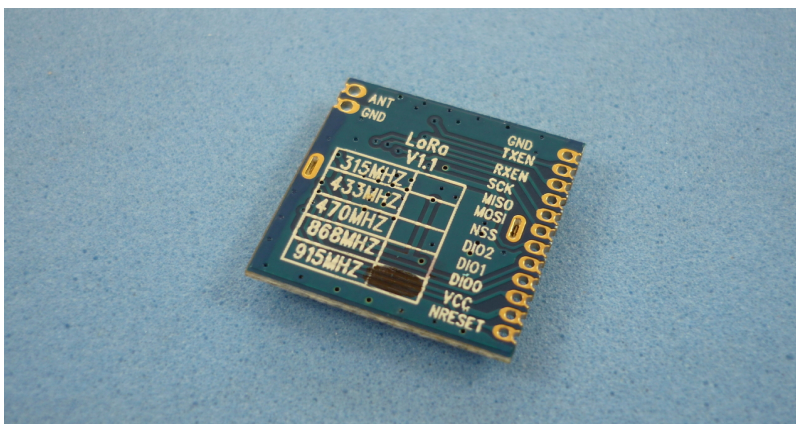


INTERNET OF THINGS USING NICERF LORA1276



LPWAN and LORA

Internet of things (IoT) has evolved in such way that every day is cheaper, smaller and less power hungry to communicate "things" that were impossible a few years ago. Now technologies like GSM and WiFi are the most used for that task, but has their disadvantages:

- GSM, 3G, LTE: High costs: A data plan is needed for communications, high energy consumption.

WiFi, BLUETOOTH : Low distance coverage (tens of meters inside buildings) , high energy consumption!

To overcome the disadvantages of previous technologies, LPWAN (Low Power Wide Area Network) has been proposed, and must fill some requirements:

- Oriented to devices with low data volume and sporadic communications.
- Low power consumption, so battery operated devices could work for many years.
-
- Wide area coverage to send and receive data without problems inside buildings, basements, industrial boxes, etc
-
-

There are now a lot of technologies in the same path like LoRa, LTE-MTC, RPMA, UNB, and others more

LoRa alliance (CISCO, IBM, SEMTECH, MICROCHIP and others) aims to create a wireless communication standard for battery operated devices with regional, national or global coverage.

More info:

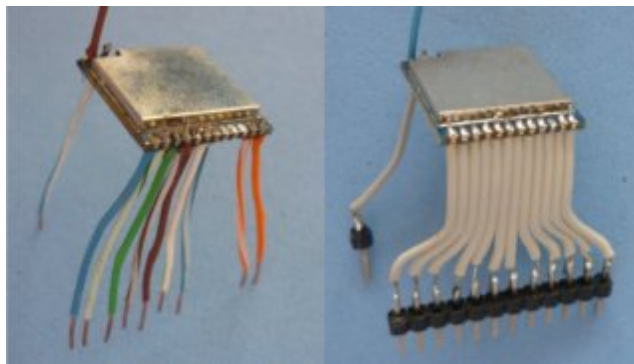
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The main advantage of LoRa is the use of ISM (Industrial, Scientific and Medical) bands, so every person could create their own LPWAN without paying royalties or spectrum fees, as long as stays inside nations's regulations.

NiceRF LoRa1276

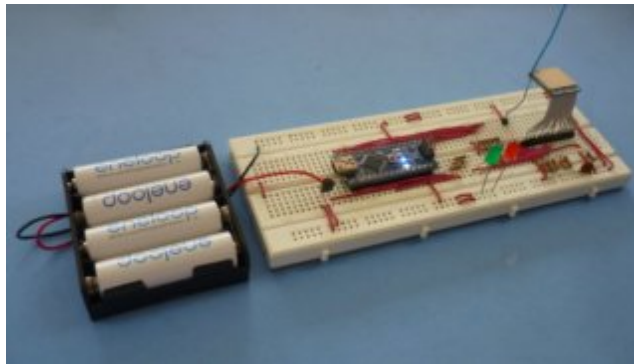
There are a lot of manufacturers of LoRa compatible modules. All of them uses SEMTECH chips, guaranteeing better c between different manufacturer's modules. The module used here is LoRa1276, manufactured by NiceRF. The modules cost about 20 dollars/pair (worldwide shipping included!) and incorporates SX1276 chip. The manufacturer claims 10km range in line-of-sight, and 1k in urban environments with a max transmission power of 120mW. The modules' package aren't hobbyist friendly due to distance between pads (1.27 mm) isn't compatible with standard breadboard (2.54 mm), however is possible to make a homemade adapter with a bit of creativity.



