Internet Of Things CA2

Step-By-Step Tutorial

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Class: DBIT/FT/3B/32

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Section 1 : Overview of the Application

A. What is the application about?

This IOT system is a Home Entertainment and Security system.

1. Security
    a. Tap RFID Card and input are saved into Firebase.
    b. If authorized, you can enter peacefully and the picture is taken and uploaded to S3
    c. If unauthorized, defence section comes in and an LCD Screen will say you're not authorized.
2. Defence
    a. Press button on dashboard.
    b. Laser Turrets will attack in random burst and speed.
3. Entertainment
    a. If motion is detected, game will start.
    b. After user plays game, score is saved into Firebase.
    c. LDR values will be taken and output on the dashboard.

This application is controllable and viewable via the IBM Node Red web server. We make use of AWS and IBM Cloud Services and we used Firebase as our Database.

A tutorial of this is uploading onto Instructables and you can view it at this link:

https://www.instructables.com/id/Overview-Home-Entertainment-and-Security-System/

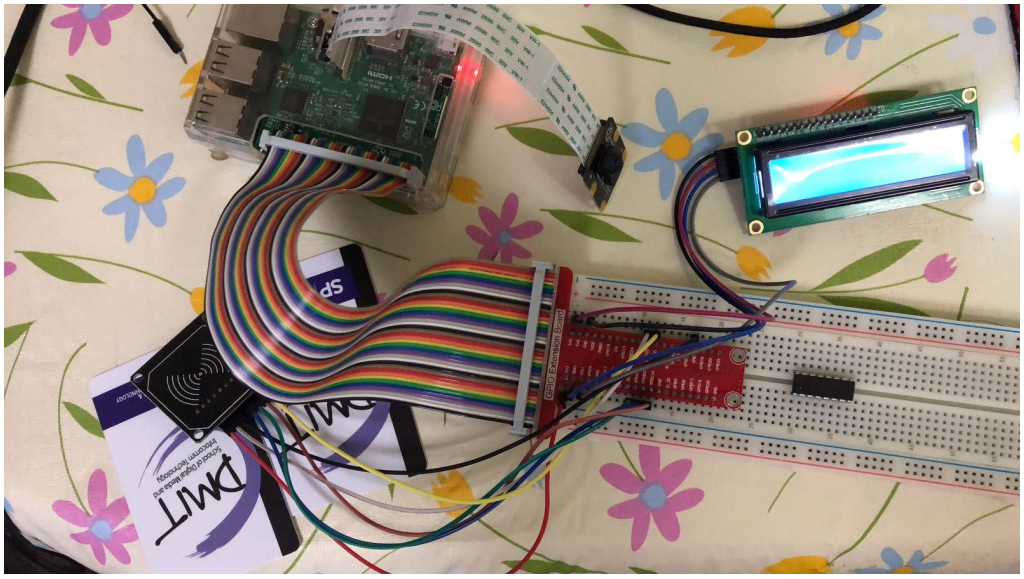
B. Summary of the steps that will be described

#	Section	Description
1	**Overview of the Application**	**A summary of what this tutorial is about.**
2	**Hardware Requirements**	**What hardware you need to create the security, defence and entertainment section.**
3	**Security**	**How to create security system**
	Hardware	How to connect the parts together
	Software	security.py is a code that will read rfid inputs and detect whether user is an intruder or not. If user is recognised, an image will be taken and uploaded to s3. The code also publishes to a topic in aws MQTT
4	**Defence**	**How to create a laser turret**
	Hardware	How to connect the parts together and most importantly, how to create the turret itself.
	Software	Laserturret.py is a code that triggers the laser turret. It shoots laser beams in random directions in random bursts and speed.
5	**Entertainment**	**How to create a simon-says game**
	Hardware	How to connect the parts together.
	Software	Entertain.py is the game code where you have to follow the pattern of the LEDS lighting up and press the corresponding buttons. It uploads scores and timestamp

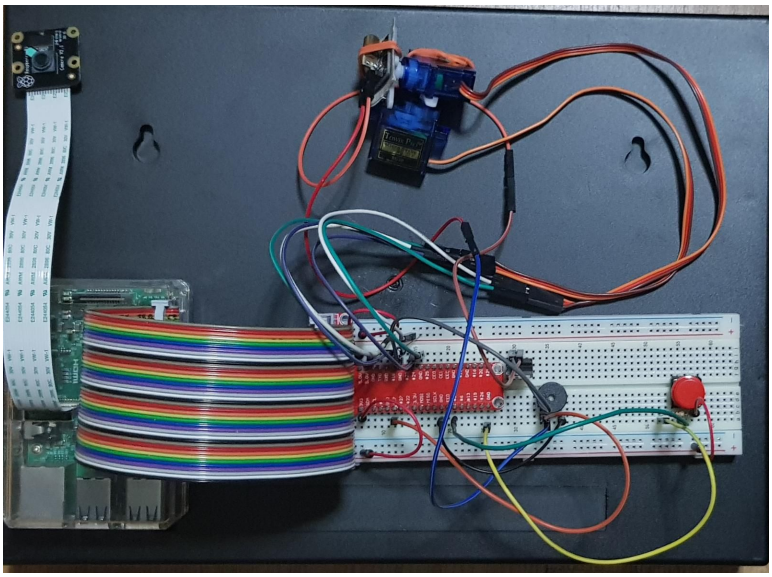
		into the firebase nosql database for further usage in the dashboards.
6	**IOT App Watson on IBM Bluemix**	**Creating a dashboard and interacting with multiple RPi from one dashboard.**
	Set up Bluemix IoT Service	Connecting different Pi to the same account
	Set up Node-Red	Downloading palettes to use in our node-red flow
	Security	
	Defence	Creating the node-red flow on RPi and on Bluemix.
	Entertainment	

C. How does the final RPI setup look like?

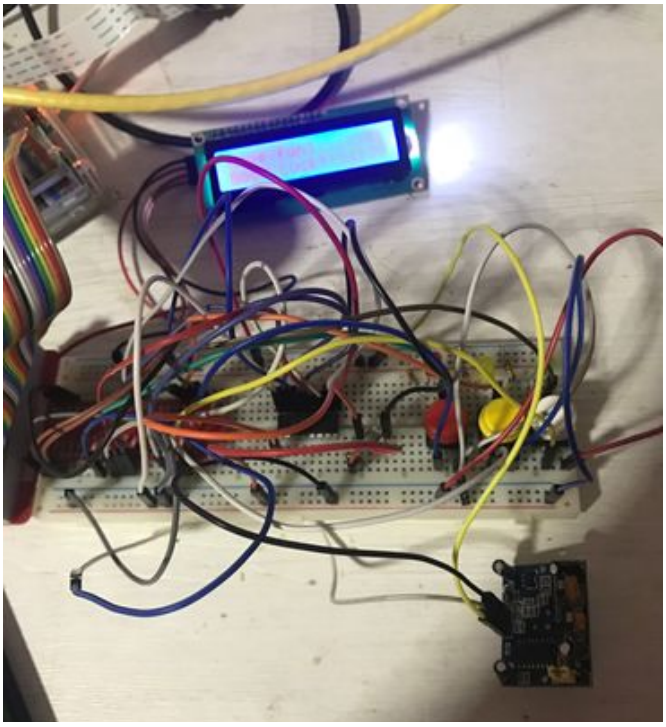
a. Security



b. Defence



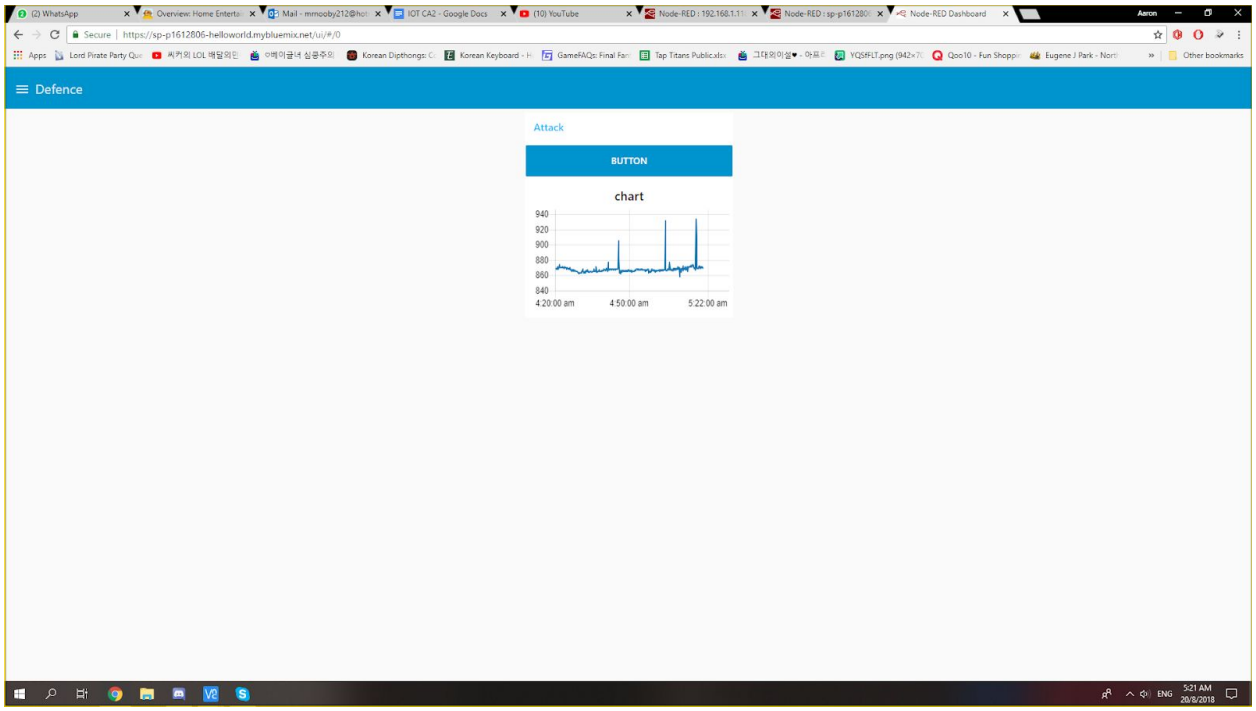
c. Entertainment



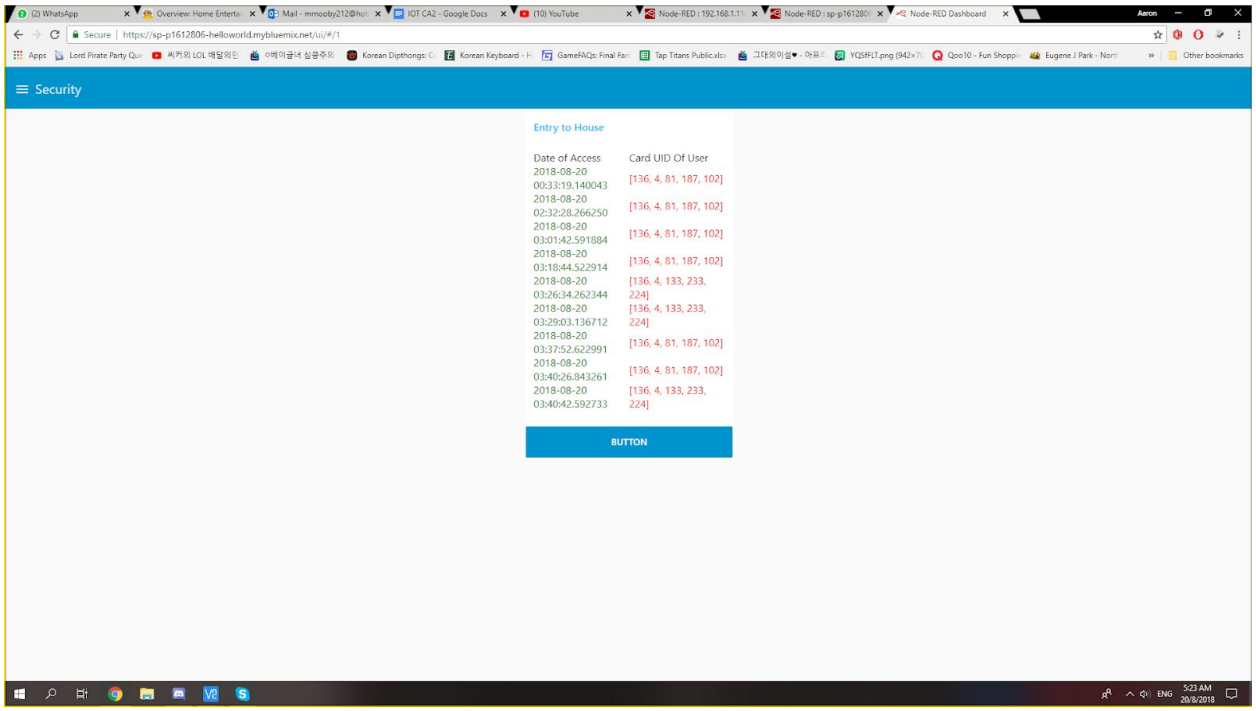
D. How does the web application look like?

As the we have created our dashboard for mobility usage on mobile phones, we decided to use a mobile responsive dashboard layout which will look better on the mobile phone. However, we still are going to show screenshots on it being opened on a web browser on a computer.

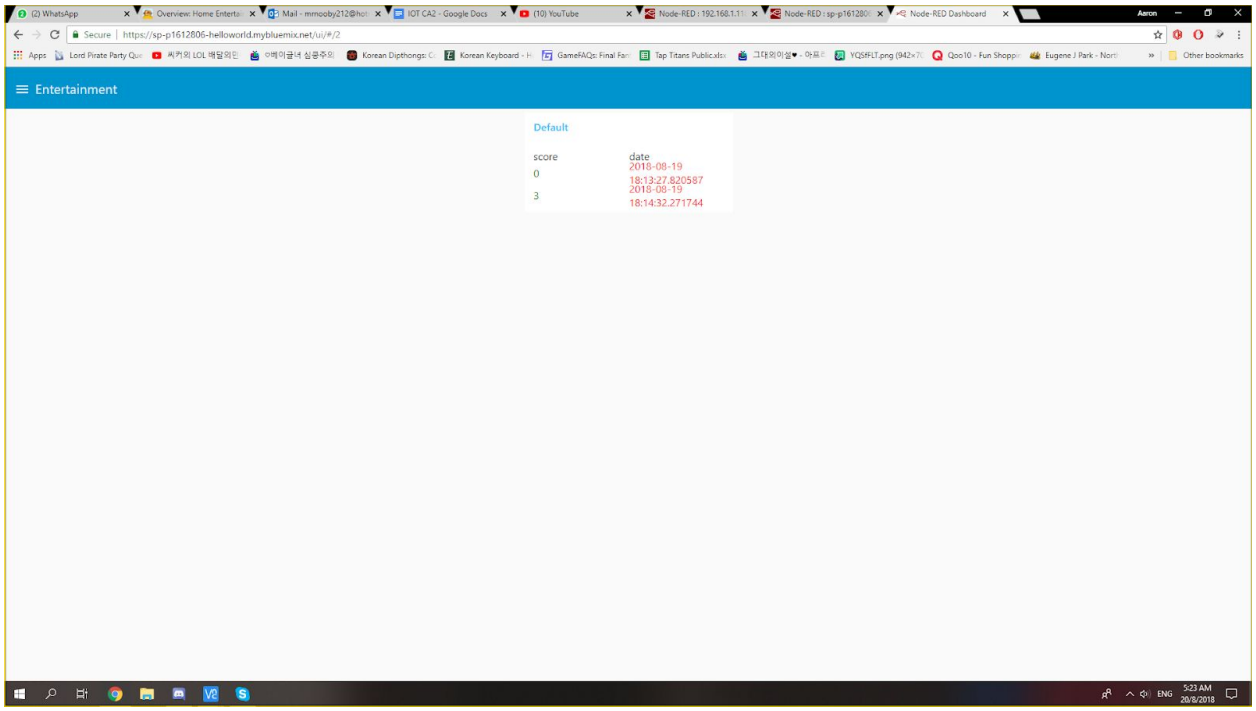
Defend + Light page



Access page



Scoreboard page



Section 2 : Hardware Requirements

A. Hardware Checklist

a. Security

- 1 Raspberry Pi
- 1 LCD
- 1 RFID Reader
- 1 PiCam
- 2 RFID Cards/Buttons
- X Female -> Male jumper cables

b. Defence

You will need

- 1 Raspberry Pi

- 2 10 kΩ Resistor (for Buttons)
- 2 Micro Servo
- 1 650nm Laser Transmitter Module
- 2 Push Button
- 1 Buzzer
- 3 Small Rubber Bands/Cable Ties (for fixing)
- X Female -> Male jumper cables
- X Regular Jump Cables
- 1 Transistor
- 1 Capacitor

c. Entertainment

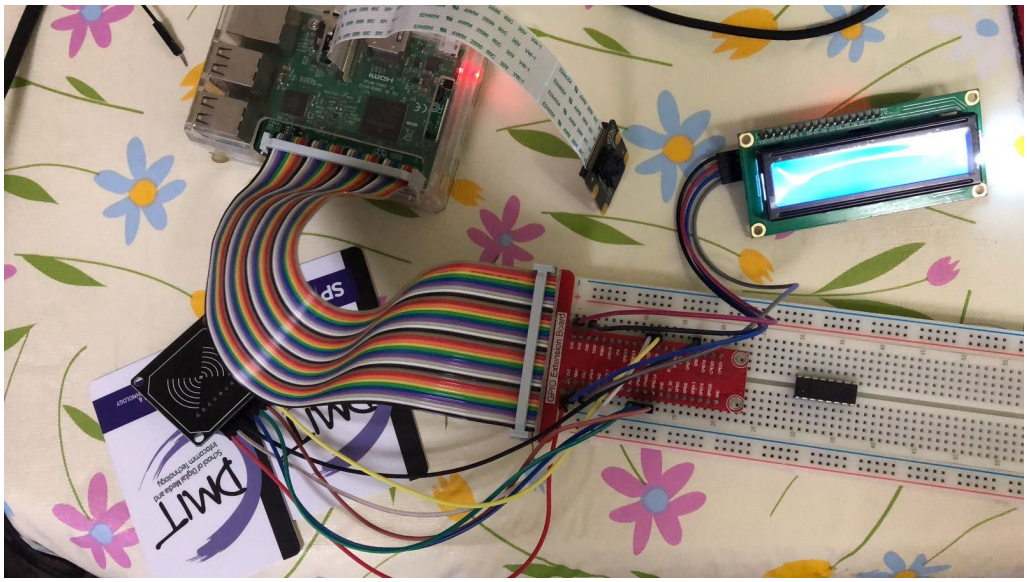
You will need

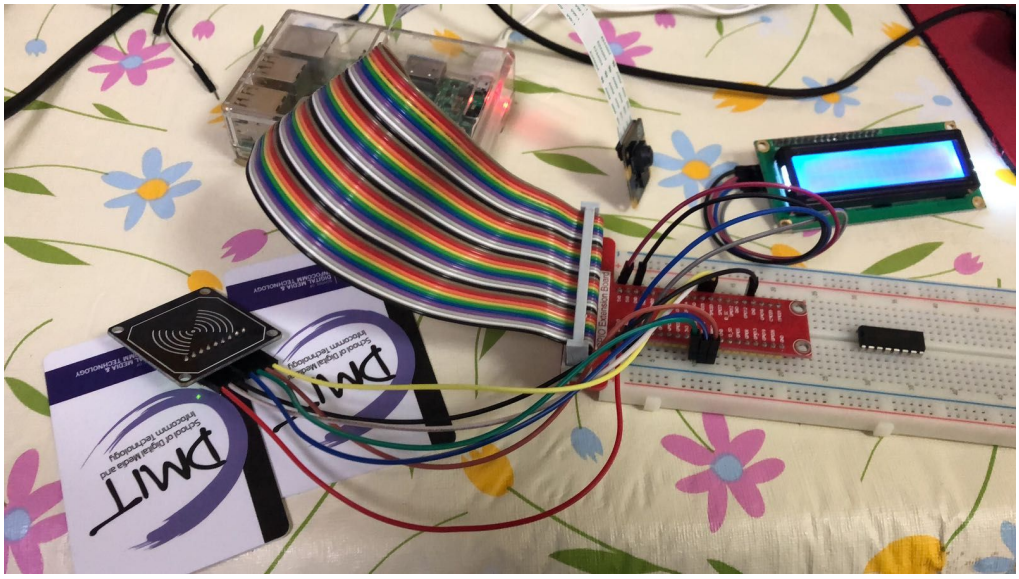
- 1 Raspberry Pi
- 3 1 kΩ Resistor (for LEDs)
- 1 10kΩ Resistor (for LDR)
- 3 LEDs (Different Colors)
- 3 Buttons
- 1 LDR
- 1 LCD
- 1 Pir Motion Sensor
- X Female -> Male jumper cables
- X Regular Jump Cables

Section 3 : Security

A. Hardware setup

A. This is what your finished connection should look like





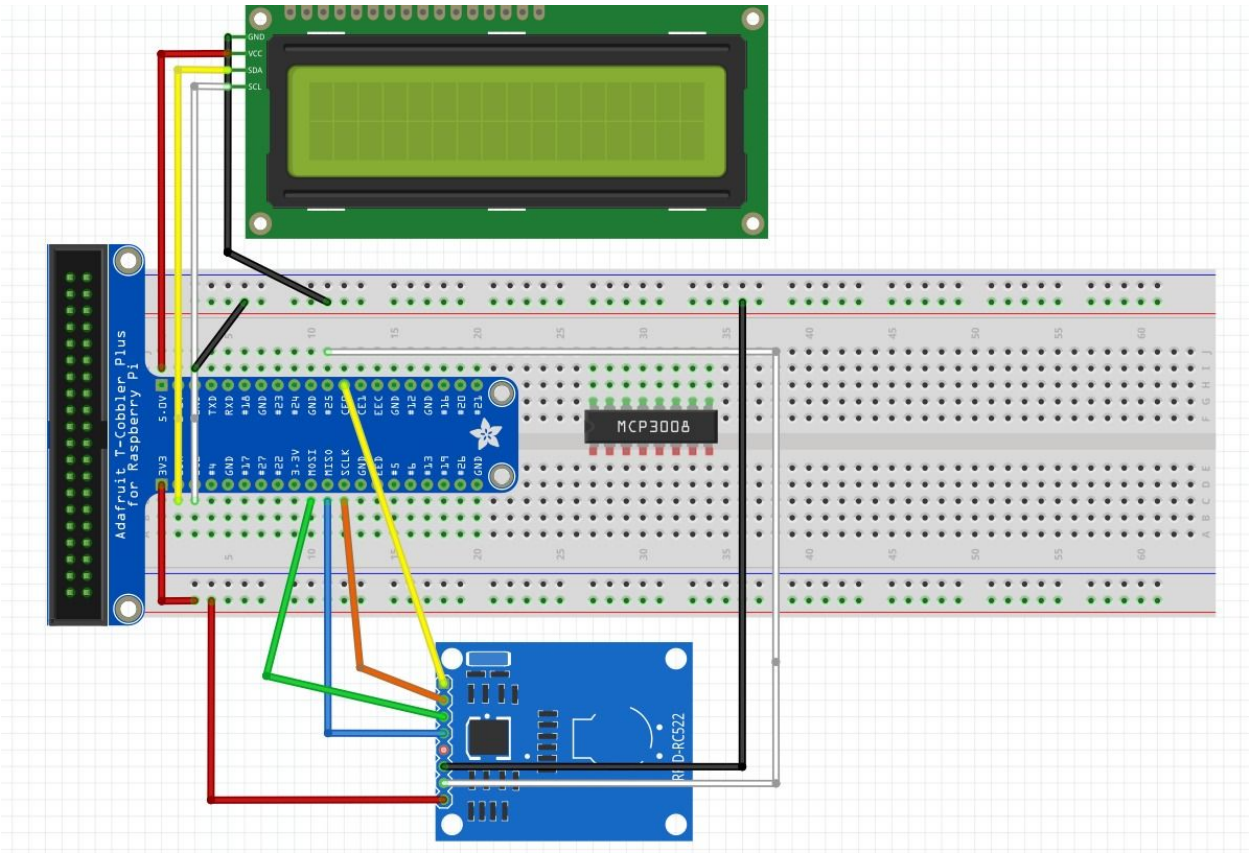
For the LCD, connect the following pins on the LCD to the RPI

Jumper color	LCD pin	RPi pin
White	SCL	SCL
Yellow	SDA	SDA
Black	GND	GND
Red	Vcc	5V

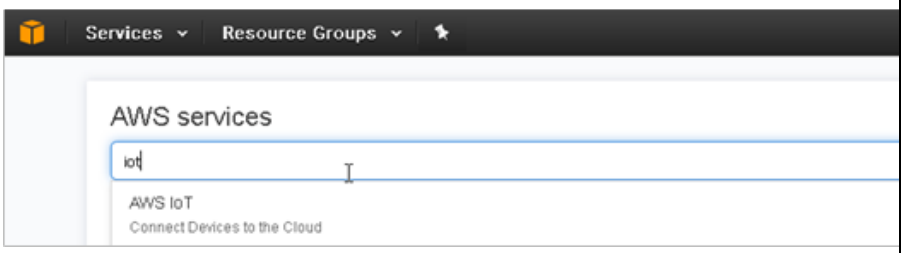
There are about 9 pins on the MFRCF522 reader given in your IoT kit. We will only be using 7 of them. Connect the pins on the MFRCF522 card reader to the RPi as indicated below.

