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import time
import board
import pwmio
from adafruit_motor import servo
from adafruit_circuitplayground import cp
# create a PWMOut object on Pin A1.
pwm = pwmio.PWMOut(board.A1, frequency=50)

# Create a servo object, my_servo.
my_servo = servo.ContinuousServo(pwm)

cp.pixels.brightness = 0.3

while True:
    print("forward")
    my_servo.throttle = -0.125
    cp.pixels[0] = (255, 255, 0)
    cp.pixels[1] = (0, 255, 255)
    cp.pixels[0] = (255, 255, 0)
    cp.pixels[1] = (0, 255, 255)
    cp.pixels[2] = (255, 0, 255)
    cp.pixels[3] = (255, 255, 0)
    cp.pixels[4] = (0, 255, 255)
    cp.pixels[5] = (255, 0, 255)
    cp.pixels[6] = (255, 255, 0)
    cp.pixels[7] = (0, 255, 255)
    cp.pixels[8] = (255, 0, 255)
    cp.pixels[9] = (255, 255, 0)
    time.sleep(60.0)
    print("reverse")
    my_servo.throttle = 0.125
    time.sleep(60.0)
    print("stop")
    my_servo.throttle = 0.0
    cp.play_tone(1000, 2)
    cp.play_tone(500, 1)
    cp.play_tone(1000, 2)
    cp.play_tone(500, 1)
    break
```