The SX1276 chip embedded in the module is able to operate from 100 MHz to 1050 MHz. However, this chip requires some external components between RF input/output pins and antenna. To minimize component burden and design complexity, the integrator put some passive and active components (capacitors, inductors, RF switch) to form a matched network, that will operate efficiently only in a small frequency range. There are different versions of modules manufactured to work in different ISM bands (a,b,c,d) to match local radio spectrum regulations, because not all countries allow to use the same ISM bands. In this example the 915Mhz version is used.

Lora 1276 and Arduino

Communication with the module is done via SPI, using an Arduino Nano (Clone) for the setup. Additional to the SPI signals, this module requires handling of additional signals. As the module works with 3.3 V max and Arduino Nano with 5 V, some signal level translation is required between Arduino and SX1276. If you don't have a signal level translation chip in your parts bin, you can work with resistors to make a voltage divider and work with the SPI in the lowest speed. The module can work as a transmitter and as a receiver, but not simultaneously. The sample code is based on an example provided by NiceRF. The module can work in different modes:



Modulation: OOK, FSK and LoRa

Error detection and correction: FEC and Cheksum

Power modes: Low power modes (for battery operated devices) and full power modes.

Interference suppression: Multiple chirp and spread factors

In the example presented, the highest power and sensibility settings were used, and works in the following way:

The transmitter sends a periodic message, on each packet sent a LED is toggled

The receiver is listening for the message, if it's received without errors a LED is toggled, if no error is detected another different LED will be toggled

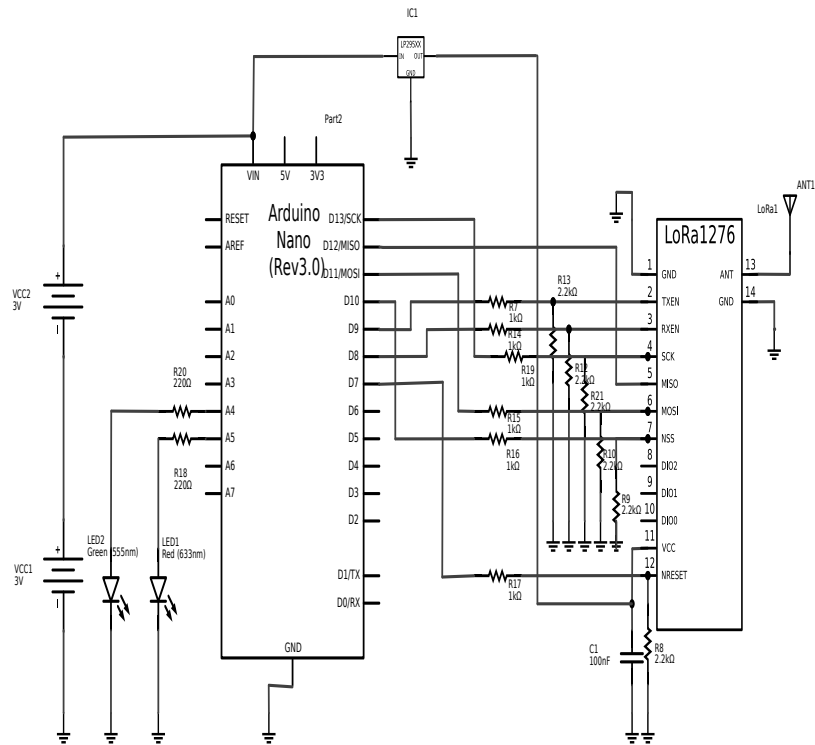
That's a very easy way to test the range of the devices. Put the transmitter in a fixed site and move the receiver until a bad message received or no message received at all in the expected interval of time.