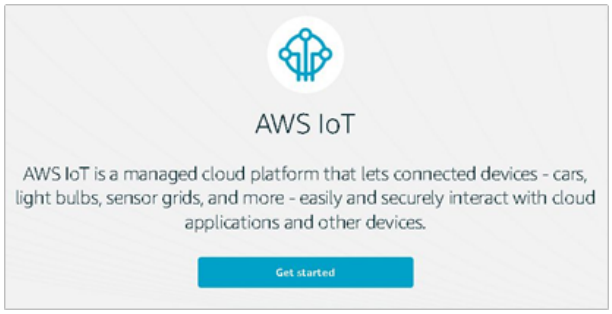
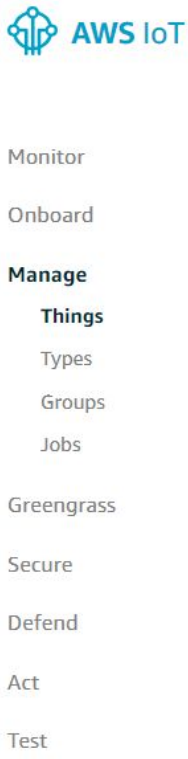
Jumper color	MFRCF522pin	RPi pin
Yellow	SDA	CE0
Orange	SCK	SCLK
Green	MOSI	MOSI
Blue	MISO	MISO
	IDR	
Black	GND	GND
White	RST	GPIO25
Red	3.3V	3.3V
	5V	

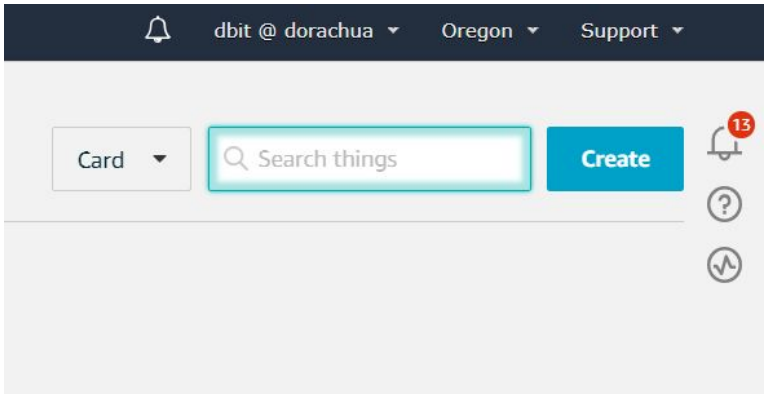
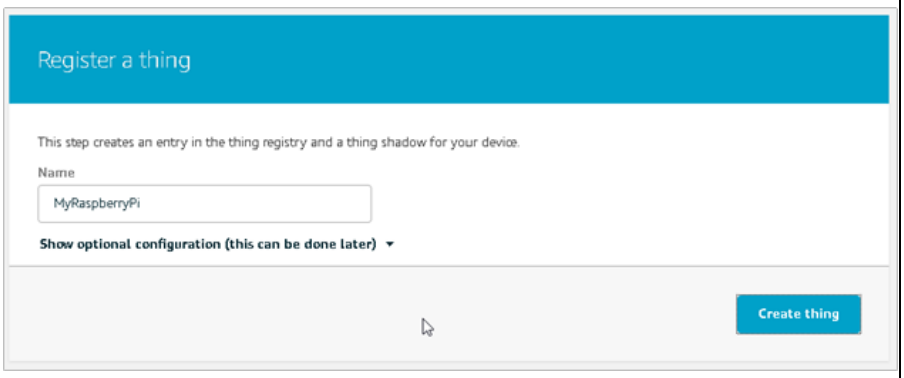
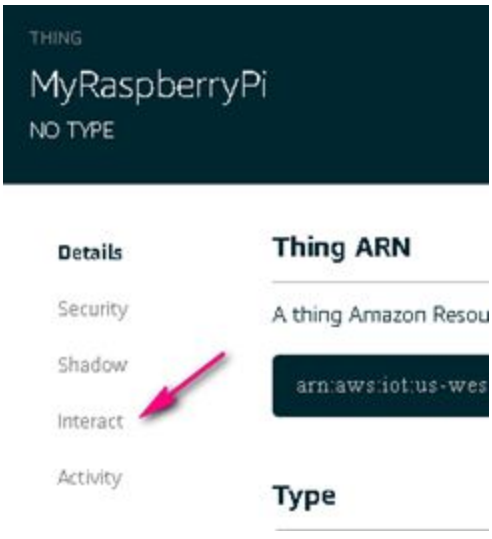
B. Fritzing Diagram

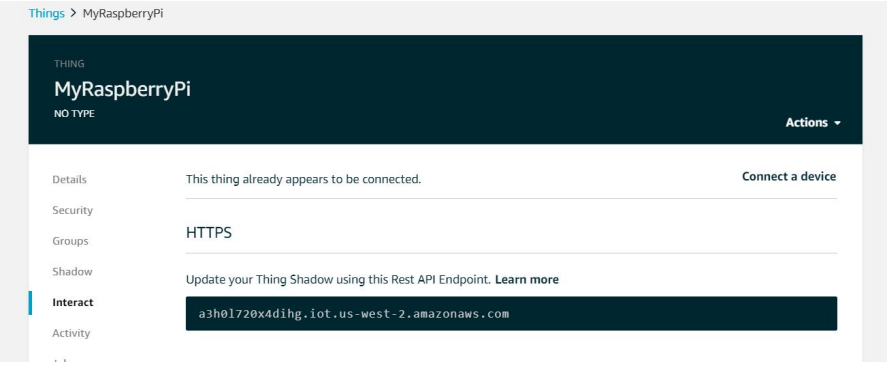
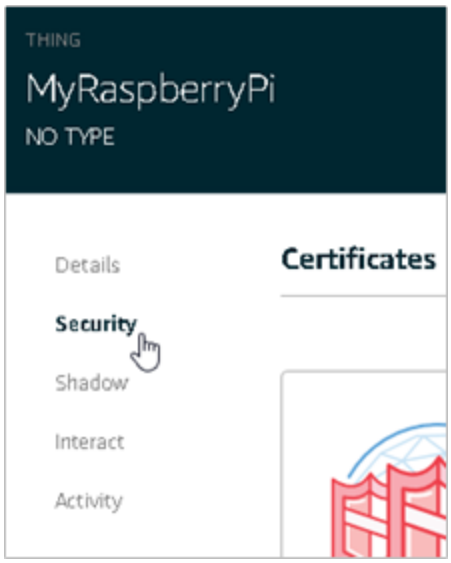
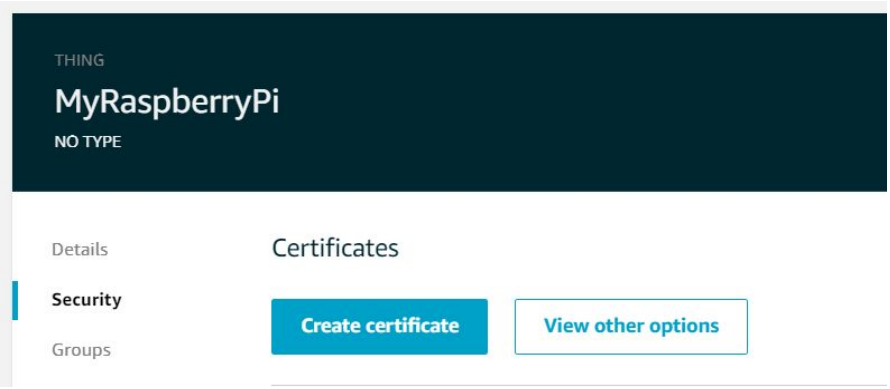


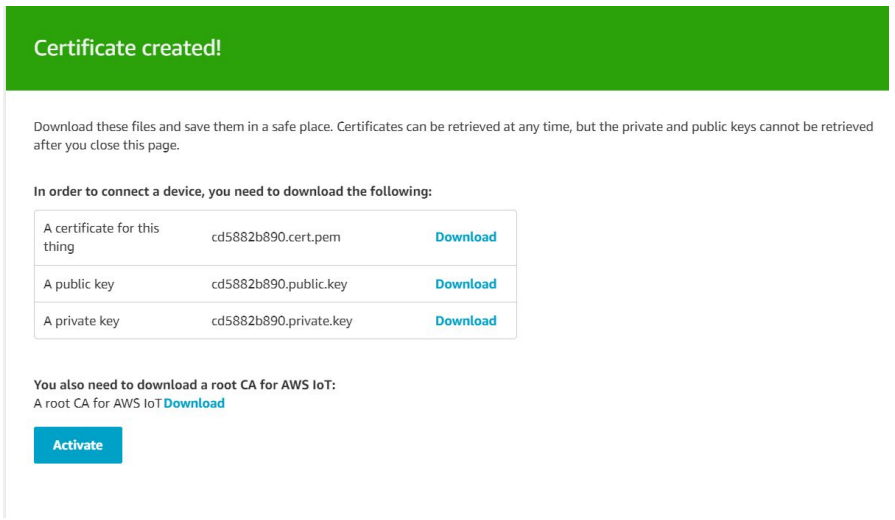
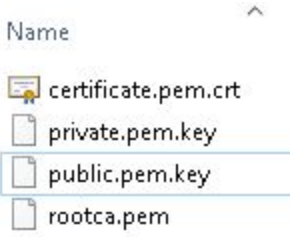
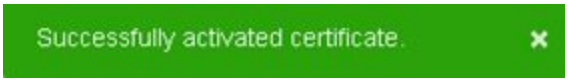
B. Configure AWS

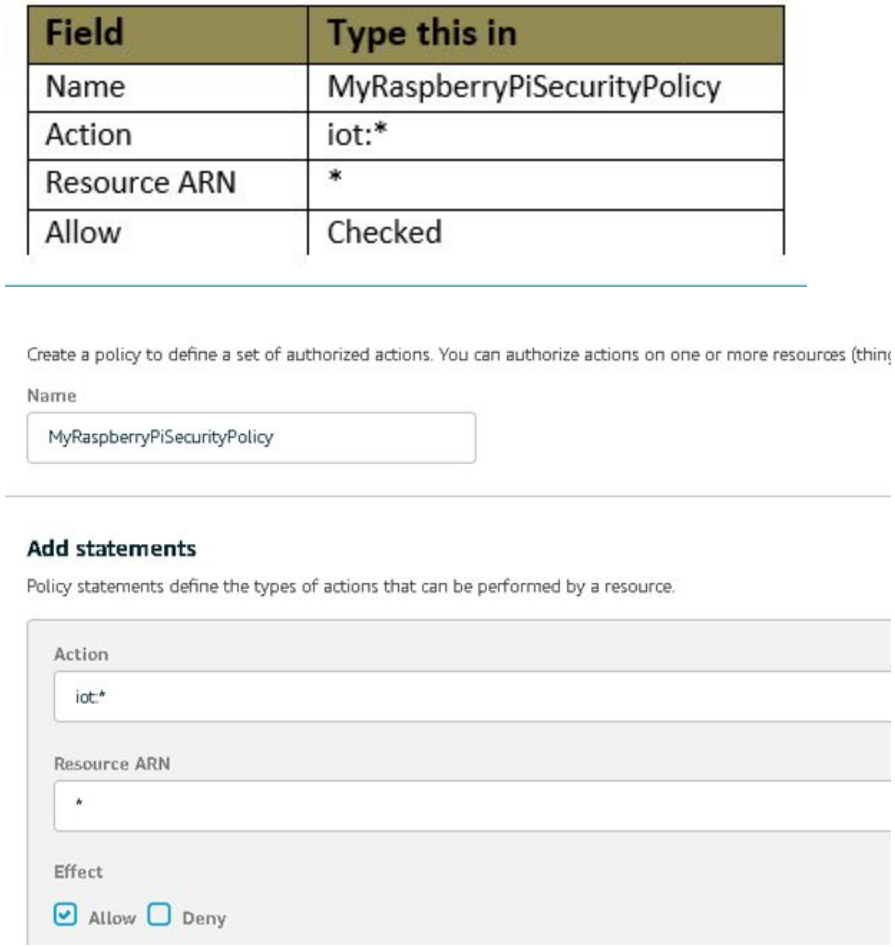
#	Description	Image
1	Turn on your Raspberry Pi and confirm you have an Internet connection. Sign in with your AWS console at https://aws.amazon.com In the AWS dashboard, type "AWS IoT" to access	

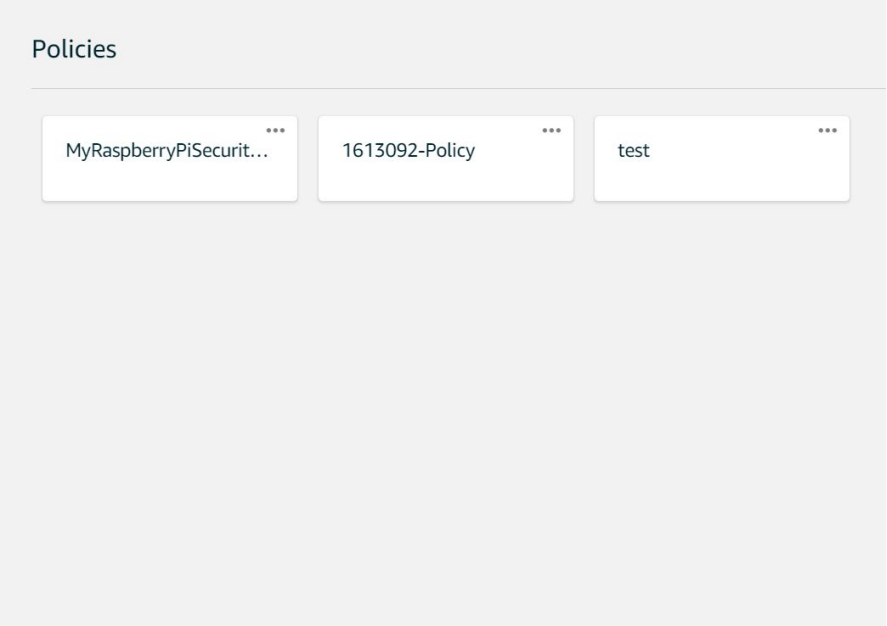
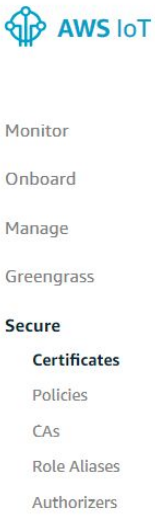
	the AWS IoT service.	
2	On the Welcome page, choose Get started	
3	In the left navigation pane, click “Manage” to expand it, then choose “Things”.	

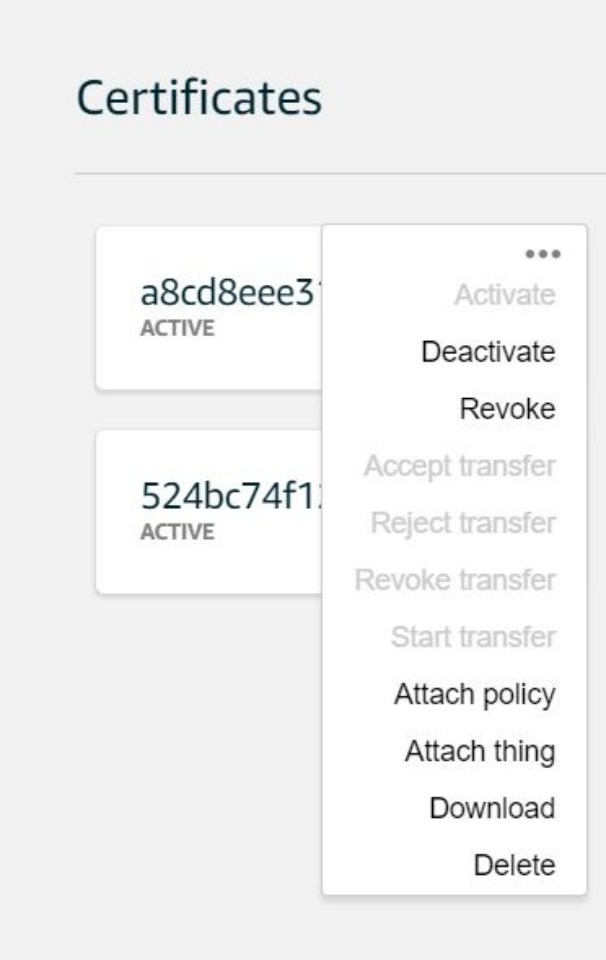
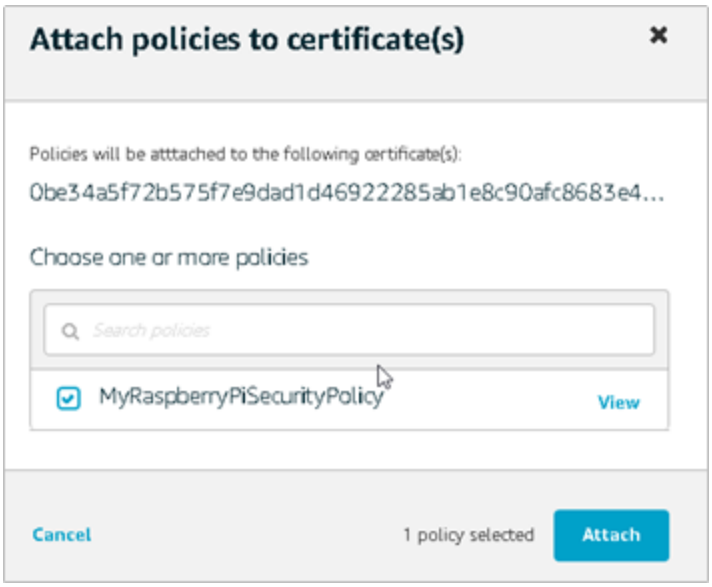
4	On the top right hand corner, you will see a button “create” Click on the button to create a thing	
5	A thing represents a device whose status or data is stored in the AWS cloud. The Thing Shadows is the state of the device, e.g. is it “on” or “off”, is it “red” or “green” etc. Our “thing” here is our RPi, so let’s type “MyRaspberryPi” for the name. Click “Create thing”	
6	On the Details page, choose **Interact**.	

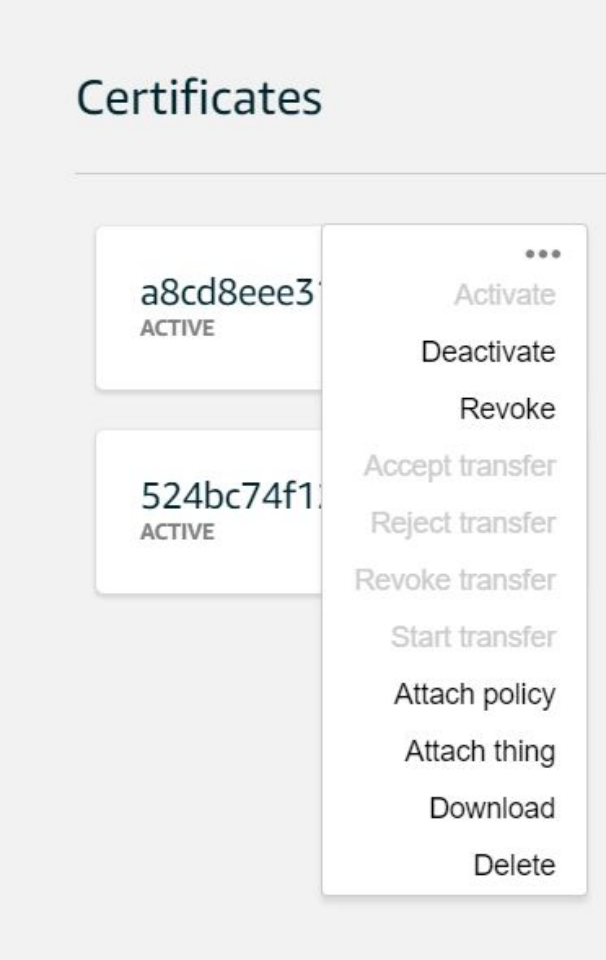
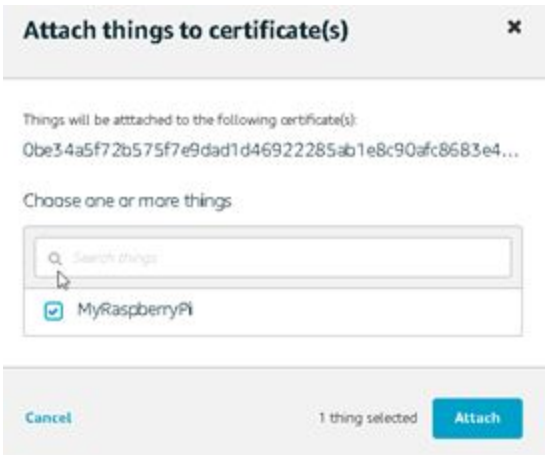
7	Copy and paste the REST API endpoint into a Notepad. You will need this value later.	
8	Next, choose **Security**	
9	Choose “Create certificate” to generate an X.509 certificate and key pair.	

10	After a while, you should see the following screen, where there are a total of **four** download links.	
11	Take note of the directory that you have downloaded the files into and change their filenames as shown	
12	Next, click the “Activate” button. Almost immediately, you should see “Successfully activated certificate” and the Activate button changes to “Deactivate”	
13	Next, click on the “Attach a policy” button that is near the bottoom right-hand corner of the page.	

14	On the next page, choose “Create new policy”	
15	On the Create a policy page, key in the following configuration and then click “**Create**”	

16	You will then see a similar page like this	
17	On the left nav bar, click “Secure and then, Certificates”	

18	From the certificate that you have created just now, click on the 3 dots and choose "**Attach Policy**"	
19	Check the "MyRaspberryPiSecurityPolicy" you created earlier and click "**Attach**" button.	

20	Attach the “Thing” to the certificate	
21	In the Attach things to certificate(s) dialog box, select the check box next to the thing you created to represent your Raspberry Pi, and then choose Attach	

C. Install AWS Python Library

Install the AWS Python library with this command

```
sudo pip install AWSIoTPythonSDK
```

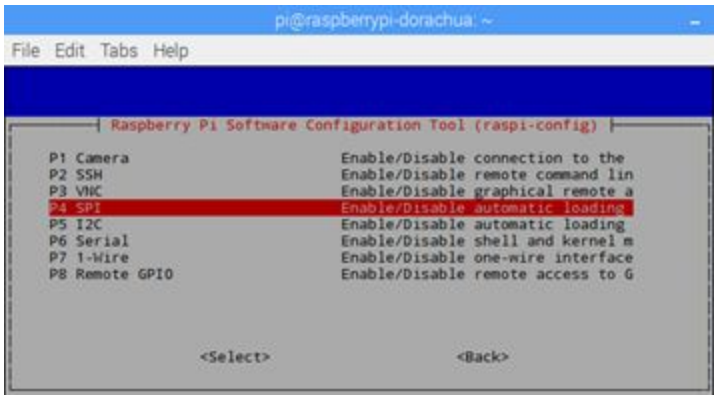
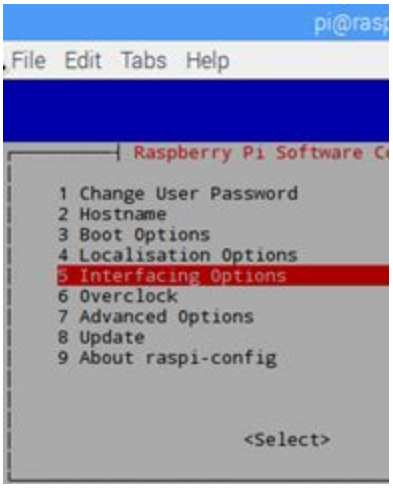
D. Install LCD Library

Install the LCD Library

```
sudo pip install rpi-lcd
```

E. Install RFID Library

#	Description
1	Enable SPI via raspi-config Run raspi-config, choose menu item “5 Interfacing Options” and enable SPI. `sudo raspi-config`

	 
2	Modify the /boot/config.txt to enable SPI `sudo nano /boot/config.txt`

3	Ensure these lines are included in config.txt
	`device_tree_param=spi=on`
	`dtoverlay=spi-bcm2835`

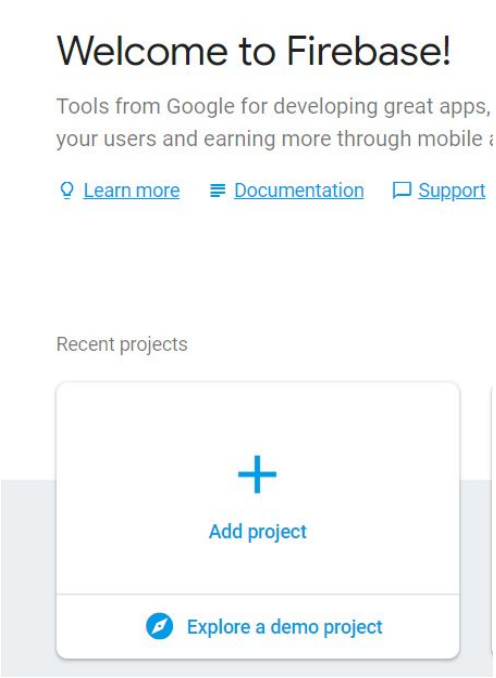
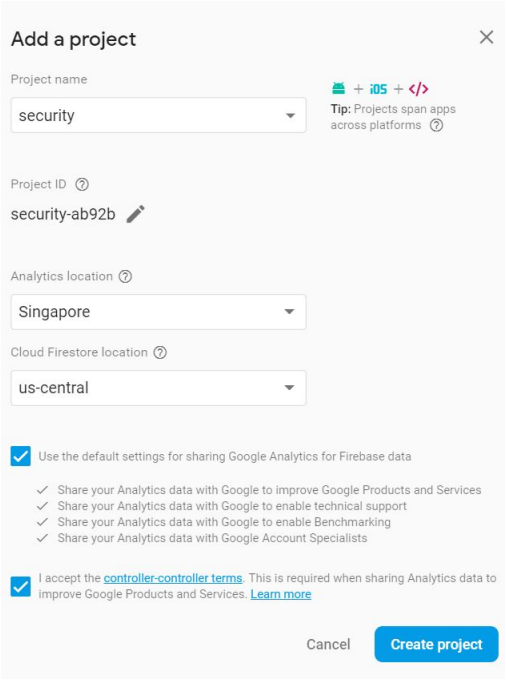
4	Install the Python development libraries `sudo apt-get install python-dev`

