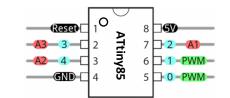


# Sparkfun Electronics ATtiny85 Arduino Quick Reference Sheet



## **Structure**

```
/* Each Arduino sketch must contain the
following two functions. */

void setup()
{ // this code runs once at the
    // beginning of the code execution.
}

void loop()
{ // this code runs repeatedly over
    // and over as long as the board is
    // powered.
}
```

#### Comments

```
// this is a single line comment
/* this is
  a multiline
  comment */
```

# Setup

```
pinMode(pinNum, INPUT/OUTPUT/INPUT_PULLUP);
/* Sets the mode of the digital I/O pin.
All pins are general I/O on the board. You
must define what the pin will be used for at
the beginning of your code in setup() */
```

## **Control Structures**

```
if(condition)
{    // if condition is true, do something here
}
else
{    // otherwise, do this
}

for(init; condition; increment)
{
    // do this, increment, and
    // repeat while condition is true.
}
```

. . . . . . . . . . . . . . . . . . . .

# Digital I/O

```
digitalWrite(pin, val);
```

/\* val = HIGH or LOW write a HIGH or a LOW
value to a digital pin. \*/

## buttonVal = digitalRead(pin);

 $/\ast$  Reads the value from a specified digital pin, either HIGH or LOW.  $^{\star}/$ 

# Analog I/O

#### analogWrite(pin, val);

/\* Writes an analog voltage (using PWM) to a
pin. val = integer value from 0 to 255 \*/

## sensorVal = analogRead(pin);

 $/\!\!^*$  Reads the voltage from the specified analog pin. 0V returns 0; Vcc returns 1023\*/

#### Time

## delay(time ms);

/\* Pauses the program for the amount of time (in milliseconds). \*/

#### millis();

/\* Returns the number of milliseconds since
the board began running the current program.
max: 4,294,967,295 \*/

## **ATtinv85 Pins**

```
Pins 0 - 4 : general purpose I/O pins (GPIO).
```

Both digitalWrite() and digitalRead() can be used with any of these pins.

Pins 0 & 1 : setup for PWM outputusing analogWrite().

Pins A1, A2, A3 : setup for reading
sensor input with analogRead().

## **Data Types**

#### **Serial Communication**

A separate USB to serial adapter like FTDI is needed for Serial communication with the ATtiny. And. the ATtiny must be flashed to run at 8 MHz instead of 1 MHz.

The ATtiny does not support Serial natively. You need to use SoftwareSerial to enable this function.

The 'for' loop is used to repeat a block of statements enclosed in curly braces. An increment counter is usually used to increment (or decrement) and terminate the loop.

#include < SoftwareSerial.h> // include library

#### SoftwareSerial tinySerial(3, 4);

/\* Put above setup() and loop() - declares tinySerial using 3 & 4 for Transmit (tx) and Receive (rx) \*/  $\,$ 

tinySerial.begin(9600); /\* begin Serial at
9600 baud. Put this line in setup() \*/

tinySerial.print(""); /\* sends data on TX line
- to your receiving computer. \*/

tinySerial.println(""); /\* sends data to
Serial Monitor with CRLF. \*/

inChar = tinySerial.read();