The software is just a little example, but could be expanded to make a more robust system

CONCLUSIONS

- In the example presented, a wire was cut to 1/4 wavelength (915 MHz) as an antenna. With a better designed antenna and in a higher position like building roof, or a tower a much more range could be obtained in urban environments.
- The module only provides the lowest OSI model layers, it's up to the user to choose an already developed communication stack or made their own according their needs.
- To test the maximum sensitivity of the receiver (and the longest transmission range) a Temperature Compensated Crystal Oscillator (TCXO) is mandatory. The module only incorporates a low cost crystal.
- The example shown, not exactly communicates a device with internet, but adding an Ethernet module to the Arduino is a relative simple task

SCHEMATIC



ARDUINO SOFTWARE TX

LORA1276TX.ino

```
/*
NiceRF LoRa1276 Module Arduino NANO Clone V3

NANO   LoRa1276
D11 MOSI 6 MOSI
D12 MISO 5 MISO
D13 SCK  4 SCK
D10     7 NSS

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*/

// using SPI library:
#include <SPI.h>

// Digital pins definition
#define MOSI 11
#define MISO 12
#define SCK  13
#define SS   10

#define NRESET 7
#define TXEN  9
#define RXEN  8
#define LED1  A4
#define LED2  A5

// register definition

#define LR_RegFifo          0x00
#define LR_RegOpMode       0x01
#define LR_RegBitrateMsb   0x02
#define LR_RegBitrateLsb   0x03
#define LR_RegFdevMsb      0x04
#define LR_RegFdMsb        0x05
#define LR_RegFrMsb        0x06
#define LR_RegFrMid        0x07
#define LR_RegFrLsb        0x08
#define LR_RegPaConfig     0x09
#define LR_RegPaRamp       0x0A
#define LR_RegOcp          0x0B
#define LR_RegLna          0x0C
#define LR_RegFifoAddrPtr  0x0D
#define LR_RegFifoTxBaseAddr 0x0E
#define LR_RegFifoRxBaseAddr 0x0F
#define LR_RegFifoRxCurrentaddr 0x10
#define LR_RegIrqFlagsMask 0x11
#define LR_RegIrqFlags     0x12
#define LR_RegRxNbBytes    0x13
#define LR_RegRxHeaderCntValueMsb 0x14
#define LR_RegRxHeaderCntValueLsb 0x15
#define LR_RegRxPacketCntValueMsb 0x16
#define LR_RegRxPacketCntValueLsb 0x17
#define LR_RegModemStat    0x18
#define LR_RegPktSnrValue  0x19
#define LR_RegPktRssiValue 0x1A
#define LR_RegRssiValue    0x1B
#define LR_RegHopChannel   0x1C
#define LR_RegModemConfig1 0x1D
#define LR_RegModemConfig2 0x1E
```

More info:

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```

#define LR_RegSymbTimeoutLsb      0x1F
#define LR_RegPreambleMsb        0x20
#define LR_RegPreambleLsb        0x21
#define LR_RegPayloadLength       0x22
#define LR_RegMaxPayloadLength    0x23
#define LR_RegHopPeriod           0x24
#define LR_RegFifoRxByteAddr      0x25
#define LR_RegModemConfig3        0x26
#define REG_LR_DIOMAPPING1        0x40
#define REG_LR_DIOMAPPING2        0x41
#define REG_LR_VERSION            0x42
#define REG_LR_PLLHOP              0x44
#define REG_LR_TCXO                 0x4B
#define REG_LR_PADAC                0x4D
#define REG_LR_FORMERTEMP          0x5B
#define REG_LR_AGCREF               0x61
#define REG_LR_AGCTHRESH1          0x62
#define REG_LR_AGCTHRESH2          0x63
#define REG_LR_AGCTHRESH3          0x64

// payload length
#define payload_length 7

// tx packet
unsigned char txbuf[payload_length]={'t','e','s','t','i','n','g'};
// rx packet
unsigned char rxbuf[30];

// Initialization
void setup() {
  byte temp = 0;

  // Initializing serial port, usefull for debugging
  Serial.begin(9600);

  // Initializing SPI pins

  pinMode(MOSI, OUTPUT);
  pinMode(MISO, INPUT);
  pinMode(SCK,OUTPUT);
  pinMode(SS,OUTPUT);
  digitalWrite(SS,HIGH); //disabling LoRa module

  // Initializing other I/O pins
  pinMode(NRESET, OUTPUT);
  pinMode(TXEN, OUTPUT);
  pinMode(RXEN, OUTPUT);
  pinMode(LED1, OUTPUT);
  pinMode(LED2, OUTPUT);

  digitalWrite(NRESET,HIGH); // Deassert reset
  digitalWrite(TXEN,LOW); // Disabling tx antenna
  digitalWrite(RXEN,LOW); // Disabling rx antenna
  digitalWrite(LED1,LOW);
  digitalWrite(LED2,LOW);

  /* Initializing SPI registers
  description of every SPCR register bits
  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
  | SPIE | SPE | DORD | MSTR | CPOL | CPHA | SPR1 | SPR0 |