5	Set up the SPI Python libraries since the card reader uses the SPI interface
	`git clone https://github.com/lthiery/SPI-Py.git`
	`cd /home/pi/SPI-Py`

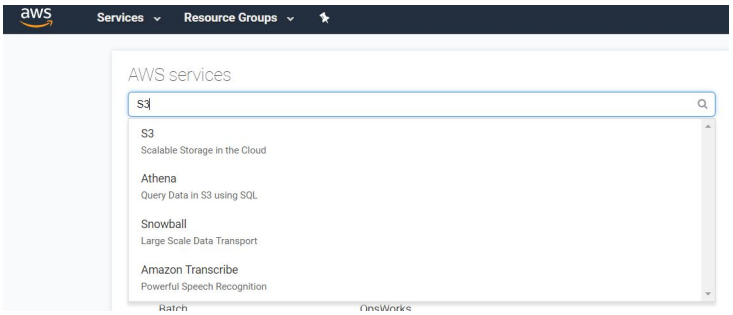
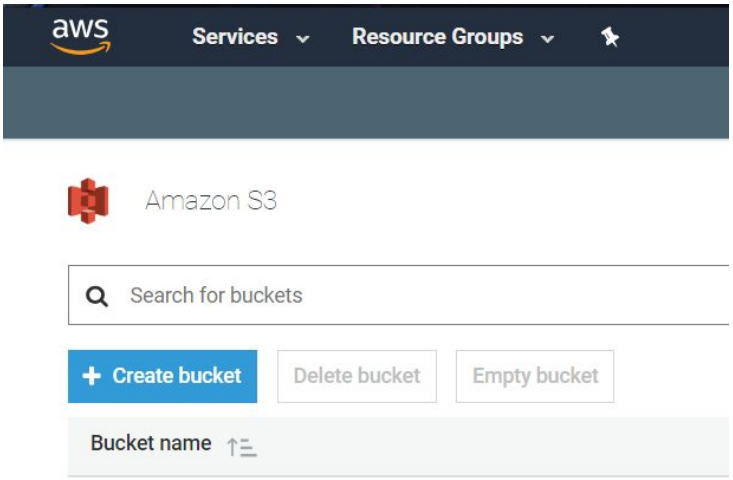
	sudo python setup.py install
6	Clone the MFRC522-python library and copy out MFRC522.py to your project directory git clone https://github.com/mxgxw/MFRC522-python.git

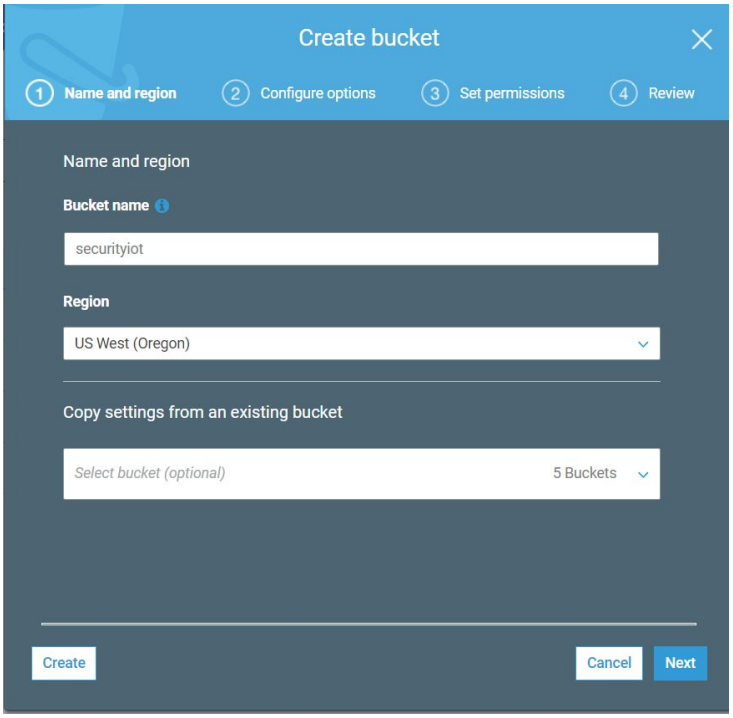
F. Setup firebase

#	Description	Image

1	To set up firebase, head to https://console.firebase.google.com After Signing in, click on add project	
2	Enter your project name whereby mine is security	

G. Setup S3 Storage

#	Description	Image
1	Log in your AWS console and search for S3	
2	Click Create Bucket	

3	Type in a unique name for your bucket and choose Region as “US West (Oregon)” which is us-west-2 Click “Create” button	

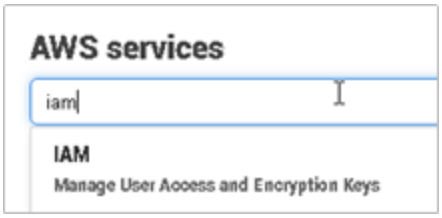
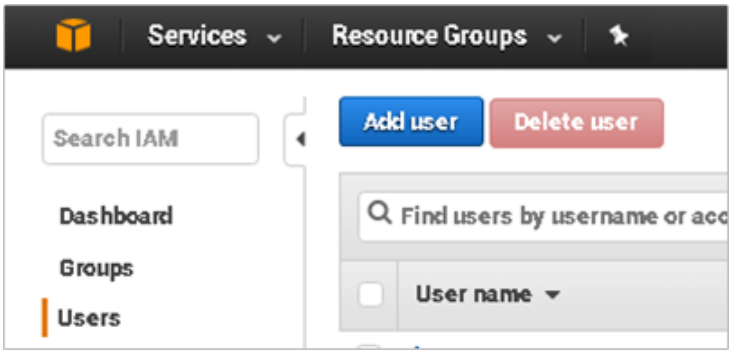
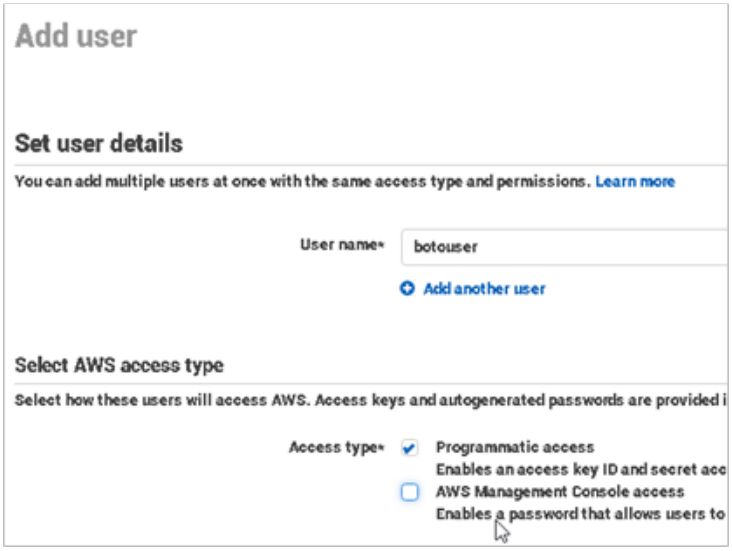
H. Install Boto on Raspberry Pi

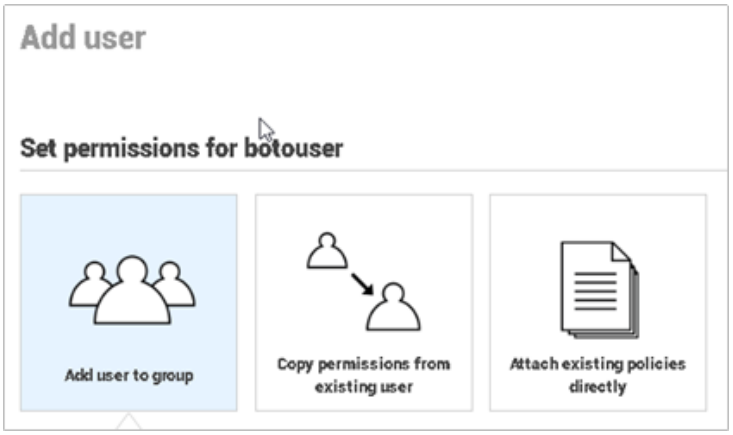
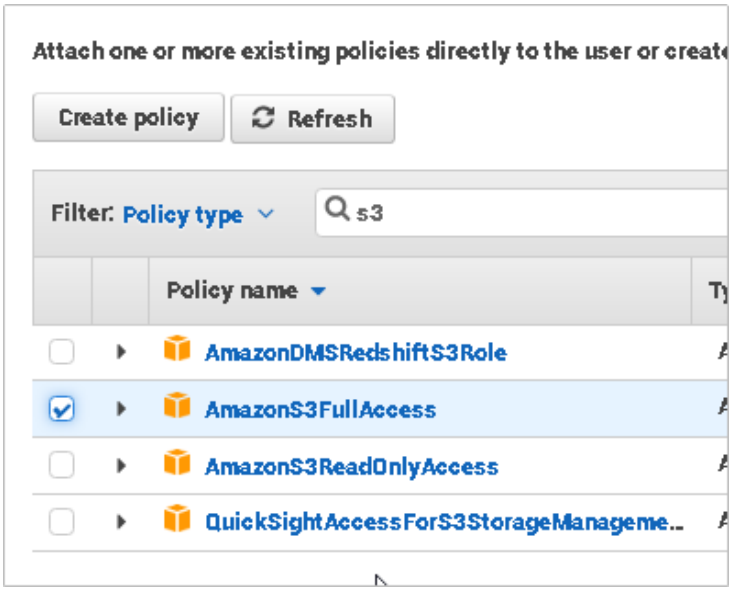
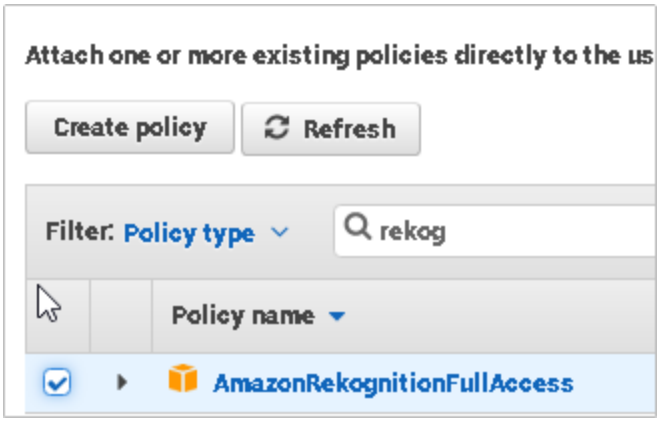
```
sudo pip install boto3
```

I. Install AWS CLI on Raspberry Pi

```
sudo pip install awscli
```

J. Credentials for AWS

#	Description	Image
1	Log in your AWS console and search for IAM	
2	Click on “Users” submenu, “Add user”	
3	Create a new user botouser and enable programmatic access	

4	In the next screen, click “Attach existing policies directly”	
5	Scroll to the bottom of the page, search for “s3” and then check the “AmazonS3FullAccess” option	
6	Next, search for “Rekognition” and then check the “AmazonRekognitionFullAccess” option	

7	Click the “Next: Review” button at the bottom of the page on the right, then on the next page, click “Create user”	
8	You should see the success page above with a link to download a csv file. **Make sure you download the .csv file to your laptop** You will need to refer to them later.	-

K. AWS Configure

On your Raspberry Pi, navigate to the directory where your Python code will be stored

```
cd ca2
```

Type the following command in your Raspberry Pi terminal so that you can use the AWS CLI to configure your credentials file:

```
aws configure
```

Enter the Access Key ID and Secret Access Key id you obtained from the previous section

Reminder that you would need to change a few things in the code that will be provided later on

In code which will be provided later on, you will need to change current code shown below to your own firebase application database url in the code

```
firebase = firebase.FirebaseApplication('https://iotca2-12f48.firebaseio.com', None)
```

In code which will be provided later on, you will need to change current code shown below to your own hostname of the thing created in aws which you had saved just now

```
host = "a280tk19mi5ck7.iot.us-west-2.amazonaws.com"
```

In code which will be provided later on, you will need to change current code shown below input in your credentials from the csv file downloaded from s3

```
access_key_id = 'AKIAJNPGQERG7Z5VFIFA'
secret_access_key = 'w8KxV67zAKMWtkx3RslD6kzgRqqjskuFy61ss22l'
```

In code which will be provided later on, you will need to Change the current code below to your own s3 bucket unique name

```
bucket_name = 'iotsecurity'
```

L. security.py code

Create new python file

```
sudo nano security.py
```

Input in current codes

```
 # Import SDK packages
from AWSIoTPythonSDK.MQTTLib import AWSIoTMQTTClient
from time import sleep
import RPi.GPIO as GPIO
import MFRC522
from datetime import datetime
from picamera import PiCamera
```

```
import os
import tinys3
import json
from rpi_lcd import LCD
import boto3
import botocore
from firebase import firebase


CONSUMER_KEY = 'h5Sis7TXdoUVncrpjSzGAvhBH'
CONSUMER_SECRET = 'ZfDVxc4aTd9doGmBQO3HiSKKzxSTKT4C3g0B3AGx8eETCJm2rY'
ACCESS_KEY = '988333099669901312-YDLEQN1weW2n1JP4lxJcFPppCsbvzQh'
ACCESS_SECRET = 'K2IlUPur6jx7DO5S0HhhZW29H5AQFOvkMMevSsk9ZzwLk'

firebase = firebase.FirebaseApplication('https://iotca2-12f48.firebaseio.com',
None)

host = "a280tk19mi5ck7.iot.us-west-2.amazonaws.com"
rootCAPath = "rootca.pem"
certificatePath = "certificate.pem.crt"
privateKeyPath = "private.pem.key"

# photo properties
image_width = 800
image_height = 600
file_extension = '.png'

access_key_id = 'AKIAJNPGQERG7Z5VFIFA'
secret_access_key = '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'
bucket_name = 'iotsecurity'


my_rpi = AWSIoTMQTTClient("basicPubSub")
my_rpi.configureEndpoint(host, 8883)
my_rpi.configureCredentials(rootCAPath, privateKeyPath, certificatePath)

my_rpi.configureOfflinePublishQueueing(-1)  # Infinite offline Publish queueing
```

```
my_rpi.configureDrainingFrequency(2)  # Draining: 2 Hz
my_rpi.configureConnectDisconnectTimeout(10)  # 10 sec
my_rpi.configureMQTTOperationTimeout(5)  # 5 sec

# camera setup
camera = PiCamera()
camera.resolution = (image_width, image_height)
camera.awb_mode = 'auto'


#LCD Setup
lcd = LCD()

# Create an object of the class MFRC522
mfrc522 = MFRC522.MFRC522()


def waitForRFIDScan():
   done = False
   while not done:
    (status,TagType) = mfrc522.MFRC522_Request(mfrc522.PICC_REQIDL)
    if status == mfrc522.MI_OK:
     # Get the UID of the card
     (status,uid) = mfrc522.MFRC522_Anticoll()
     done = True
     return uid

def uploadToS3(file_name):
   filepath = file_name + file_extension
   camera.capture(filepath)
   conn = tinys3.Connection(access_key_id, secret_access_key)
   f = open(filepath, 'rb')
   conn.upload(filepath, f, bucket_name,
               headers={
               'x-amz-meta-cache-control': 'max-age=60'
               })
   if os.path.exists(filepath):
```

```
        os.remove(filepath)


def checkRFIDNumber(rfidnumber):
    return rfidnumber == [136, 4, 133, 233, 224]

# # # Custom MQTT message callback
# def customCallback(client, userdata, message):
#     print("Received a new message: ")
#     data = json.loads(message.payload)
#     try:
#         similarity = data[1][0]['Similarity']
#         print("Received similarity: " + str(similarity))
#         if(similarity >= 90):
#             print("Access allowed, opening doors.")
#             print("Thank you!")
#     except:
#         pass
#     print("Finished processing event.")


# Custom MQTT message callback
def customCallback(client, userdata, message):
    print("Received a new message: ")
    print(message.payload)
    print("from topic: ")
    print(message.topic)
    print("--------------\n\n")

# Connect and subscribe to AWS IoT
my_rpi.connect()
my_rpi.subscribe("security/entry", 1, customCallback)
sleep(2)

# Publish to the same topic in a loop forever
while True:
    print("waiting..")
```

```
    scan = waitForRFIDScan()
    print(scan)
    if(checkRFIDNumber(scan)):
        print("RFID correct, taking photo...")
        lcd.text('Welcome', 1)
        file_name = "user"
        uploadToS3(file_name)
        my_rpi.publish("security/entry", "User entered", 1)
        datestr = str(datetime.now())
        imgUrl = "https://s3-us-west-2.amazonaws.com/iotsecurity/user.png"
        data={ 'Date': datestr, 'UID': str(scan), 'image': imgUrl}
        result = firebase.post('/entry/',data)
        sleep(5)
        lcd.clear()
    else:
        print("Bad RFID - Access Denied")
        lcd.text('Access Denied', 1)
        my_rpi.publish("security/entry", "Intruder Detected", 1)
        datestr = str(datetime.now())
        data={ 'Date': datestr, 'UID': str(scan)}
        result = firebase.post('/entry/',data)
        sleep(5)
        lcd.clear()
        # sleep(10)
```

M. Run security.py code

Run code to get security system working

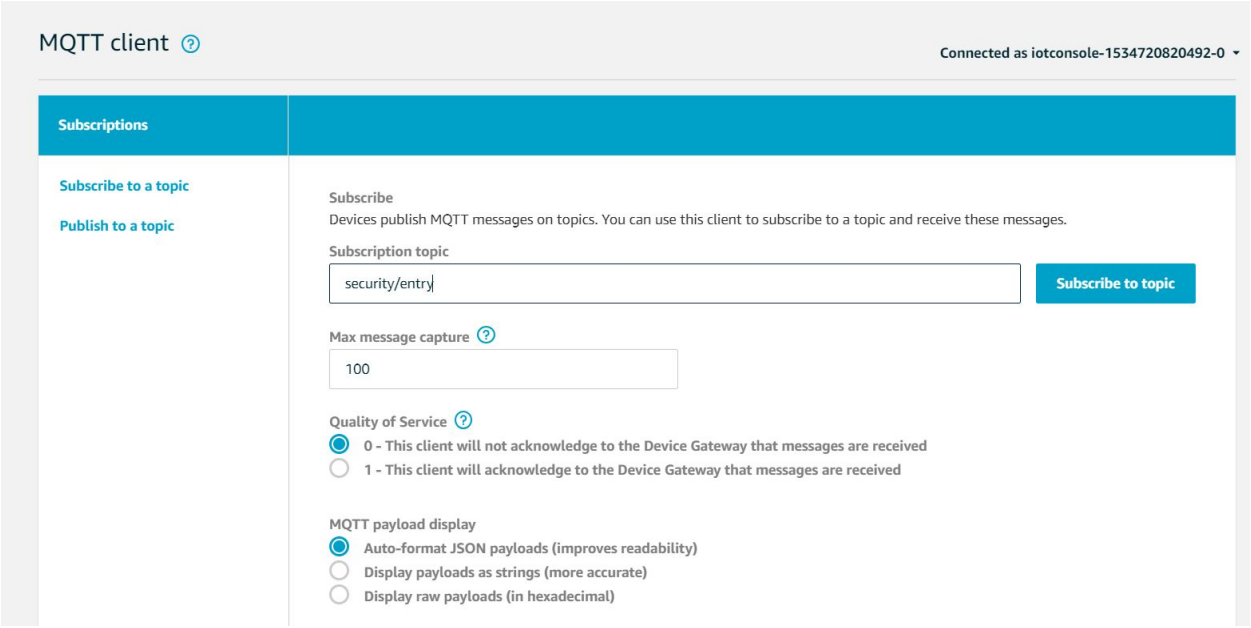
```
python security.py
```

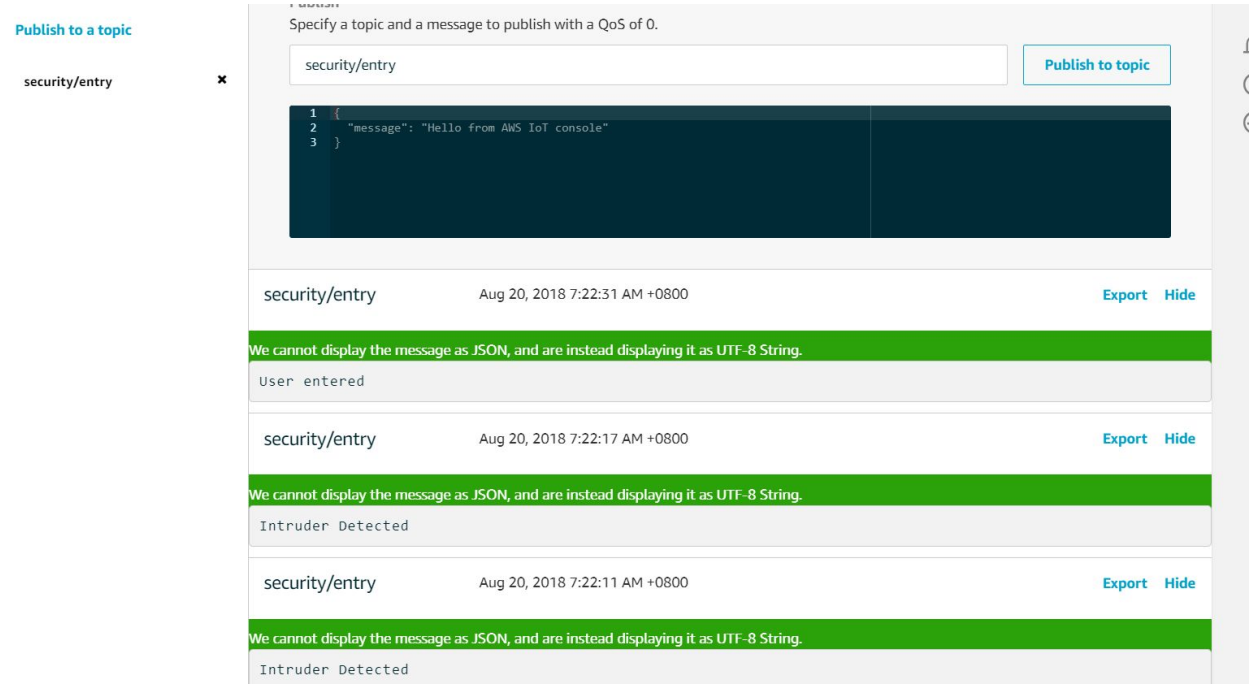
N. View MQTT

In the AWS IoT console, in the left navigation pane, choose Test.

Type in the topic on which your thing publishes. In our case, it is “security/entry”

Click “Subscribe to topic”





O. Image Recognition

Create a new python file

```
sudo nano imagerecognition.py
```

Input in the current code and change replace bucket name with your own

```
import boto3
import botocore
from picamera import PiCamera
from time import sleep

# Set the filename and bucket name
BUCKET = 'iotsecurity' # replace with your own unique bucket name
location = {'LocationConstraint': 'us-west-2'}
file_path = "/home/pi/Desktop"
file_name = "test.jpg"

def takePhoto(file_path,file_name):

   with PiCamera() as camera:
       #camera.resolution = (1024, 768)
       full_path = file_path + "/" + file_name
       camera.capture(full_path)
       sleep(3)

def uploadToS3(file_path,file_name, bucket_name,location):
   s3 = boto3.resource('s3') # Create an S3 resource
   exists = True

   try:
       s3.meta.client.head_bucket(Bucket=bucket_name)
   except botocore.exceptions.ClientError as e:
       error_code = int(e.response['Error']['Code'])
       if error_code == 404:
           exists = False

   if exists == False:
```

```
        s3.create_bucket(Bucket=bucket_name,CreateBucketConfiguration=location)

    # Upload the file
    full_path = file_path + "/" + file_name
    s3.Object(bucket_name, file_name).put(Body=open(full_path, 'rb'))
    print("File uploaded")


def detect_labels(bucket, key, max_labels=10, min_confidence=90,
region="us-west-2"):
    rekognition = boto3.client("rekognition", region)
    response = rekognition.detect_labels(
        Image={
            "S3Object": {
                "Bucket": bucket,
                "Name": key,
            }
        },
        MaxLabels=max_labels,
        MinConfidence=min_confidence,
    )
    return response['Labels']


takePhoto(file_path, file_name)
uploadToS3(file_path,file_name, BUCKET,location)
for label in detect_labels(BUCKET, file_name):
    print("{Name} - {Confidence}%".format(**label))
```

Run code to recognize things that are outside your home!

