <SPI.h>
23 // #include <Ethernet.h>
24 // #include <Ethernet2.h>
25 // #include <EthernetEV2.h>
26 // #include <EthernetV2.h>
27 // #include <Ethernet2.h>
28 // #include <EthernetEV2.h>
29 // #include <EthernetEV2_0.h>
30 // #include <EthernetEV2.h>
31 // #include <EthernetEV2.h>
32
33 // #define MH_N_R 120 //Max 16 bit registers for Modbus is 120
34 // #define MH_N_C 100 //Max coils for Modbus is 250 - you need check many so here is a multiple of 8
35 // #define MH_POINT 500
36
```

The exemple of sketch:

```
WS2005
#include <SPI.h>
#include <EthernetEV2_0.h>
#include "Mudbus.h"

Modbus Mb;

byte user[] = {
  0x0E, 0x0D, 0x0E, 0x0F, 0x0F, 0x0D
};

IPAddress ip(192, 168, 1, 144);
IPAddress gateway(192, 168, 1, 1);
 IPAddress subnet(255, 255, 255, 0);

// Take a MAC address and IP address for your controller below.
// The IP address will be dependent on your local network.
// gateway and subnet are optional.
// Initialize the Ethernet server library
// with the IP address and port you want to use
// (port 80 is default for HTTP):
//EthernetServer server(802);

#define w5200_m 10
#define SDIARD_CS 4
```

```
void setup() {
  // start the SPI library:
  SPI.begin();
  pinMode(SDWE&#39;_CS, OUTPUT);
  digitalWrite(SDWE&#39;_CS, HIGH); // deselect the SD card
  // start the Ethernet connection and the server:
  Ethernet.begin(mac, ip, gateway, subnet);

  //server.begin();

  delay(1000);
  pinMode(7, INPUT);

}

void loop() {
  Kb.R[0];
  /*
  //Analog inputs 0-1023
  Mb.R[40] = analogRead(A0); //pin A0 to Mb.R[0]
  Mb.R[41] = analogRead(A1);
  Mb.R[42] = analogRead(A2);
  Mb.R[43] = analogRead(A3);
  Mb.R[44] = analogRead(A4);
  Mb.R[45] = analogRead(A5);
  //Analog outputs 0-255
  analogWrite(F, Mb.R[100]); //pin -6 from Mb.R[F]
  */
  //Digital inputs
  //Mb.S[47] = digitalRead(24); //pin 7 to Mb.C[7]
  //Mb.S[47] = 1024; //pin 7 to Mb.C[7]
  //Mb.S[9] = digitalRead(10);
  digitalWrite(7, Mb.R[9]);
  Kb.R[10] = 666;
}
```