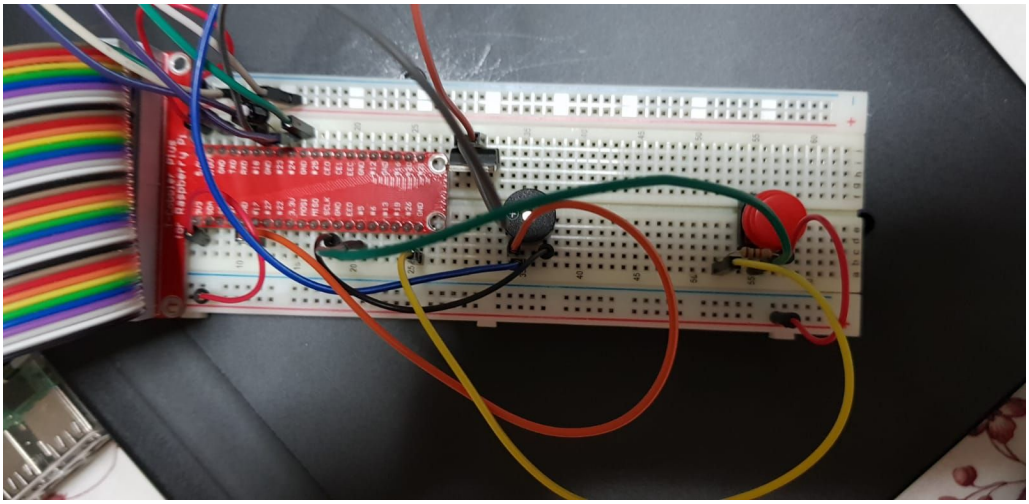
```
python imagerecognition.py
```

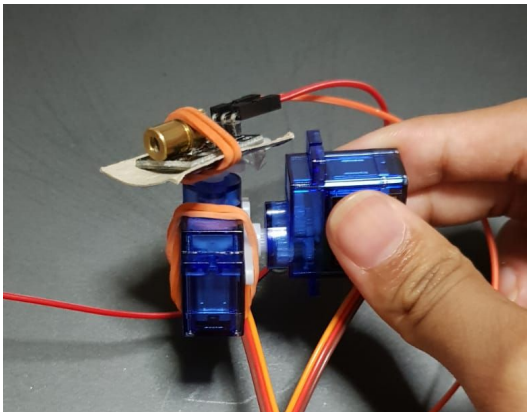
Section 4 : Defence

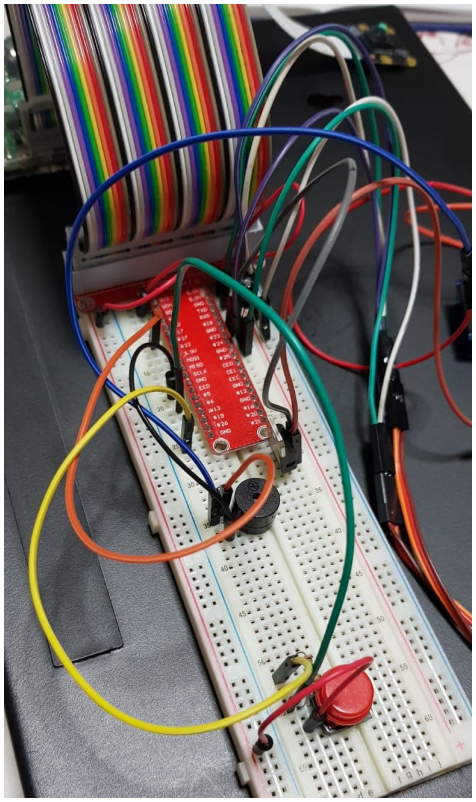
A. Hardware Setup

a. The RPi Connections

This is what your finished connection should look like.

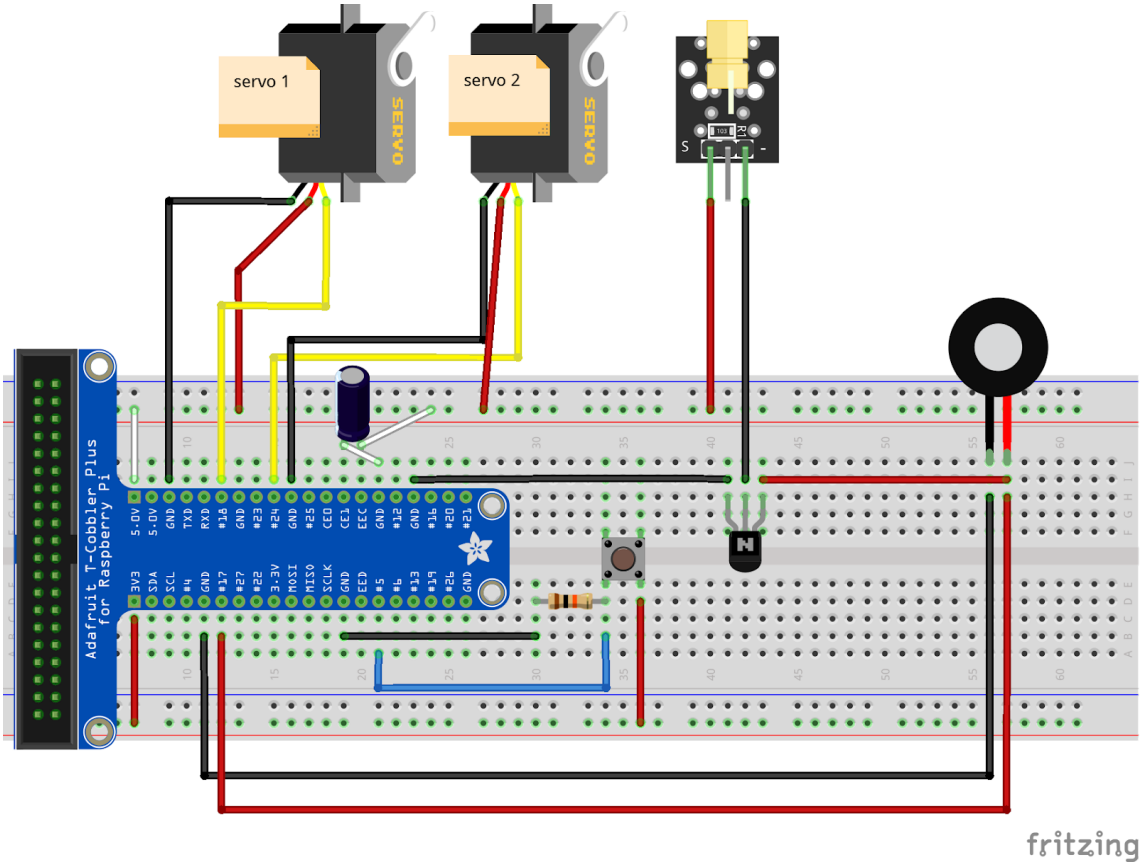






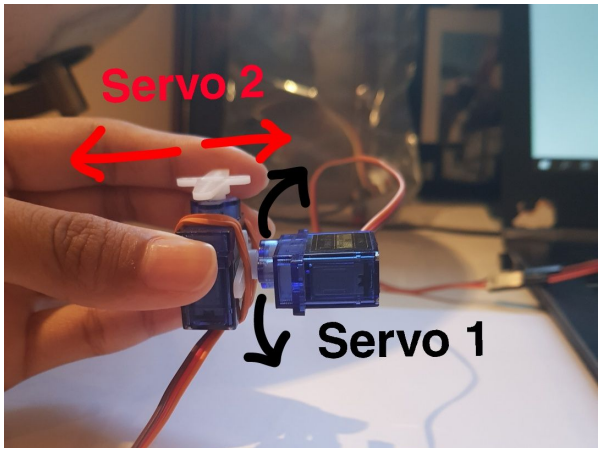
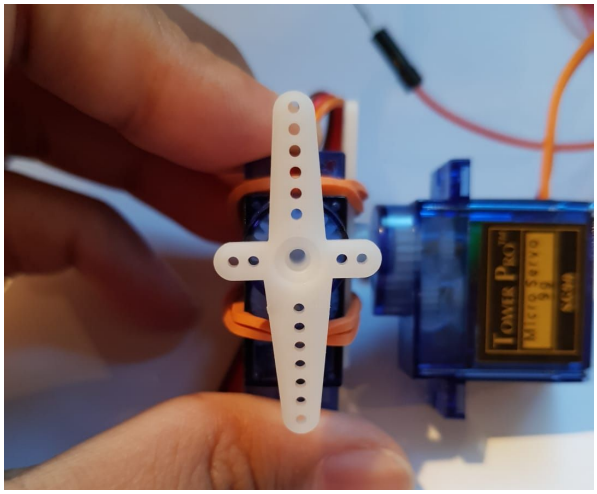
b. The Fritzing Diagram

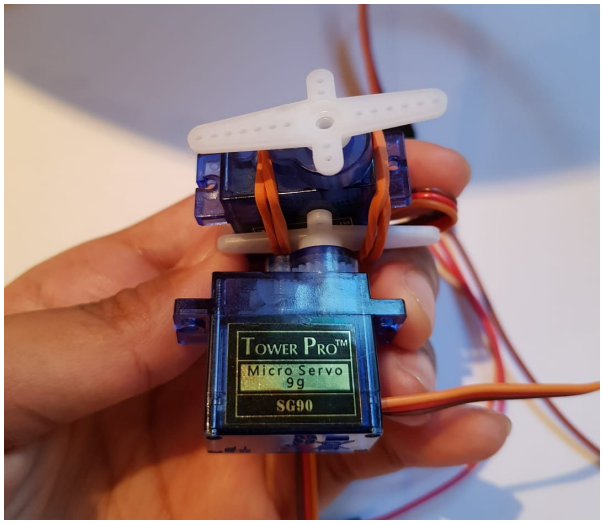
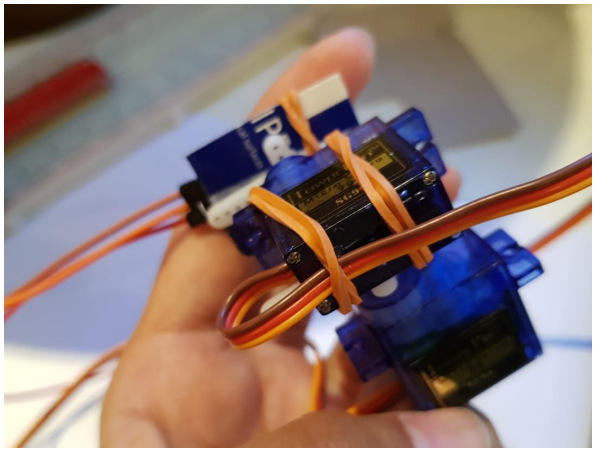
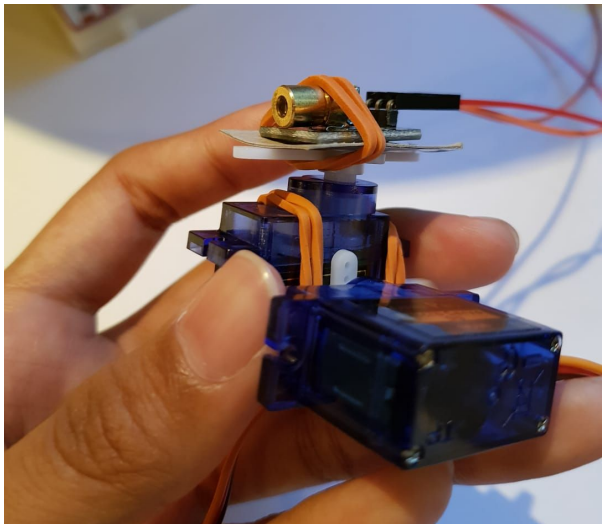
The fritzing diagram looks like this. Set up your RPi like so!

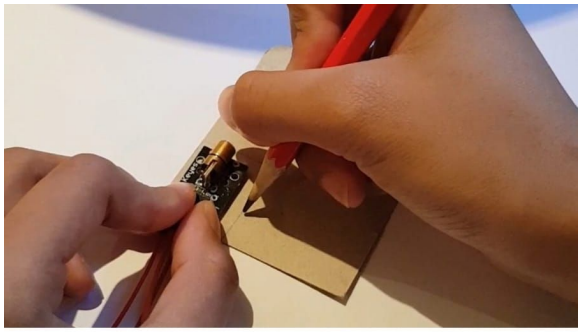
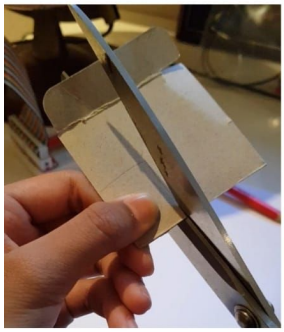
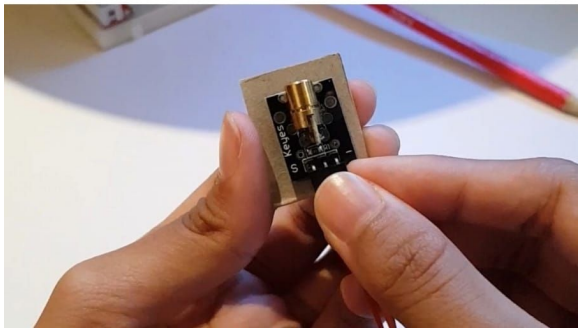
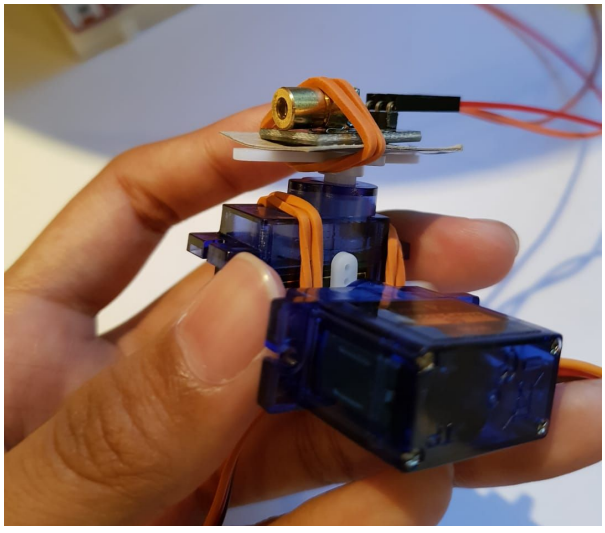


c. Connect The Components

The following steps will describe how to get the laser turret setup.

#	Description	Image
1	Here's what you want to achieve. Servo 1 allows us to aim the laser module higher or lower (black arrows). Servo 2 allows us to aim the laser module left or right (red arrows).	
2	Attach the cross head for BOTH servos.	

3	User rubber bands/zip ties to attach servo one (top) to servo 2 (bottom).	
4	Tuck in the cable of servo 2 under the rubber band as well. This is so that when the servo rotates, the wire won't be caught in the motion.	
5	Next, we'll put together the laser module.	

6	Put something hard under the laser module. This will allow us a larger and sturdier surface to attach the laser module to the servo. I used a scrap piece of cardboard and tape.	   
7	Attach the laser module to the servo by using rubber band and some tape on the underside of the cardboard. Then you're done!	

The following steps will explain the main wiring. Don't forget the resistors!

Part	Cable Color	PIR Pin	RPi Pin
Servo 1	Orange	PVM	#18
	Red	5V	5V Rail
	Brown	GND	GND
Servo 2	Orange	PVM	#24
	Red	5V	5V Rail
	Brown	GND	GND
Laser Transmitter Module	Orange	GND	GND / Middle Leg (Transistor)
	Red	S	5V Rail
Buzzer	Blue	VOUT	#17
	Green	GND	GND
Attack Button	Red	VOUT	3V
	Blue	GPIO	#5
	Black	GND	GND
Transistor	Black	Right Leg	GND
		Middle Leg	Laser GNT
		Left Leg	GND

Capacitor		Long Leg	5V
		Short Leg	GND

B. Software

a. laserturret.py

The codes below, when run, will trigger the laser turret. The laser turret will shoot in random directions, in random bursts and speed.

```
from gpiozero import LED, Buzzer, Button, Servo
import time
from signal import pause
import random

#led = LED(12)
#pir = MotionSensor(19, sample_rate=5,queue_len=1)
buzzer_pin = Buzzer(17)
attack = Button(5, pull_up=False)
#reset = Button(6, pull_up=False)
servo1 = Servo(18)
servo2 = Servo(24)

def ledON():
      led.on()
      print("LED is on")

def ledOFF():
      led.off()
      print("LED is off")

def fire():
      print("weapons hot")
      buzzer_pin.on()
      time.sleep(0.1)
      buzzer_pin.off()

def laserturret():
```

```
            timeBetweenBurst = random.uniform(0.2,1)
            timeBetweenShots = random.uniform(0.05,0.2)
            servo1start = random.randrange(-1,1)
            servo1end = random.randrange(-1,1)
            servo2start = random.randrange(-1, 1)
            servo2end = random.randrange(-1,1)
            numShots = random.randrange(5,20)

            servo1change = (servo1end - servo1start)/numShots
            servo2change = (servo2end - servo2start)/numShots
            servo1.value = servo1start
            servo2.value = servo2start
            time.sleep(0.1)
            shot = 0

            detail = [timeBetweenBurst,timeBetweenShots, servo1.value,
servo2.value, numShots]
            print(detail)

            while shot<numShots:
                  shot+= 1
                  servo1.value = servo1start
                  servo2.value = servo2start

                  servo1start = servo1change
                  servo2start = servo2change

                  fire()
                  time.sleep(timeBetweenShots)

            time.sleep(timeBetweenBurst)

notes = {
      'B0' : 31,
      'C1' : 33, 'CS1' : 35,
      'D1' : 37, 'DS1' : 39,
      'EB1' : 39,
      'E1' : 41,
      'F1' : 44, 'FS1' : 46,
```

```
    'G1' : 49, 'GS1' : 52,
    'A1' : 55, 'AS1' : 58,
    'BB1' : 58,
    'B1' : 62,
    'C2' : 65, 'CS2' : 69,
    'D2' : 73, 'DS2' : 78,
    'EB2' : 78,
    'E2' : 82,
    'F2' : 87, 'FS2' : 93,
    'G2' : 98, 'GS2' : 104,
    'A2' : 110, 'AS2' : 117,
    'BB2' : 123,
    'B2' : 123,
    'C3' : 131, 'CS3' : 139,
    'D3' : 147, 'DS3' : 156,
    'EB3' : 156,
    'E3' : 165,
    'F3' : 175, 'FS3' : 185,
    'G3' : 196, 'GS3' : 208,
    'A3' : 220, 'AS3' : 233,
    'BB3' : 233,
    'B3' : 247,
    'C4' : 262, 'CS4' : 277,
    'D4' : 294, 'DS4' : 311,
    'EB4' : 311,
    'E4' : 330,
    'F4' : 349, 'FS4' : 370,
    'G4' : 392, 'GS4' : 415,
    'A4' : 440, 'AS4' : 466,
    'BB4' : 466,
    'B4' : 494,
    'C5' : 523, 'CS5' : 554,
    'D5' : 587, 'DS5' : 622,
    'EB5' : 622,
    'E5' : 659,
    'F5' : 698, 'FS5' : 740,
    'G5' : 784, 'GS5' : 831,
    'A5' : 880, 'AS5' : 932,
    'BB5' : 932,
```

```
      'B5' : 988,
      'C6' : 1047, 'CS6' : 1109,
      'D6' : 1175, 'DS6' : 1245,
      'EB6' : 1245,
      'E6' : 1319,
      'F6' : 1397, 'FS6' : 1480,
      'G6' : 1568, 'GS6' : 1661,
      'A6' : 1760, 'AS6' : 1865,
      'BB6' : 1865,
      'B6' : 1976,
      'C7' : 2093, 'CS7' : 2217,
      'D7' : 2349, 'DS7' : 2489,
      'EB7' : 2489,
      'E7' : 2637,
      'F7' : 2794, 'FS7' : 2960,
      'G7' : 3136, 'GS7' : 3322,
      'A7' : 3520, 'AS7' : 3729,
      'BB7' : 3729,
      'B7' : 3951,
      'C8' : 4186, 'CS8' : 4435,
      'D8' : 4699, 'DS8' : 4978
}

def buzz(frequency, length): #create the function "buzz" and feed it
the pitch and duration)

      if(frequency==0):
            time.sleep(length)
            return
      period = 1.0 / frequency          #frequency
      delayValue = period / 2           #calcuate the time for half of
the wave
      numCycles = int(length * frequency)    #num of waves = duratime
x freq

      for i in range(numCycles):       #start a loop from 0 to the
variable "cycles" calculated above
            buzzer_pin.on()
            time.sleep(delayValue)
```

```
            buzzer_pin.off()
            time.sleep(delayValue)


def play(melody,tempo,pause,pace=0.800):

      for i in range(0, len(melody)):        # Play song

            noteDuration = pace/tempo[i]
            buzz(melody[i],noteDuration)     # Change the frequency
along the song note

            pauseBetweenNotes = noteDuration * pause
            time.sleep(pauseBetweenNotes)

while True:
            laserturret()
            break;
```

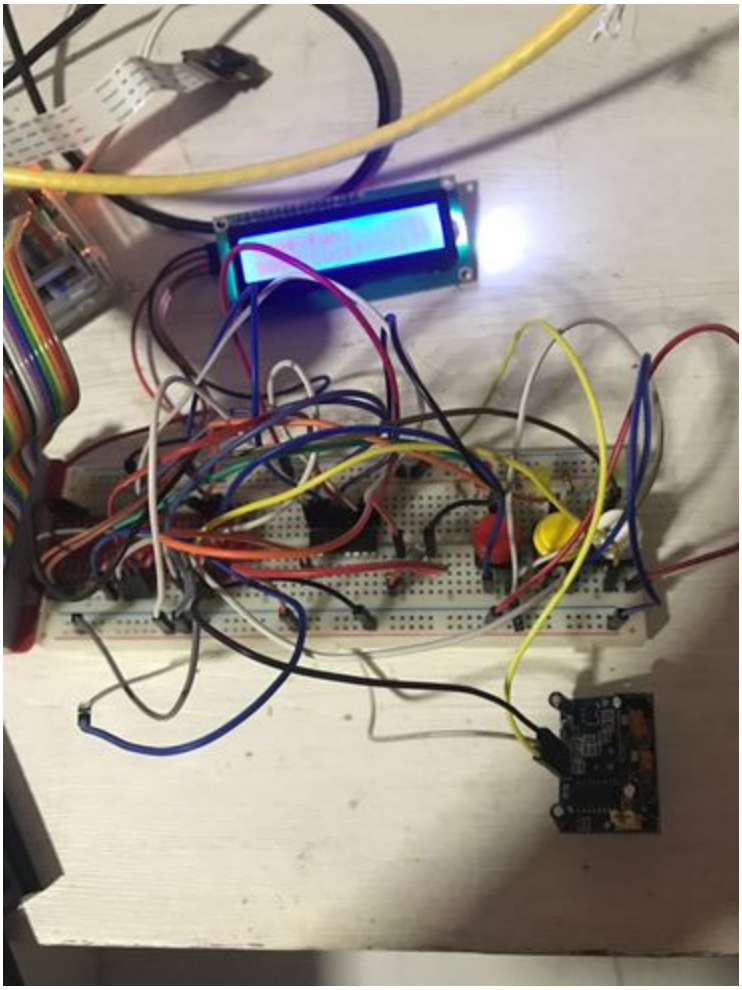
We are done with the Defence section of the Home Entertainment and Security system. We'll finish completing the other setups in the system and then proceed to creating our dashboard in Section 6.

Section 5: Entertainment

A.Hardware Setup

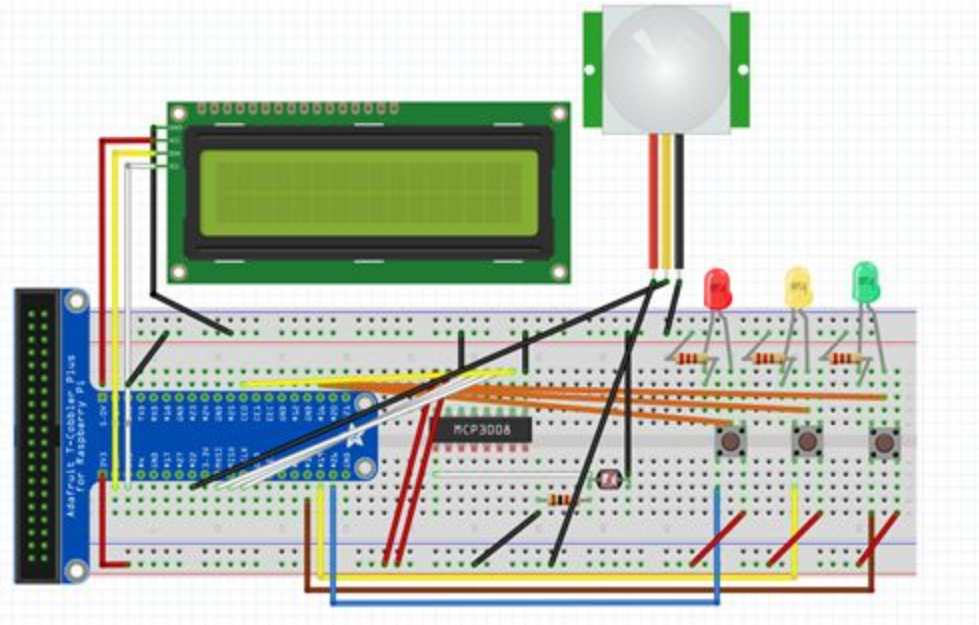
a. The RPi Connections

This is what your finished connection should look like.



b. The Fritzing Diagram

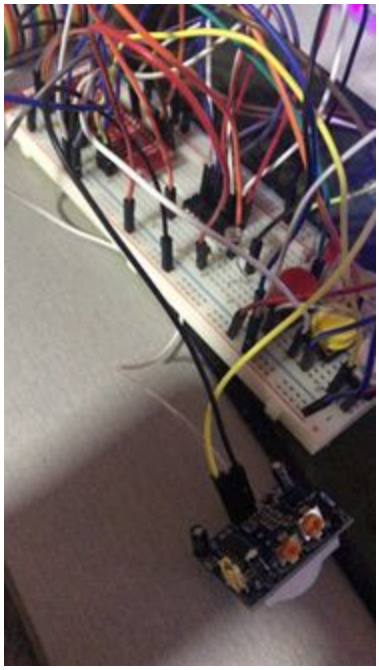
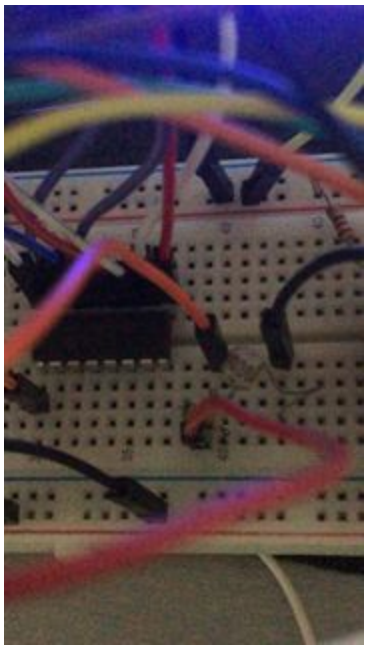
The fritzing diagram looks like this. Set up your RPi like so!

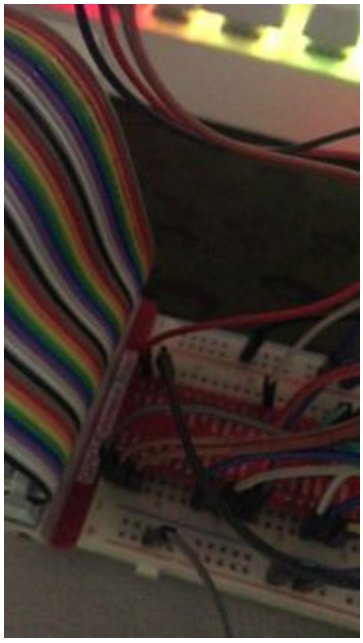


c. Connect the Components

The following steps will describe how to get the entertainment system setup.

#	Description	Image
1	Connect the three buttons and three LEDs as shown, following the fritzing diagram for a clearer view.	

2	Connect the PIR Motion Sensor to detect motion and start game.	
3	Connect the LDR alongside the MCP3008 Required connections	

4	Connect the LCD to the raspberry pi to view the status of the game, and you're done!	

The following steps will explain the main wiring. Don't forget the resistors!

Part	Cable Color	PIR Pin	RPi Pin
LCD	Orange	SCL	SCL
	Red	SDA	SDA
	Brown	GND	GND
	Black	VCC	5V
PIR Motion Sensor	Red	VCC	3V Rail
	Brown	VOUT	#22

	Black	GND	GND
LDR			
	Orange	A0	Pin 1 MCP3008
LED (R, Y, G)	Red	GPIO	#16
	Yellow	GPIO	#20
	Green	GPIO	#21
Buttons (R, Y, G)	Red	GPIO	#13
	Yellow	GPIO	#19
	Green	GPIO	#26

B.Software

A. Entertain.py

The codes below, when run, will run the simon says game, which u have to follow the pattern of the LEDS lighting up and press the corresponding buttons. It uploads scores and timestamp into the firebase nosql database for further usage in the dashboards.

```
import RPi.GPIO as GPIO
import threading
import time
import random
import os
import tweepy
from rpi_lcd import LCD
from subprocess import call
from time import sleep
from datetime import datetime
from firebase import firebase


CONSUMER_KEY = 'h5Sis7TXdoUVncrpjSzGAvhBH'
CONSUMER_SECRET =
'ZfDVxc4aTd9doGmBQO3HiSKKzxSTKT4C3g0B3AGx8eETCJm2rY'
ACCESS_KEY = '988333099669901312-YDLEQN1weW2n1JP4lxJcFPppCsbvzQh'
ACCESS_SECRET = 'K2IlUPur6jx7DO5S0HhhZW29H5AQFOvkMMevSsk9ZzwLk'


auth = tweepy.OAuthHandler(CONSUMER_KEY, CONSUMER_SECRET)
auth.secure = True
auth.set_access_token(ACCESS_KEY, ACCESS_SECRET)
api = tweepy.API(auth)
```

```
firebase = firebase.FirebaseApplication('https://iotca2-12f48.firebaseio.com',
None)
lcd=LCD()
lcd.text('Have fun!', 1)
lcd.text('Good Luck!', 2)
sleep(1)


# Red, Yellow, Green
LIGHTS = [40, 38, 36]
BUTTONS = [37, 33, 35]
NOTES = ["E3", "A4", "E4"]


# values you can change that affect game play
speed = 0.5


# flags used to signal game status
is_displaying_pattern = False
is_won_current_level = False
is_game_over = False


# game state
current_level = 1
current_step_of_level = 0
```

```
pattern = []


def initialize_gpio():
    GPIO.setmode(GPIO.BOARD)
        GPIO.setup(LIGHTS, GPIO.OUT, initial=GPIO.LOW)
        GPIO.setup(BUTTONS, GPIO.IN, pull_up_down=GPIO.PUD_DOWN)
        for i in range(3):
      GPIO.add_event_detect(BUTTONS[i], GPIO.FALLING,
                    verify_player_selection)


def verify_player_selection(channel):
        global current_step_of_level, current_level, is_won_current_level,
is_game_over
        if not is_displaying_pattern and not is_won_current_level and not
is_game_over:
      flash_led_for_button(channel)
        if channel == BUTTONS[pattern[current_step_of_level]]:
        current_step_of_level += 1
        if current_step_of_level >= current_level:
            current_level += 1
            is_won_current_level = True
        else:
        is_game_over = True
```

```
def flash_led_for_button(button_channel):
        led = LIGHTS[BUTTONS.index(button_channel)]
        GPIO.output(led, GPIO.HIGH)
        time.sleep(0.4)
        GPIO.output(led, GPIO.LOW)

def add_new_color_to_pattern():
        global is_won_current_level, current_step_of_level
        is_won_current_level = False
    current_step_of_level = 0
        next_color = random.randint(0, 2)
    pattern.append(next_color)

def display_pattern_to_player():
        global is_displaying_pattern
    is_displaying_pattern = True
        GPIO.output(LIGHTS, GPIO.LOW)
        for i in range(current_level):
        GPIO.output(LIGHTS[pattern[i]], GPIO.HIGH)
        time.sleep(speed)
        GPIO.output(LIGHTS[pattern[i]], GPIO.LOW)
```

```
        time.sleep(speed)
    is_displaying_pattern = False


def wait_for_player_to_repeat_pattern():
    while not is_won_current_level and not is_game_over:
            time.sleep(0.1)


def reset_board_for_new_game():
            global is_displaying_pattern, is_won_current_level, is_game_over
            global current_level, current_step_of_level, pattern
            is_displaying_pattern = False
            is_won_current_level = False
            is_game_over = False
            current_level = 1
    current_step_of_level = 0
            pattern = []
            GPIO.output(LIGHTS, GPIO.LOW)


def send_data(score):


            lcd.text('End of game,', 1)
    lcd.text('See you soon!', 2)
```

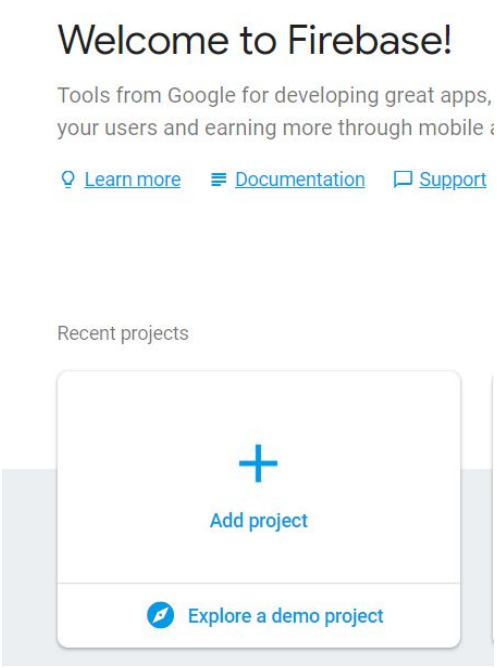
```
        datestr = str(datetime.now())
        while True:
    print(datestr)
    print(score)
    data={ 'Date': datestr,
         'Score': score
       }
    result = firebase.post('/scores/',data)
    print(result)
        if score > 2:
      status='Someone has scored '+ (str(score)) +' on '+datestr+'!'
      api.update_status (status = status)
        break


def start_game():
        while True:
      add_new_color_to_pattern()
      display_pattern_to_player()
        wait_for_player_to_repeat_pattern()
        if is_game_over:
        send_data(current_level - 1)
        print("Game Over! score is {} colors!\n".format(current_level - 1))
```

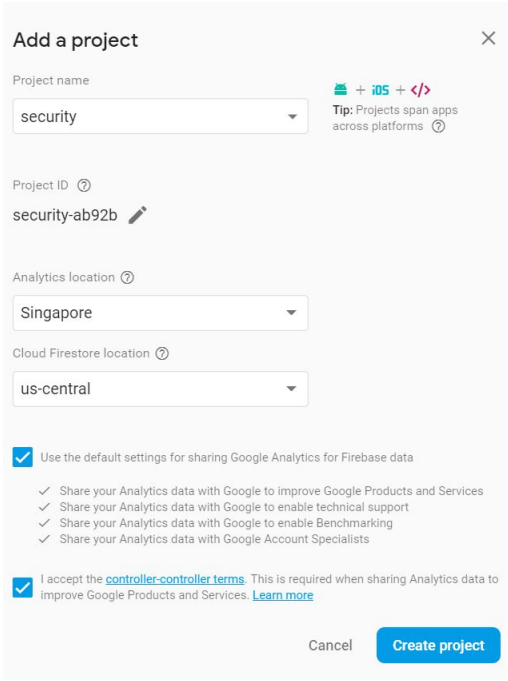
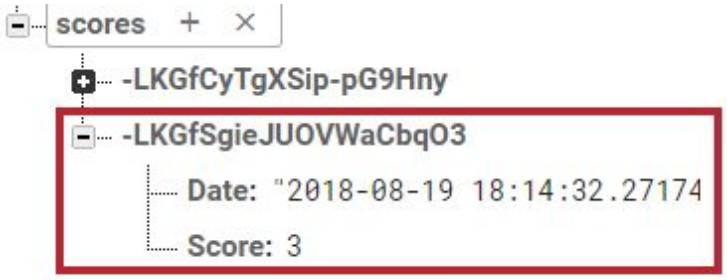
```
            sleep(2)
        print("Thanks for playing!\n")
        lcd.text('',1)
        lcd.text('',2)
            break
            time.sleep(2)


def start_game_monitor():
            t = threading.Thread(target=start_game)
            t.daemon = True
            t.start()
            t.join()


def main():
            try:
            os.system('cls' if os.name == 'nt' else 'clear')
            print("Begin new round!\n")
        initialize_gpio()
        start_game_monitor()
            finally:
            GPIO.cleanup()
```

```
if __name__ == '__main__':
        main()
```

We have now come to the end of the entertainment system setup guide!

B. Setup Firebase database

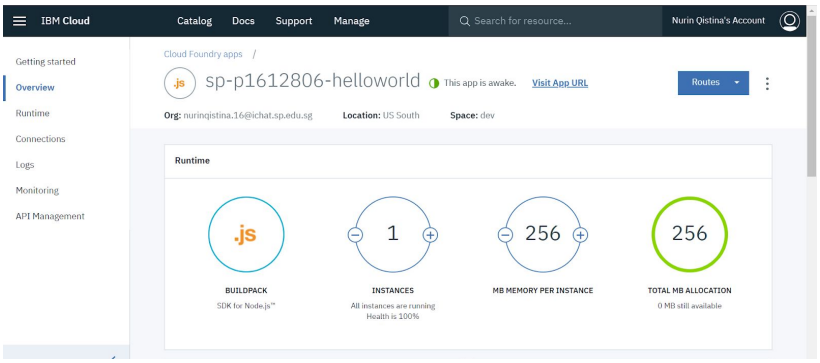
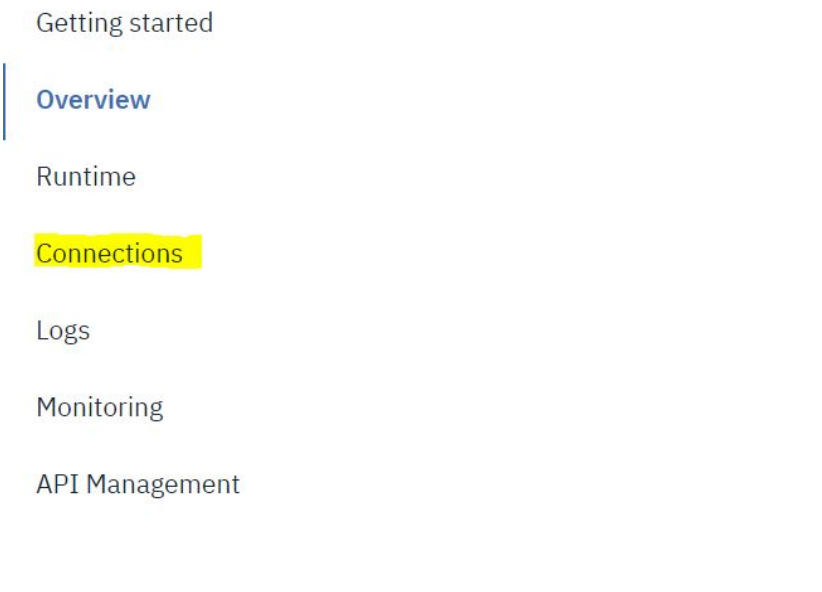
#	Description	Image
1	To set up firebase, head to https://console.firebase.google.com After Signing in, click on add project	

2	Enter your project name whereby mine is security	
3	Now, when u run the entertainment system, it will log into the firebase realtime database as such, whereby date and score will be stored per game.	

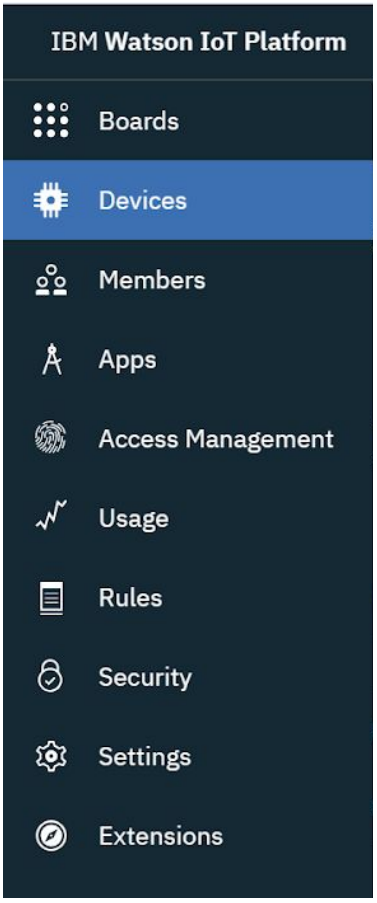
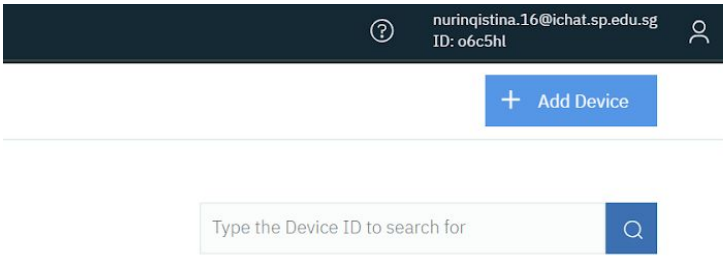
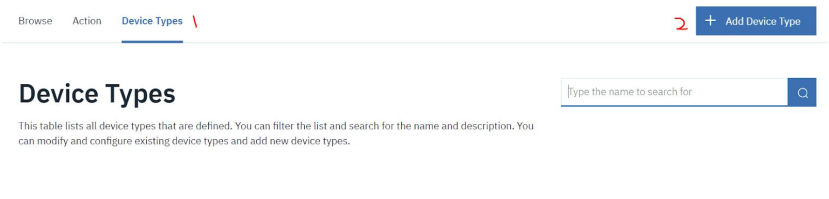
Section 6 : IOT App Watson on IBM Bluemix

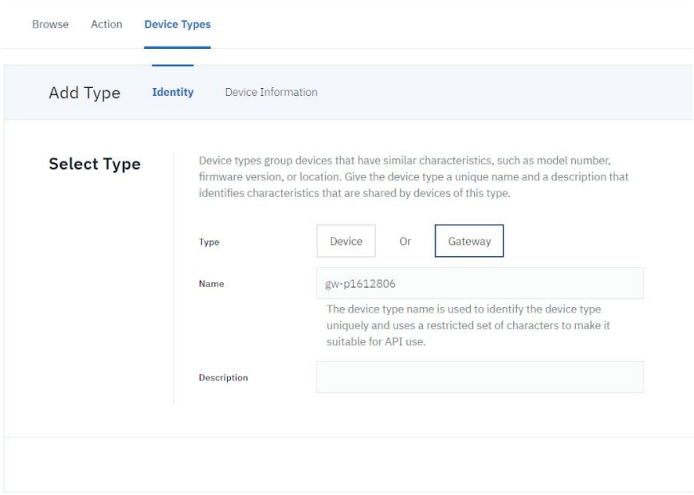
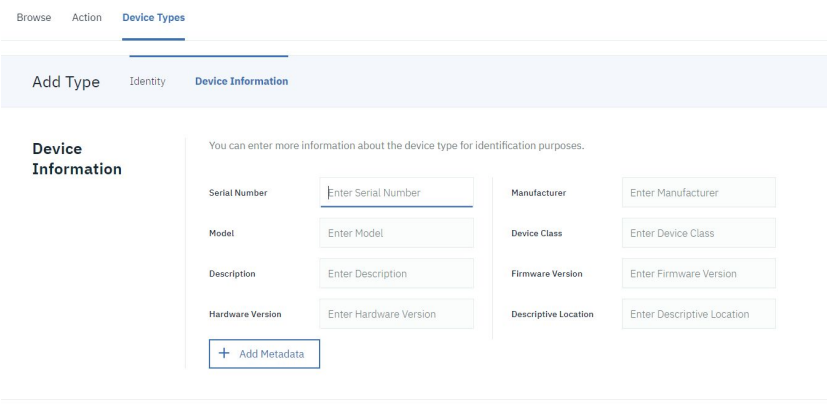
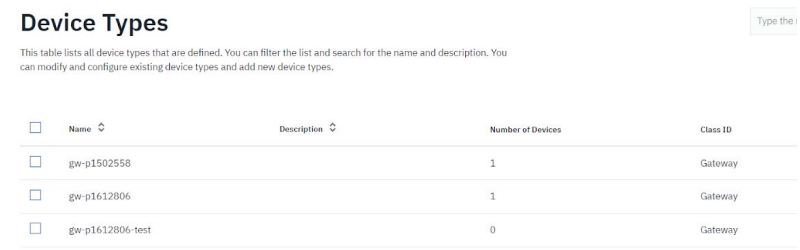
Set up Bluemix IoT Service

a. Set up a Gateway Device Type

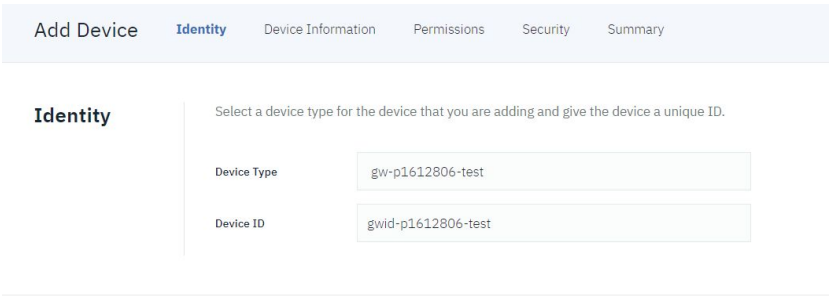
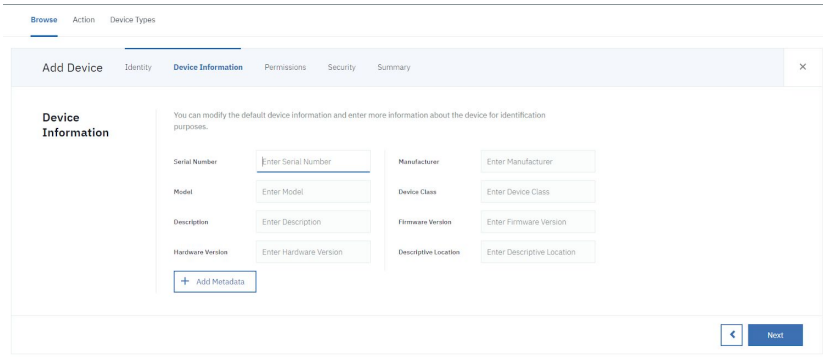
#	Description	Image
1	Open your cloud foundry app and make sure it is running.	
2	Click on the connections tab.	

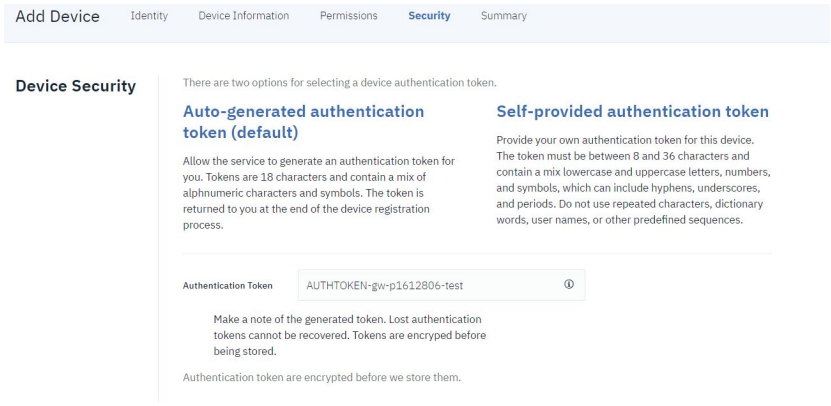
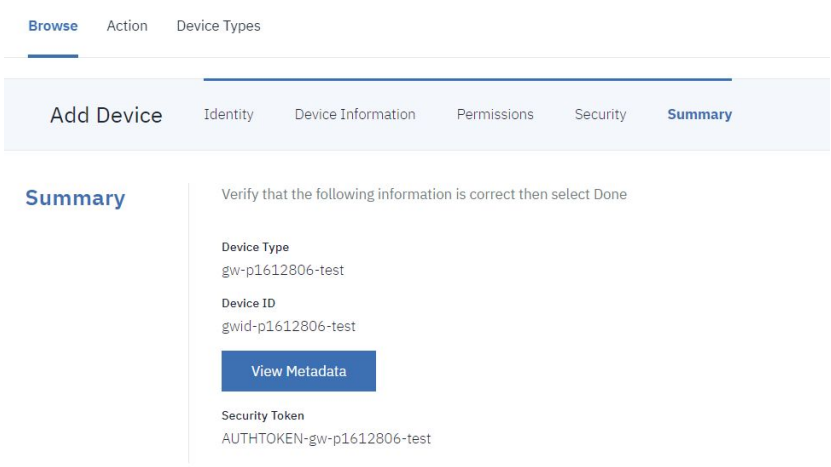
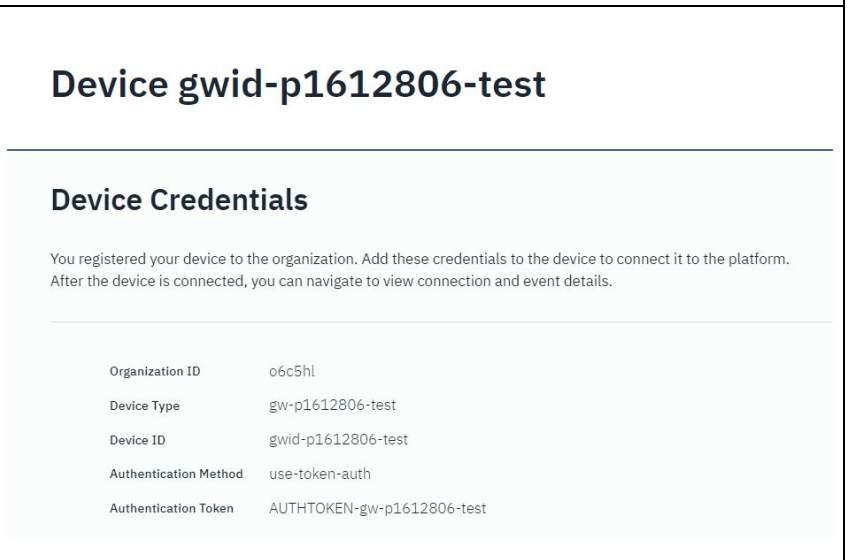
3	You will be brought to the IoT service configuration as shown. Click on the “Launch” button.	
4	Note the URL you’ve been redirected to. In our case, it is: *https://o6c5hl.internetofthings.ibmcloud.com*	

5	Hover over the side bar and click Devices	
6	Click on add devices on the top right.	
7	On the top bar, you'll see as shown. Click "Device Types" then click "Add Device Type"	

8	Select Gateway and create a recognizable name for the Pi you are using. Eg. gw-p1612806	
9	Skip this and click done.	
10	If successful, you'll be able to see the gateway you've created. Create a gateway for each Pi that you'll be using. For example, we have 2 pi currently for our system. Note: gw-1612806-test is for demo.	

b. Set up the Pi as a Gateway

#	Description	Image
1	Continuing from the previous section, we'll add a new device.	
2	Create an identity for the device. Device type will be the type we created previously (gw-p1612806-test). We name our Device ID as "gwid-p1612806-test" Click next.	
3	Skip Device Information and Permissions. Click Security.	

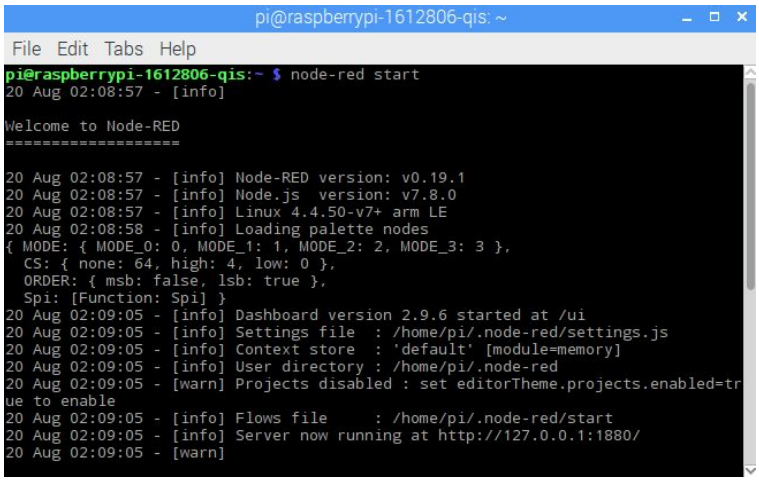
4	On the Security tab, you'll see this. We create our Auth Token and name it "AUTHTOKEN-gw-p1612806-test" Once you're done, Click next.	
5	Ensure you've types everything correctly and click done.	
6	Wait a few minutes for this page to load. This is important! Take down this information and save it.	

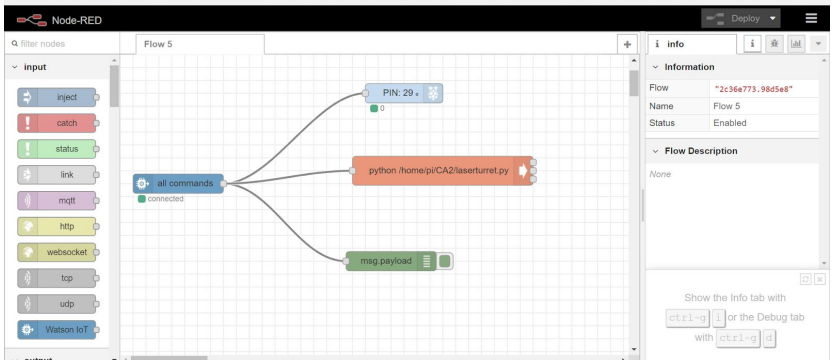
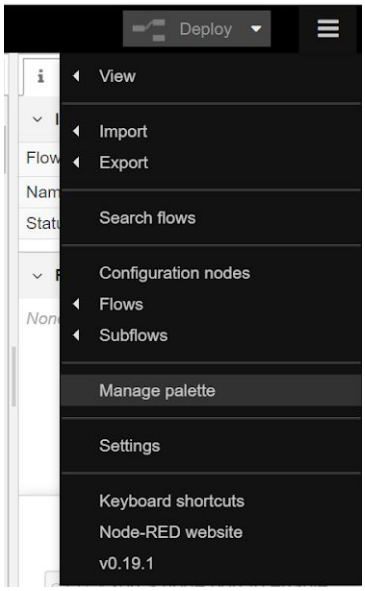
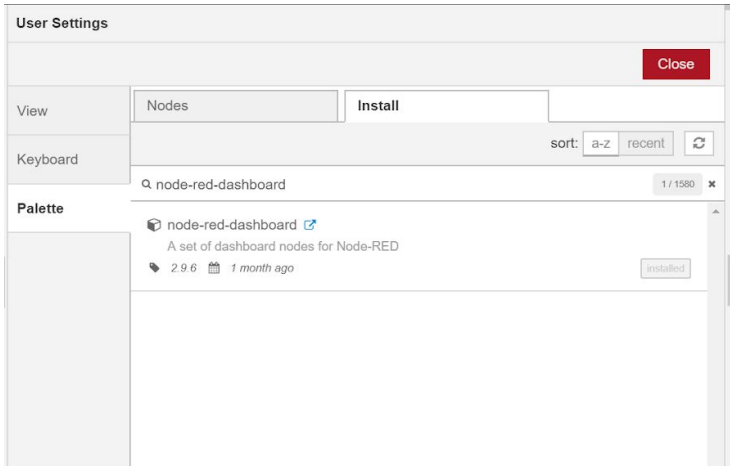
Set up Node-Red

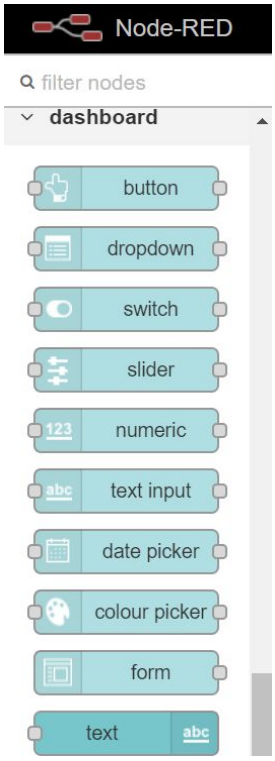
c. Install IBM Watson Node-RED nodes

#	Description	Image
1	Open a terminal window and install it in on your Rpi.	sudo npm i -g node-red-contrib-ibm-watson-iot
2	Once succesful, reboot your RPi.	Sudo reboot now

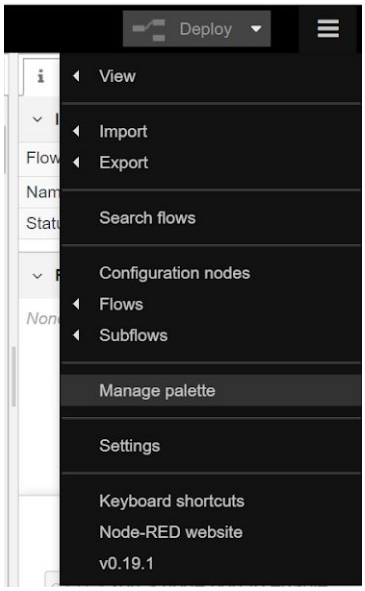
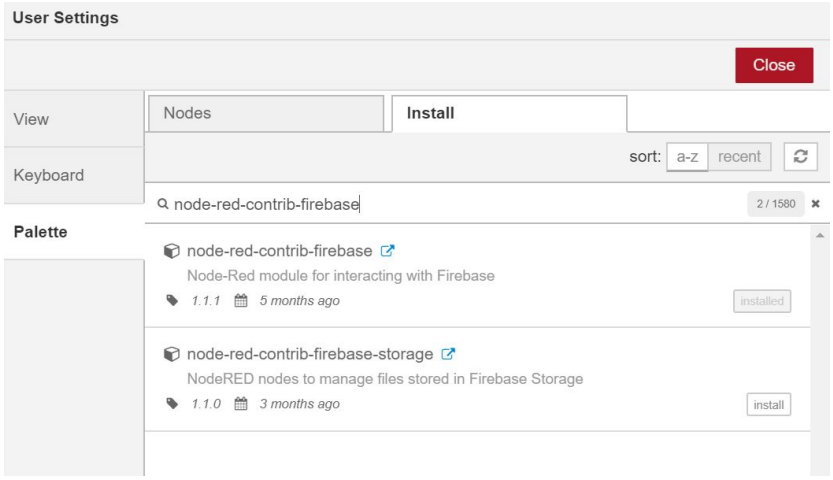
d. Install Node-Red-Dashboard Nodes

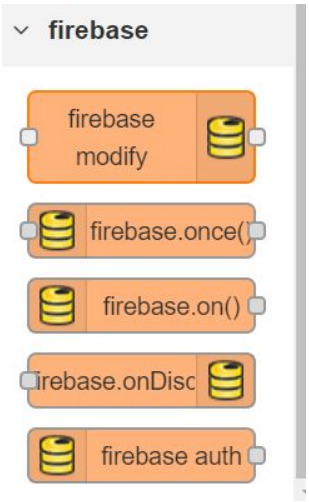
#	Description	Image
1	Open a terminal window and run Node-red.	

2	Open the node-red flow editor by going to your RPi ip address followed by the :1880 extension For example, mine is http://192.168.0.117:1880	
3	Click the hamburger icon on the top right followed by Manage Palette	
4	Click the install tab and search for “node-red-dashboard” If it’s not installed yet, go ahead and install it. As you can see, I have already installed it.	

5	Once installed, you should see it on the side in the list of the available nodes.	

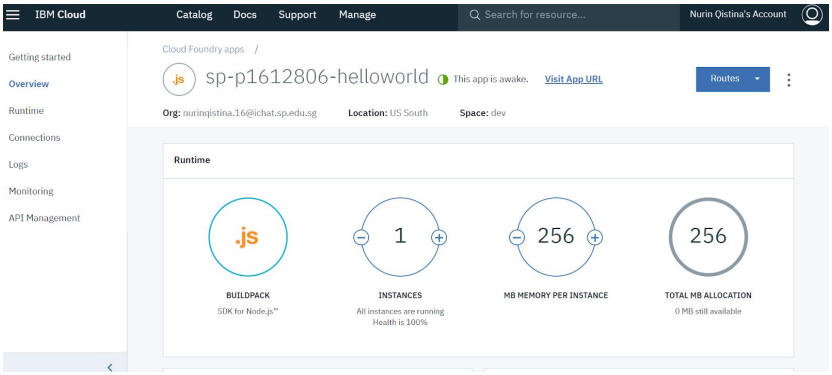
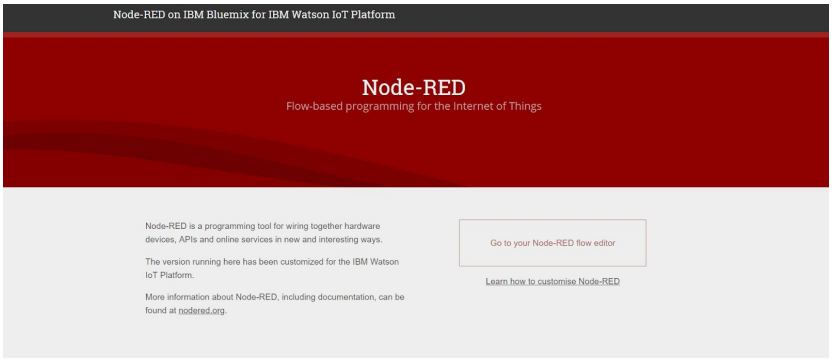
e. Install Firebase Nodes

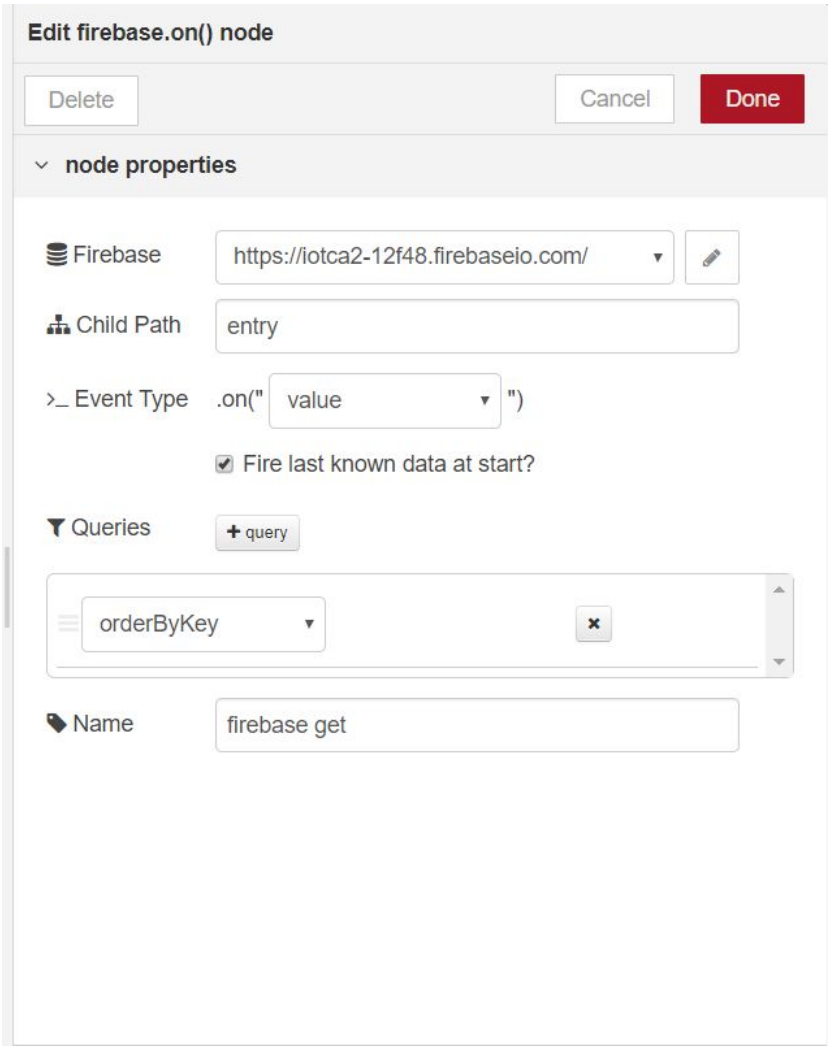
#	Description	Image
1	Click the hamburger icon on the top right followed by Manage Palette	
2	Click the install tab and search for “node-red-contrib-firebase” If it’s not installed yet, go ahead and install it. As you can see, I have already installed it.	

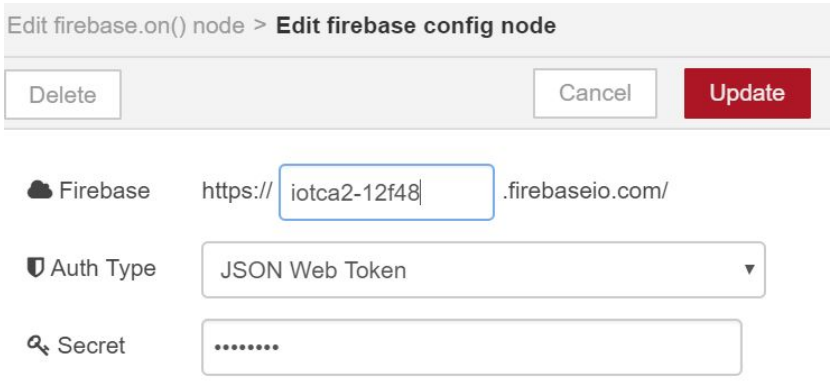
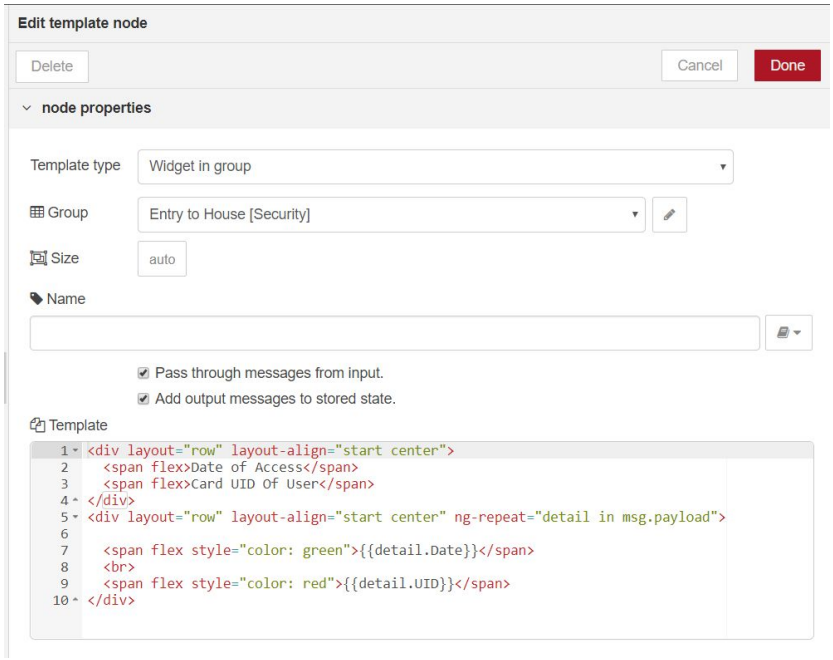
3	Once installed, you should see it on the side in the list of the available nodes.	

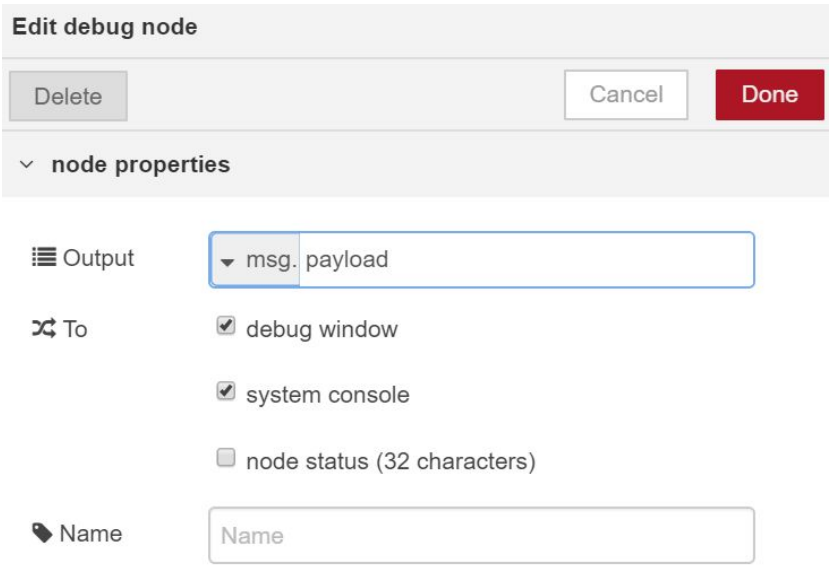
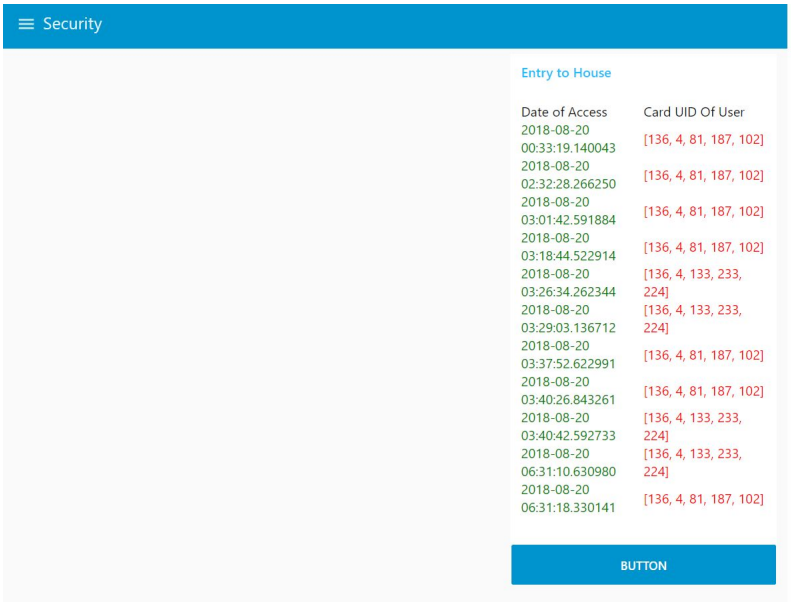
Security

A. Create Scoreboard Node-RED Flow on Bluemix

#	Description	Image
1	On the IBM Bluemix Console. On our App, you'll see this page. Click "Visit App URL"	
2	You'll see this page. Click go to your Node-RED Flow Editor.	
3	This is the flow that we will be creating show who has attempted to enter the house at different timestamps	
4	You will need the following nodes. 1. Firebase.on 2. Template	

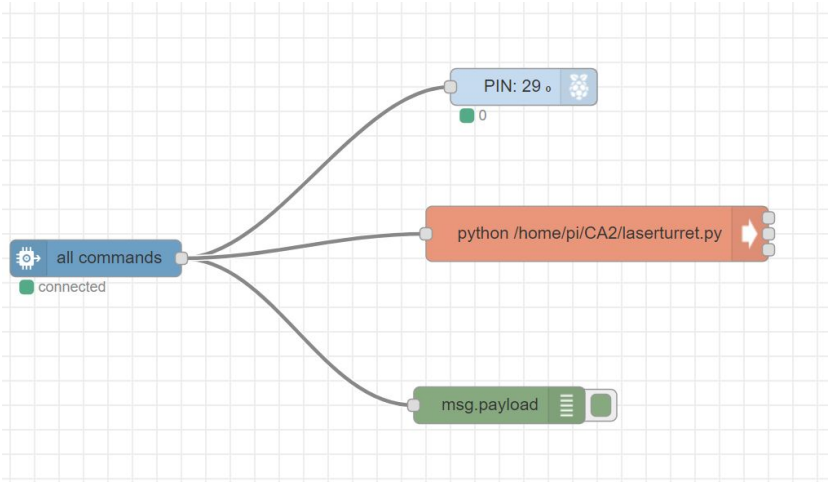
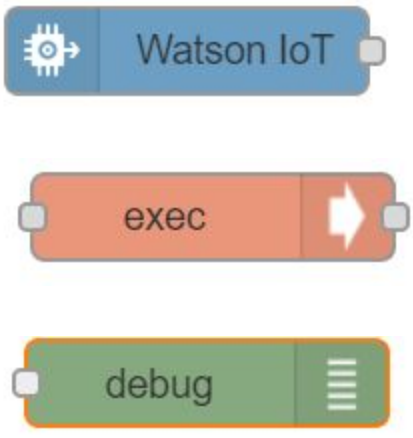
	3. Debug	
5	Double click the firebase.on node. Change the child path to whatever you have set in the code, mine for example is entry	

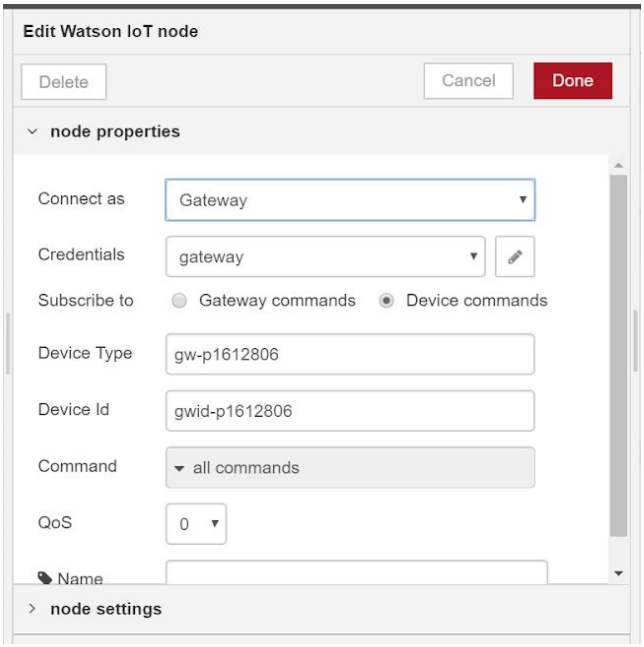
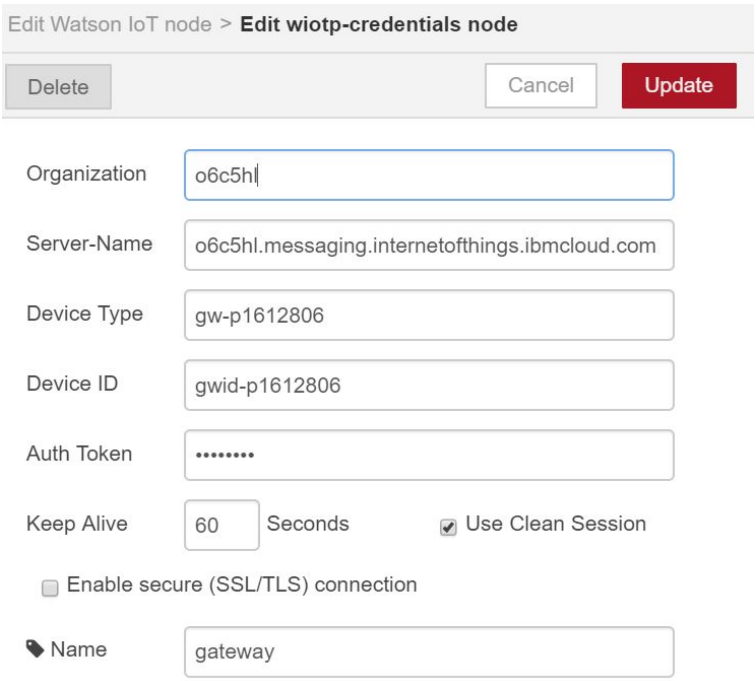
6	You will be prompted to config the firebase auth, enter the secret key which can be retrieved from the firebase console	
7	Double click the template node. Configure it as such.	
8	In the code section, we'll paste the following codes;	`<div layout="row" layout-align="start center">` `  <span flex>Date of Access</span>` `  <span flex>Card UID Of User</span>` `</div>` `<div layout="row" layout-align="start center" ng-repeat="detail in msg.payload">` `  <span flex style="color: green">{{detail.Date}}</span>` `   ` `  <span flex style="color:`

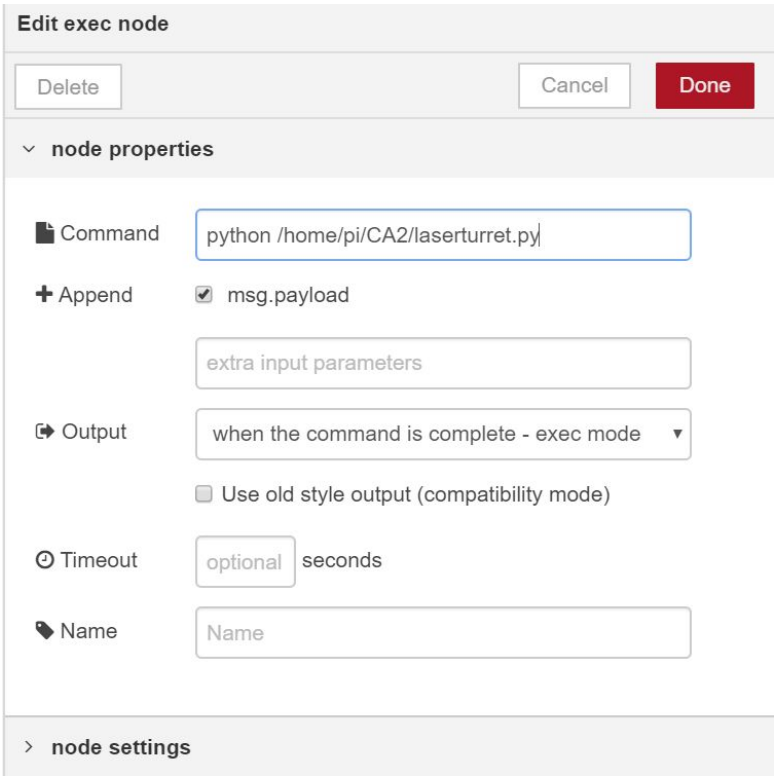
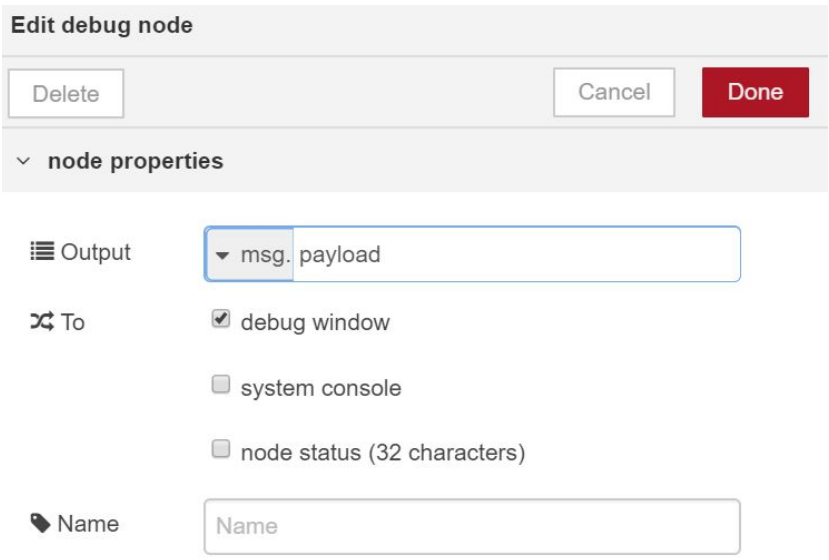
		red">{{detail.UID}}
9	In the debug code, configure it as such. This is just for our reference in case we need it later on.	
10	You can then view who has entered/attempeted to enter your house at what time on the dashboard	

Defence

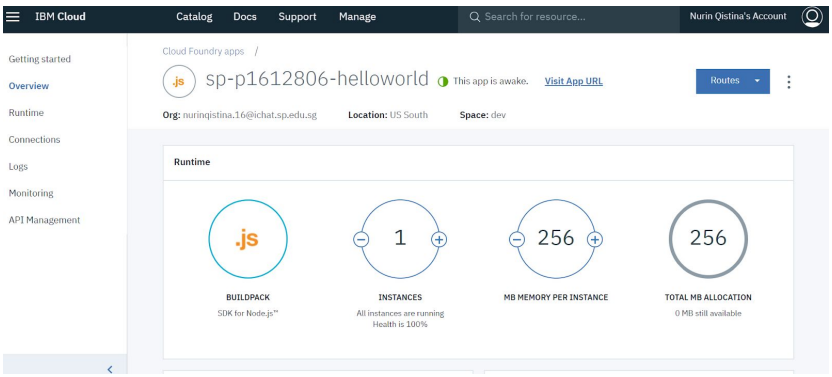
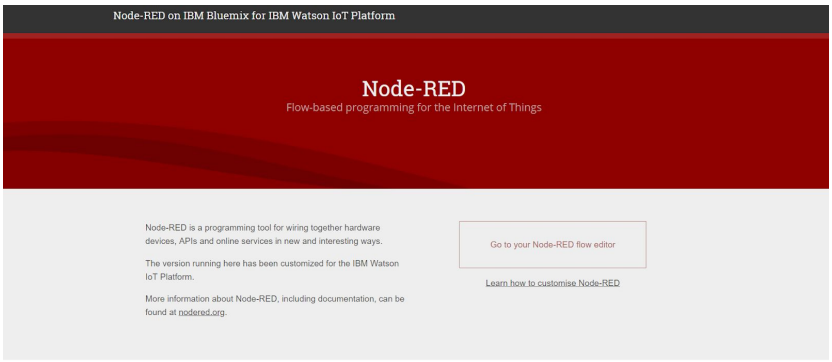
A. Create Node-RED Flow on RPi

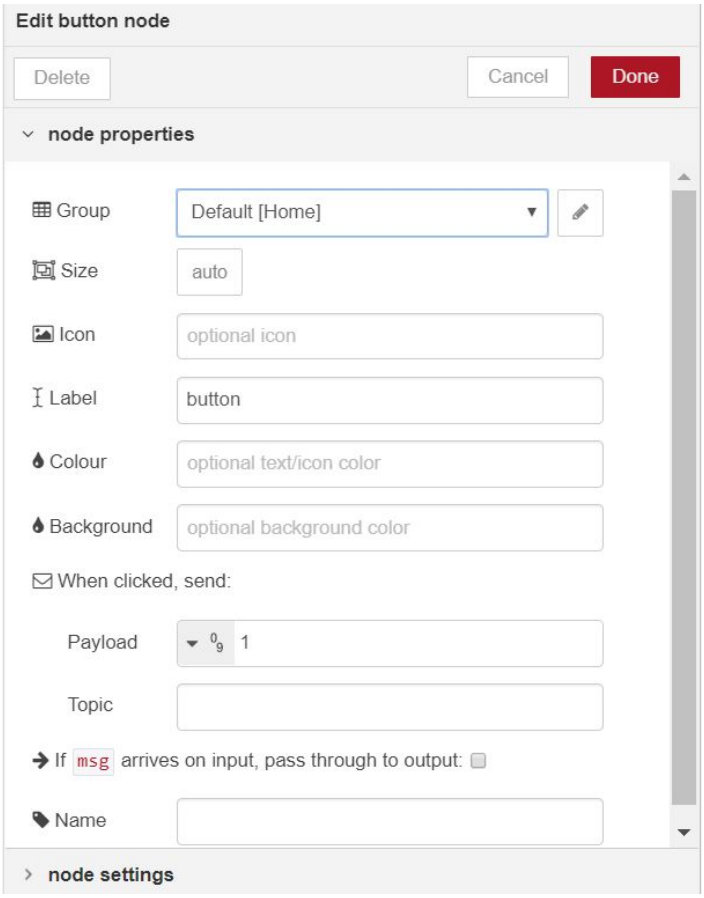
#	Description	Image
1	We are going to create a flow on your Defence RPi. This is a look on the completed flow. How this works is: When there is an input from the watson bluemix IOT end, it will run laserturret.py. In the later sections, we'll create a dashboard where you can interact with the laser turret.	
2	Add the following nodes to your flow. 1. Watson IOT Input 2. Exec 3. Debug	

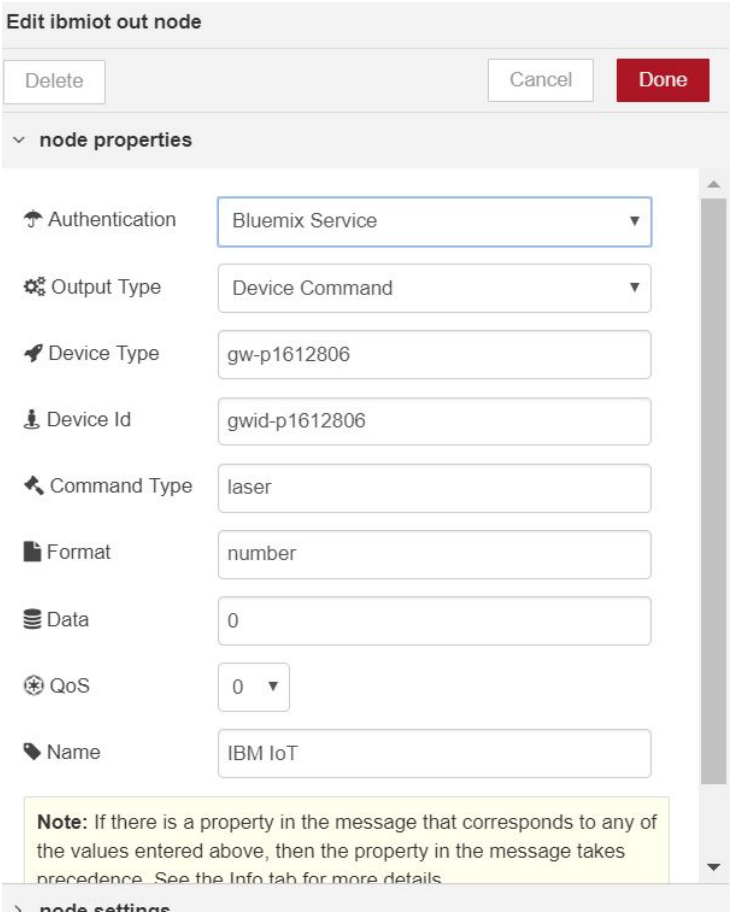
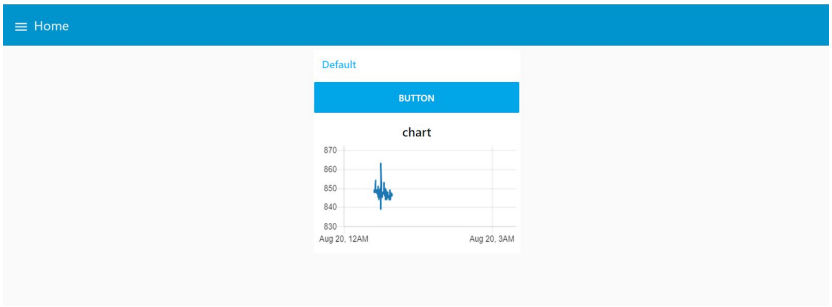
3	Double click your Watson IOT node and set the configurations like so :	
4	You'll be prompted to add new wiotp credentials. Remember previously in section 6 part 1, we added new device gateway and type. We were also given credentials that we saved. This is where you put those credentials.	

5	Double click your exec node. In Section 4, we created a python code called laserturret.py where we store inside our RPi. Now, we'll call it.	
6	Double click the debug node. This is just for our reference later in case we need it.	
7	Run node-red on the defence RPi and continue to the next section.	

B. Create Node-RED Flow on Bluemix

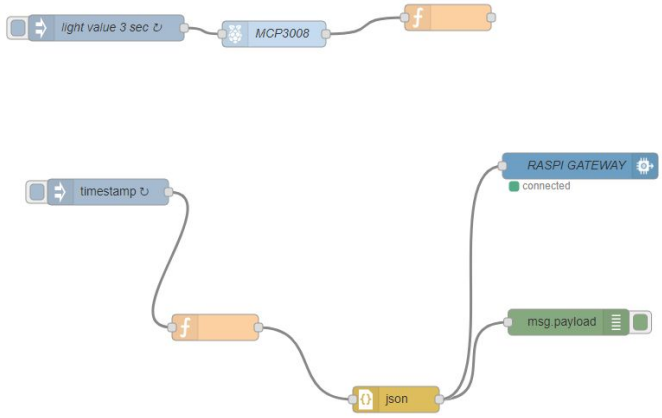
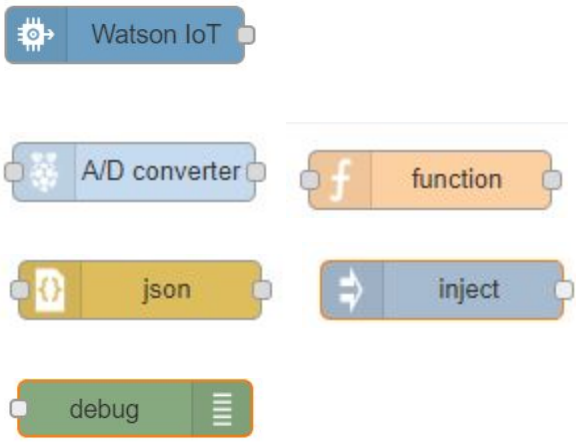
#	Description	Image
1	Back on the IBM Bluemix Console. On our App, you'll see this page. Click "Visit App URL"	
2	You'll see this page. Click go to your Node-RED Flow Editor.	
3	This is the very simple flow that we will create. You will need a button node and a IBM IoT output node.	

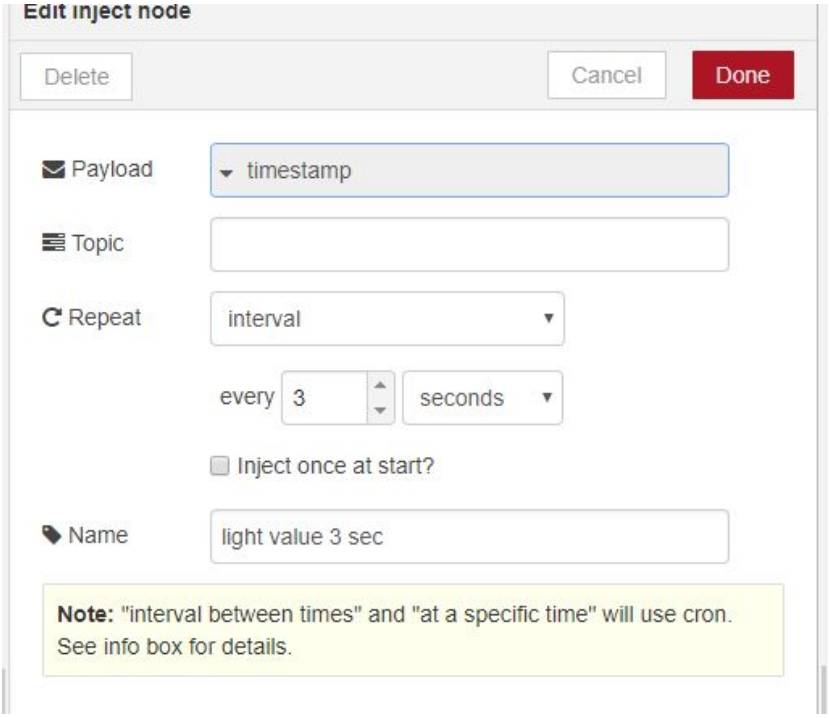
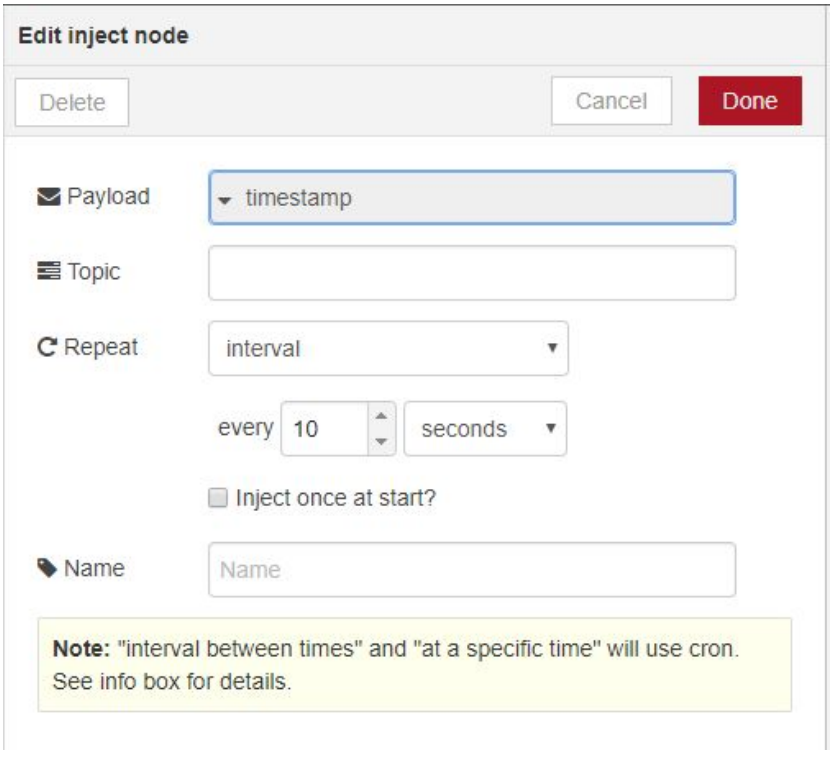
4	Configure the button node as such. This button will stimulate a button press. So whenever this button is pressed, it will send a signal to our Defence RPi and run laserturret.py	

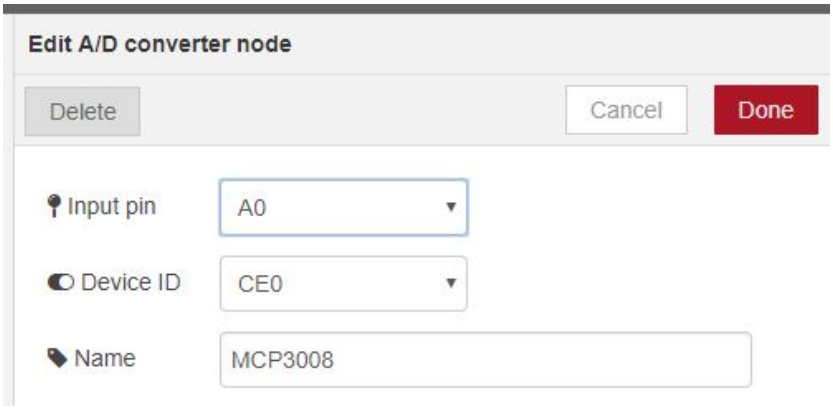
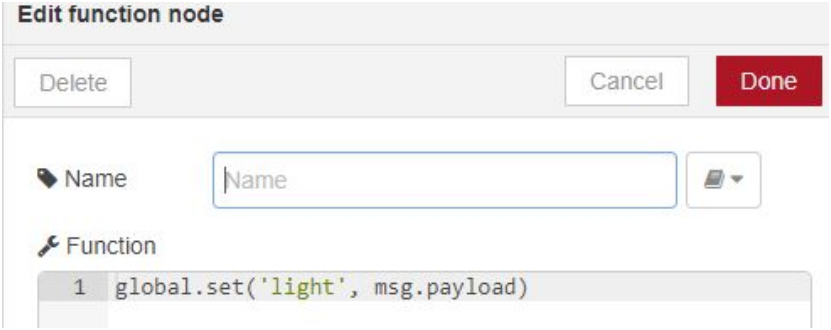
5	Configure the IBM IOT node as such.	
6	Preview on the dashboard. This is what the button will look like on the dashboard! Note that the chart is part of another section in this tutorial.	
7	Now, when you press the button, your laser turret will start attacking any intruders!! Rmb to run node-red flow for the RPi.	

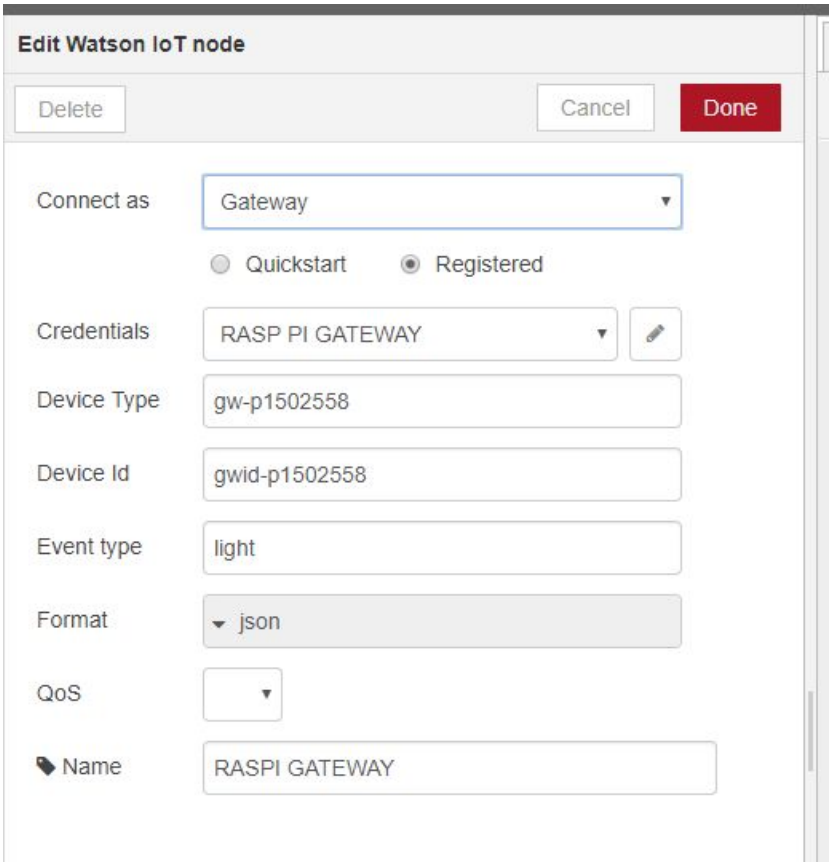
Entertainment

A. Create LDR Node-RED Flow on RPi

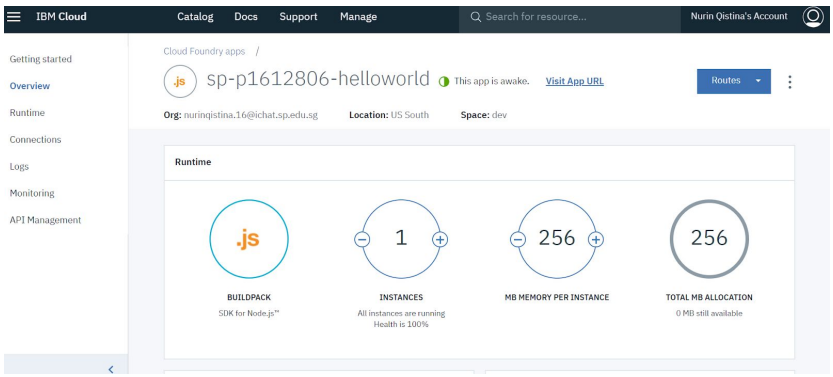
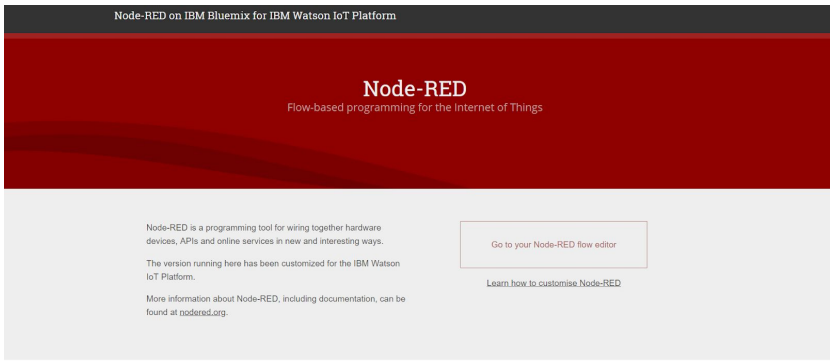
#	Description	Image
1	We are going to create a flow on your Entertainment RPi. This is a look on the completed flow. How this works is: It'll keepsending light data from LDR every 10 seconds In the later sections, we'll create a dashboard where you can interact and view charts of given values	
2	Add the following nodes to your flow. 4. Watson IOT Input 5. A/D Converter 6. Debug 7. Function 8. Json 9. inject	

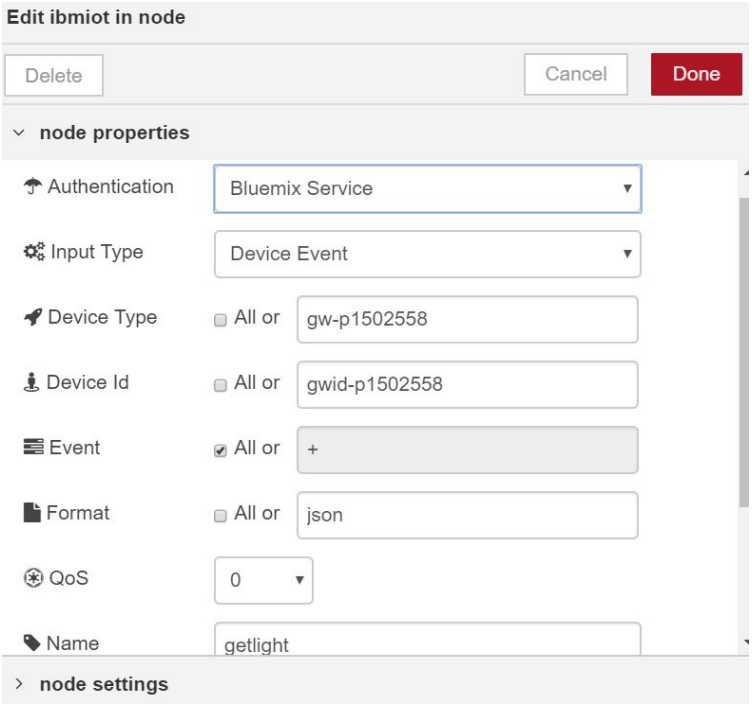
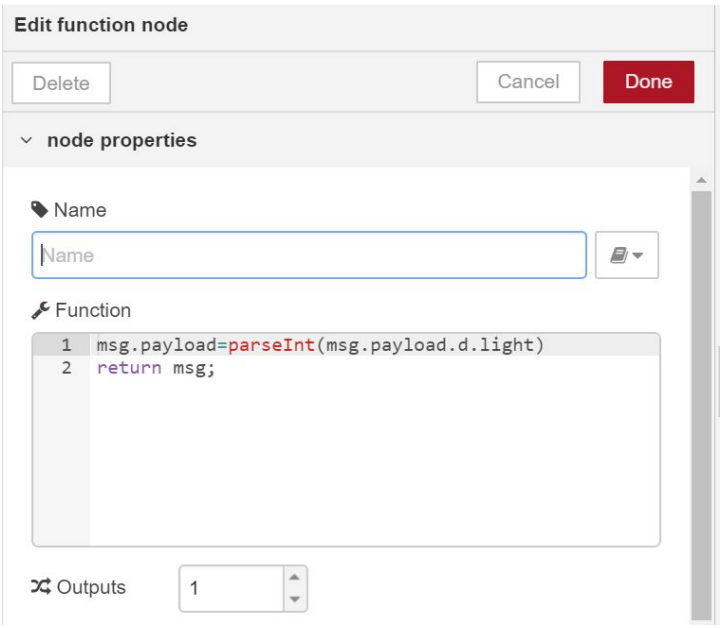
3	Create an injector with interval to store light values and post	
4	Create an injector to send light values to IOT Watson Gateway	

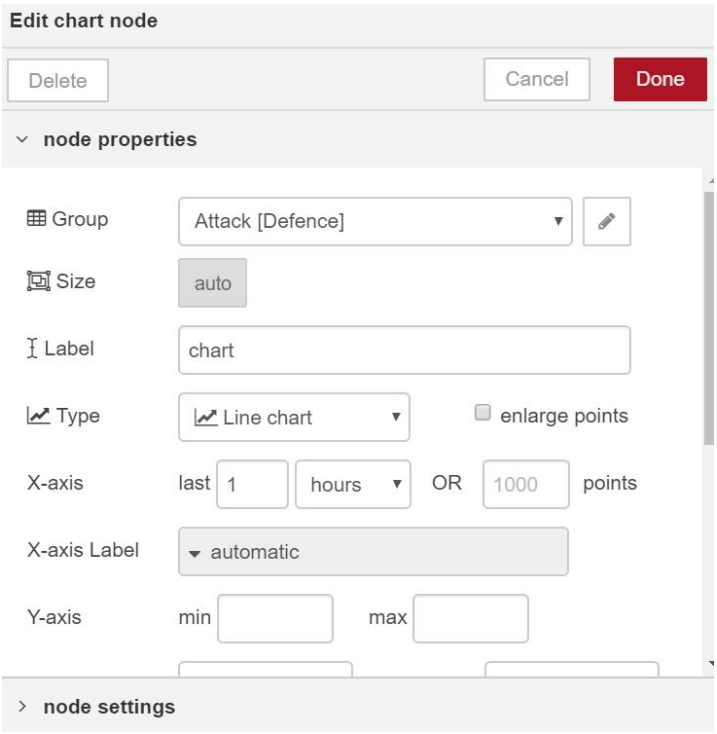
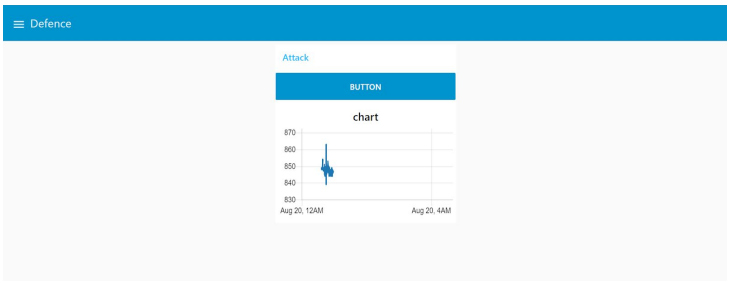
5	Write inputs for MCP3008 node	
6	Parse payload from MCP3008 node to set globally	
7	Read globally set light vaules and convert to json using json node	

8	Parse into IOT Watson Gateway to be sent to ibm node red dashboard	

B. Create LDR Node-RED Flow on Bluemix

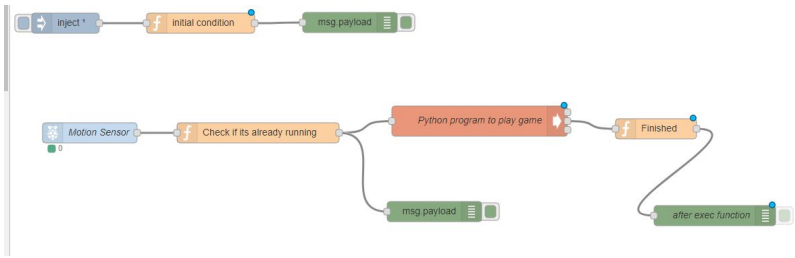
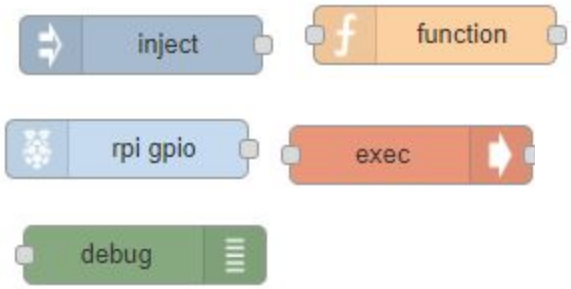
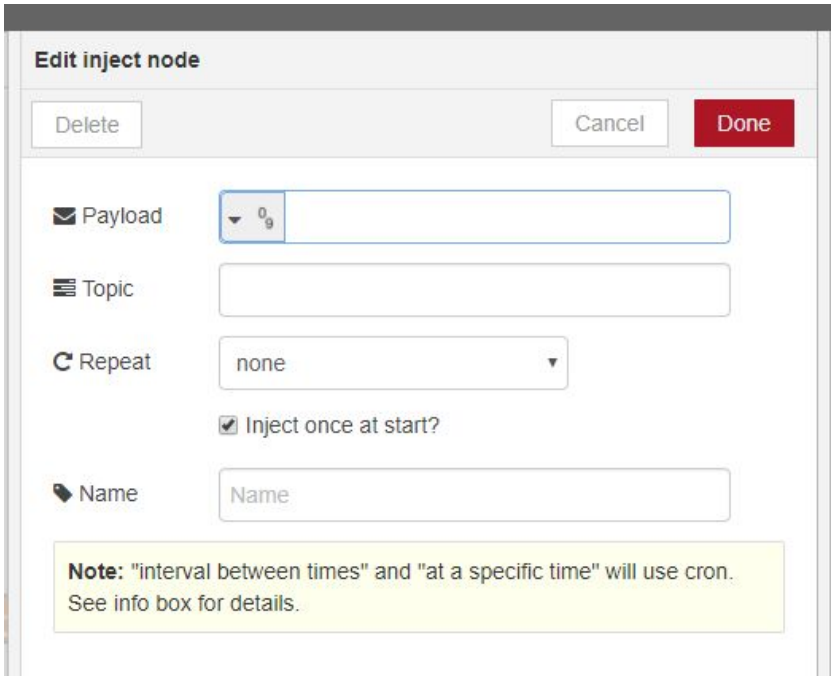
#	Description	Image
1	On the IBM Bluemix Console. On our App, you'll see this page. Click "Visit App URL"	
2	You'll see this page. Click go to your Node-RED Flow Editor.	
3	This is the flow that we will be creating to view ldr values	
4	The nodes you will need are 1. Ibmiot input 2. Function 3. Chart dashboard	 

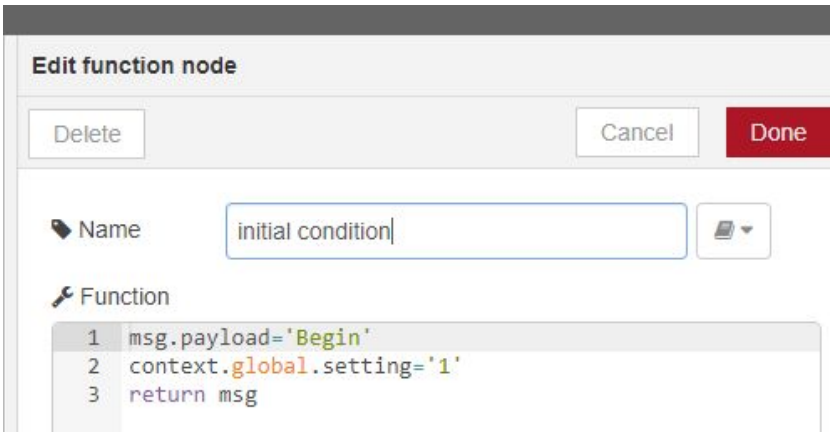
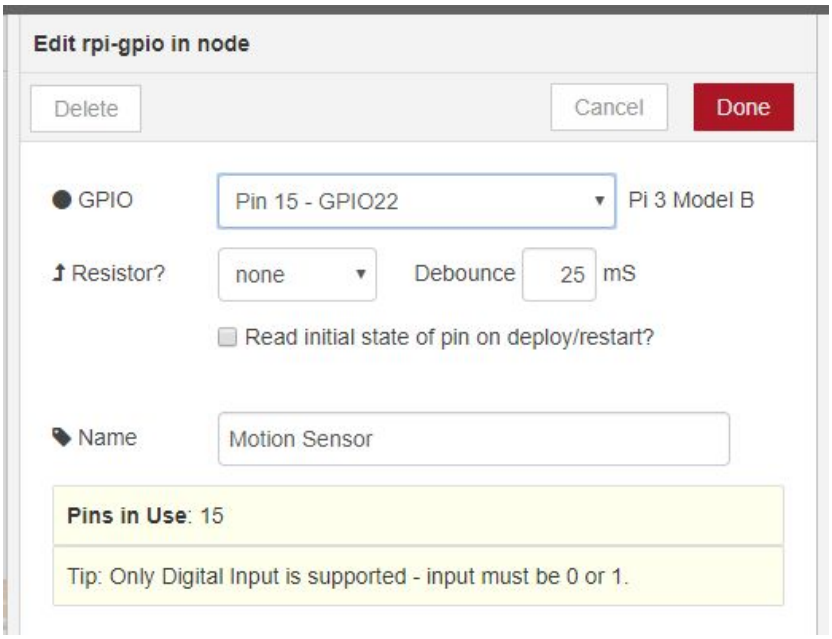
		
5	Double click the ibmiot input node. Configure it like so:	
6	Double click the function node. Configure it like so	

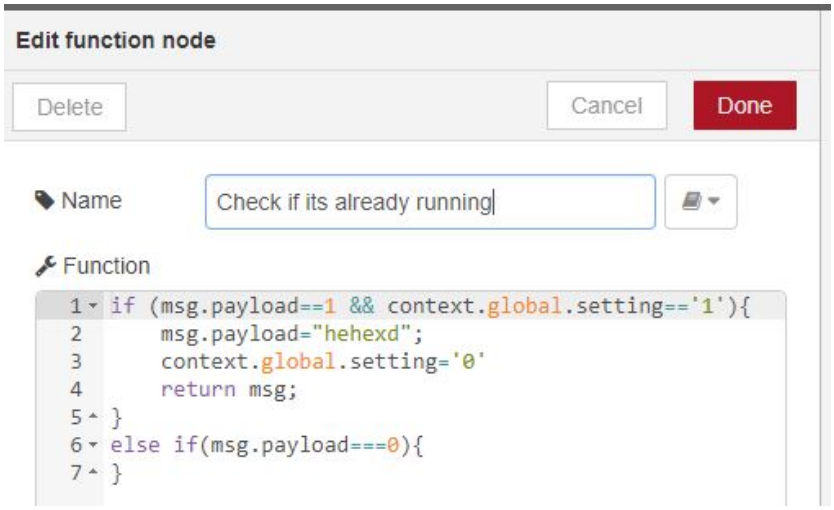
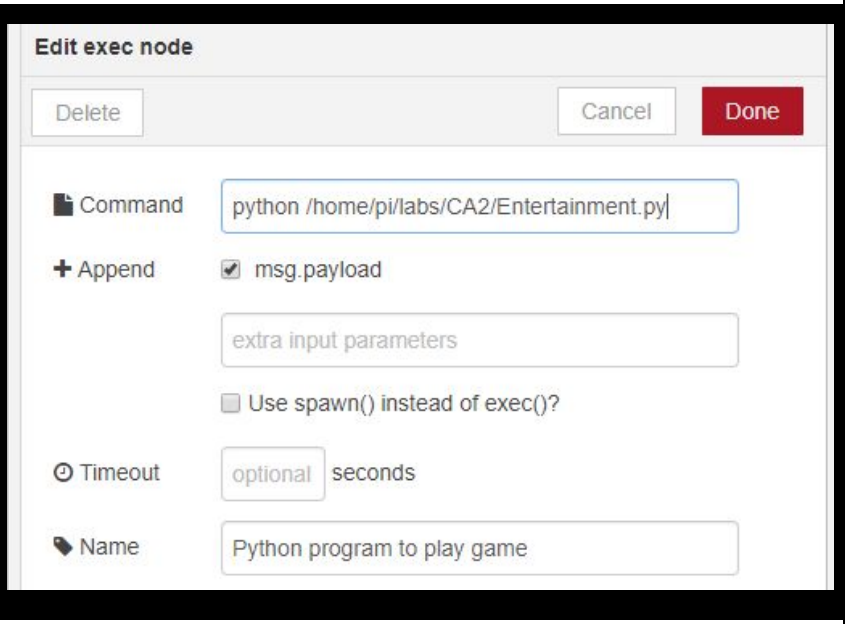
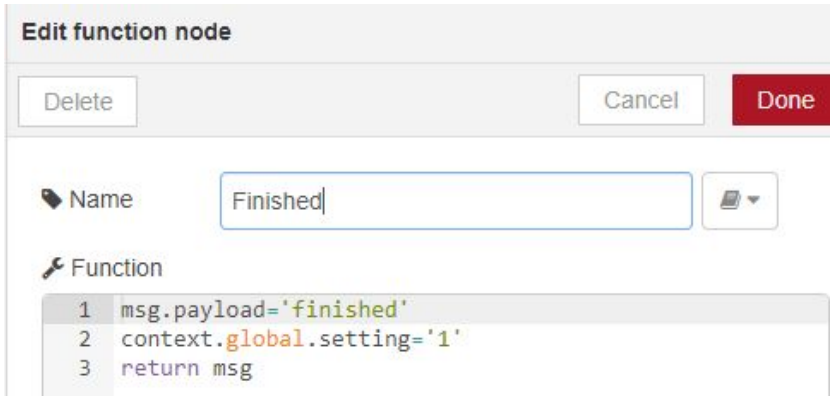
7	Double click the chart node. Configure it like so.	
8	Preview the chart on the dashboard! This is what you will see.	

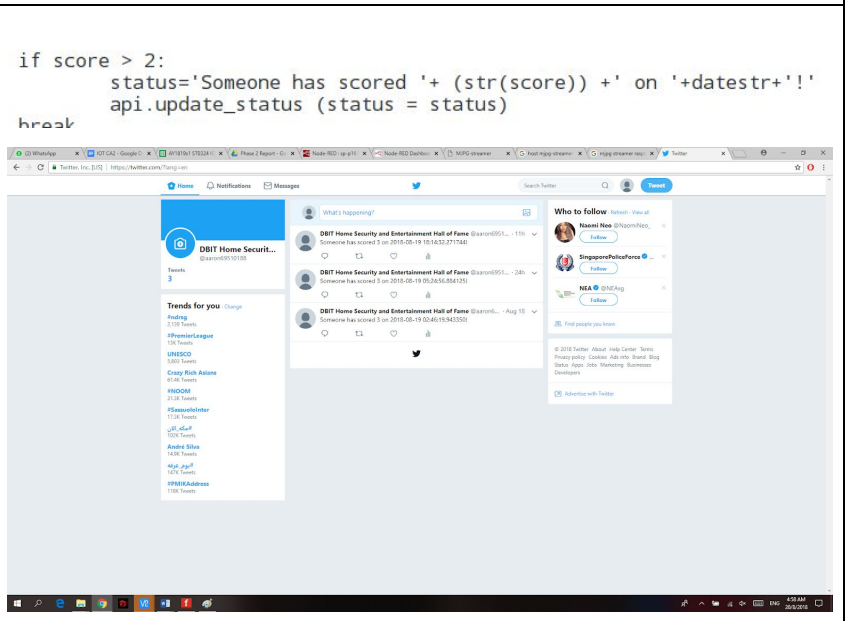
C. Create Entertainment Node-RED Flow on RPi

#	Description	Image

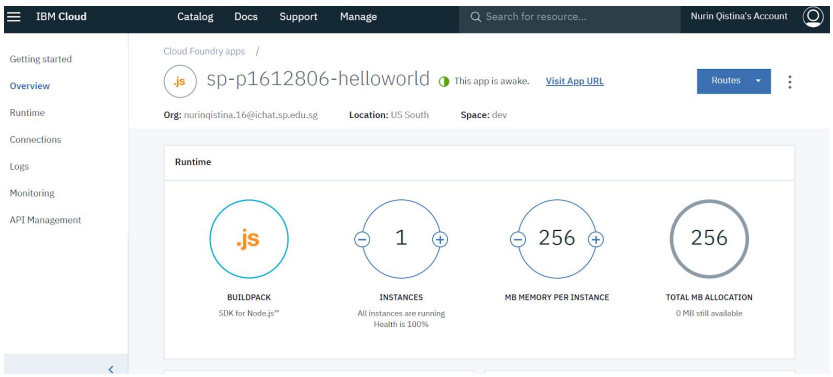
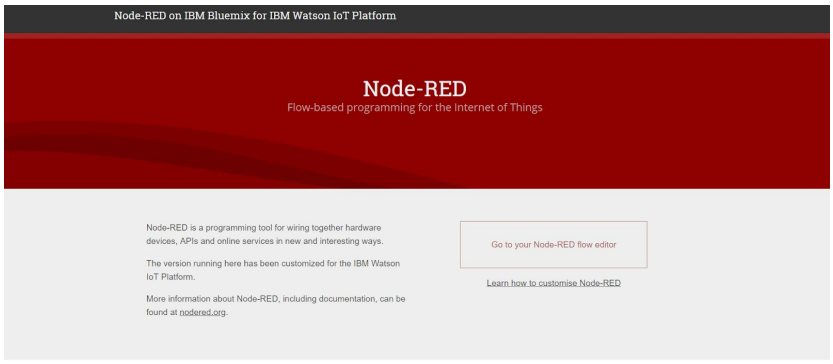
1	On the node-red RPi, create the following flow	
2	You'll need the following nodes 1. Inject 2. Function 3. Rpi gpio 4. Exec 5. debug	
3	This is the branch that we will be creating to set the initial condition, whereby it will start the loop	
4	Create the inject which will inject once at start	

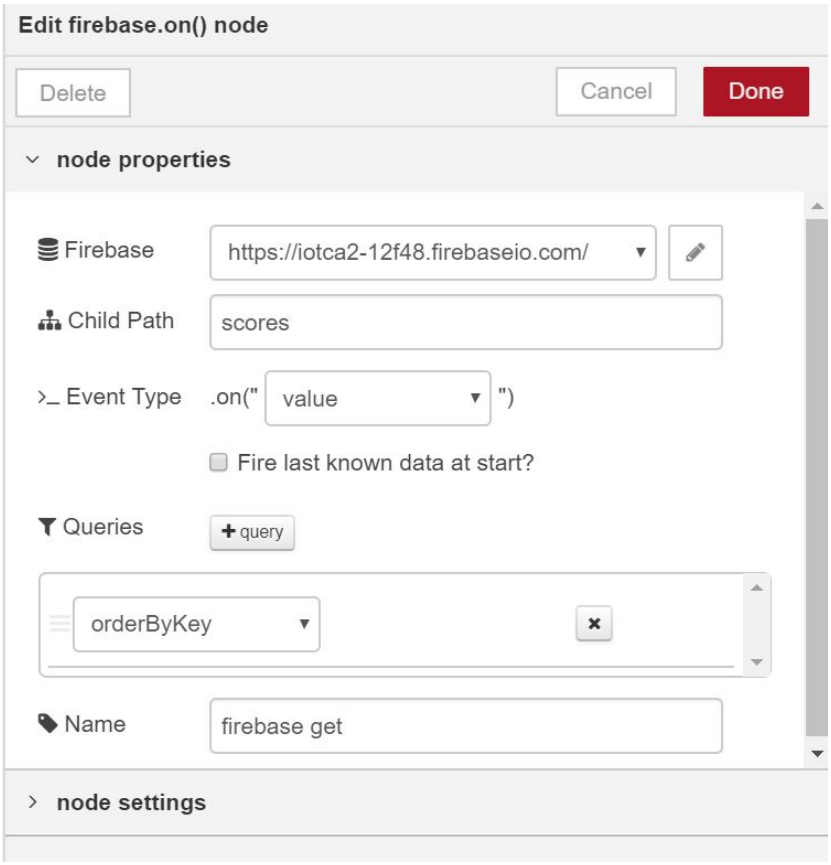
5	Followed by setting a function to create a global variable, this will help kick start the entire program	
6	Create a rpi gpio with the following settings and gpio pin 22 to read from the motion sensor	

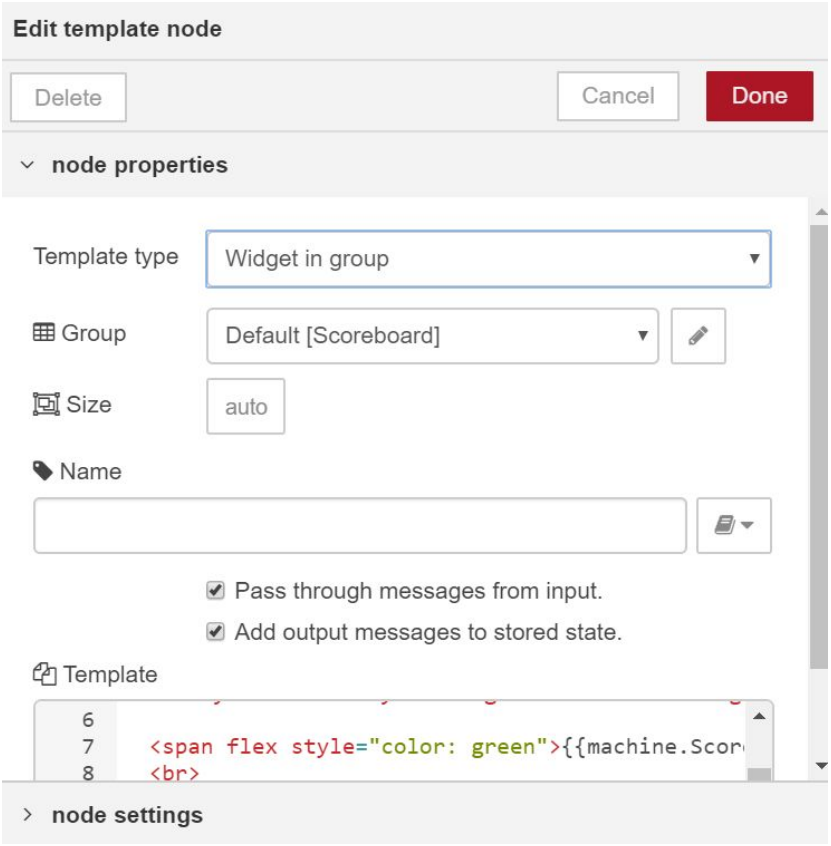
7	Do a function that checks if the program is already running, else continue or wait	
8	If the program is not running, execute a python file from the entertainment RPi, which will run the gamification of simon says.	
9	Finally, after the program is finished, run a function to set the global variable back to 1, in order to continue the program	

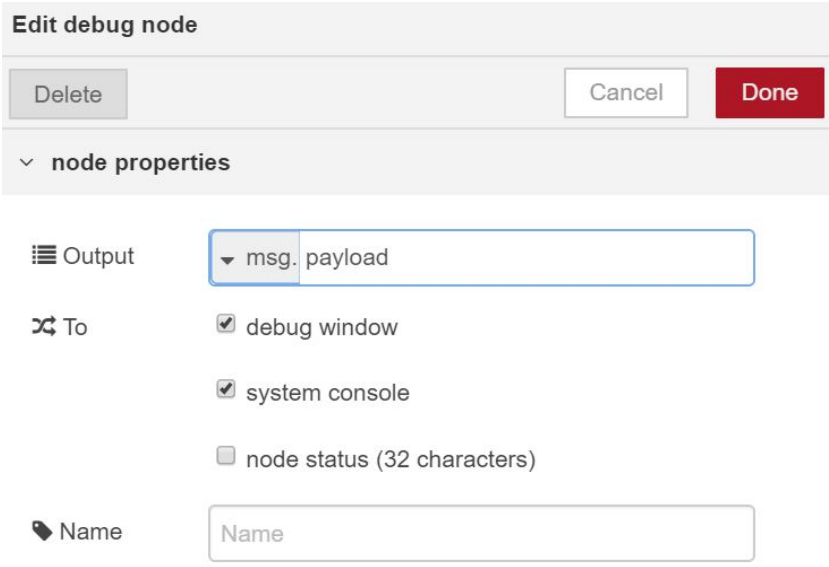
10	This means that when everytime motion is sensed, the program will run and if theres already an instance whereby the game is running, it will not execute another time. Additionally, game scores and timestamps will be stored into firebase nosql database in the executional file which can be seen on the right.	
11	Additionally, a twitter bot was implemented as our hall of fame channel whereby the code will automatically detect people who score more than 3 points and will post it on our twitter page !	

D. Create Scoreboard Node-RED Flow on Bluemix

#	Description	Image
1	On the IBM Bluemix Console. On our App, you'll see this page. Click "Visit App URL"	
2	You'll see this page. Click go to your Node-RED Flow Editor.	
3	This is the flow that we will be creating to list down the scores from the simon-says game.	
4	You will need the following nodes. 4. Firebase.on 5. Template 6. Debug	 

		
5	Double click the firebase.on node.	
6	You will be prompted to config the firebase auth	

7	Double click the template node. Configure it as such.	
8	In the code section, we'll paste the following codes;	`<div layout="row" layout-align="start center">` `  <span flex>score</span>` `  <span flex>date</span>` `</div>` `<div layout="row" layout-align="start center" ng-repeat="machine in msg.payload">` `  <span flex style="color: green">{{machine.Score}}</span>` `   ` `  <span flex style="color: red">{{machine.Date}}</span>` `</div>`

9	In the debug code, configure it as such. This is just for our reference in case we need it later on.	
10	Preview it on the dashboard!