  SPIE - Enable SPI interrupt (logic 1)
  SPE - Enable SPI (logic 1)
  DORD - Send Least Significant Bit (LSB) first (logic 1) , Send Most Significant Bit (MSB) first (logic 0)
  MSTR - Enable SPI master mode (logic 1), slave mode (logic 0)
  CPOL - Setup clock signal inactive in high (logic 1), inactive in low (logic 0)
  CPHA - Read data on Falling Clock Edge (logic 1), Rising edge (logic 0)

```

SPR1 y SPR0 - Setup SPI data rate: 00 Fastest (4MHz), 11 Slowest (250KHz)

```
// SPCR = 01010011
//interrupt disabled,spi enabled,most significant bit (msb) first,SPI master,clock inactive low,
data fech rising clock edge, slowest data rate*/
```

```
SPCR = (1<<SPE)|(1<<MSTR)|(1<<SPR1)|(1<<SPR0);
temp=SPSR; //Reading and discarding previous data
temp=SPDR; //Reading and discarding previous data
delay(10);
```

```
}
```

```
void loop() {
```

```
digitalWrite(LED1,LOW);
digitalWrite(LED2,LOW);
```

```
reset_sx1276();
Config_SX1276(); // intializing RF module
```

```
while(1){
  mode_tx(); // transmit packet
  delay(300);
```

```
}
```

```
}
```

```
byte SPIreadRegister(byte addr) {
```

```
byte result;
```

```
digitalWrite(SS, LOW); // Select LoRa module
```

```
SPDR = addr; // Send address & Start transmission. In READ mode bit 7 of address is always 0! for sx1276
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR; // Discard first reading
```

```
SPDR = 0x0; // Sending dummy byte to get the result
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR; // Reading register value
```

```
digitalWrite(SS, HIGH); // Deselect LoRa module
```

```
return (result);
```

```
}
```

```
byte SPIwriteRegister(byte addr,byte value) {
```

```
byte result;
```

```
digitalWrite(SS, LOW); // Select LoRa module
```

```
SPDR = addr | 0x80; // Send address & Start transmission. In WRITE mode bit 7 of address is always 1! for sx1276
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR; // Discard first reading
```



```

SPDR = value;          // Sending byte
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR;        // Discard second reading

digitalWrite(SS, HIGH); // Deselect LoRa module
}

void SPIwriteBurst(unsigned char addr, unsigned char *ptr, unsigned char len)
{
    unsigned char i;
    unsigned char result;

    digitalWrite(SS, LOW); // Select LoRa module

    SPDR = addr | 0x80; // Send address & Start transmission. In WRITE mode bit 7 of address is always 1! for sx1276
    while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
    {
};
    result = SPDR; // Discard first reading

    for (i=0; i <= len; i++){

        SPDR = *ptr; // Sending bytes
        while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
        {
};
        result = SPDR; // Discard second reading

        //DEBUG DEBUG DEBUG
        Serial.print(*ptr, HEX);
        //DEBUG DEBUG DEBUG

        ptr++;
    }

    //DEBUG DEBUG DEBUG
    Serial.print("\n");
    //DEBUG DEBUG DEBUG

    digitalWrite(SS, HIGH); // Deselect LoRa module
}

void SPIreadBurst(unsigned char addr, unsigned char *ptr, unsigned char len)
{
    unsigned char i;
    unsigned char result;

    digitalWrite(SS, LOW); // Select LoRa module

    SPDR = addr; // Send address & Start transmission. In READ mode bit 7 of address is always 0! for sx1276
    while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
    {
};
    result = SPDR; // Discard first reading

    for (i=0; i <= len; i++){

        SPDR = 0; // Sending dummy byte to get the result
        while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
        {
};
        *ptr = SPDR; // move pointer

        ptr++;
    }
}

```

```

//DEBUG DEBUG DEBUG
Serial.print("\n");
// DEBUG DEBUG DEBUG

digitalWrite(SS, HIGH);    // Deselect LoRa module
}

void reset_sx1276(void)
{
digitalWrite(TXEN, LOW);
digitalWrite(RXEN, LOW);

digitalWrite(NRESET, LOW);
delay(10);
digitalWrite(NRESET, HIGH);
delay(20);
}

void Config_SX1276(void)
{
    // put in sleep mode to configure

    SPIwriteRegister(LR_RegOpMode,0x00);           // sleep mode, high frequency
    delay(10);

    SPIwriteRegister(REG_LR_TCXO,0x09);           // external crystal
    SPIwriteRegister(LR_RegOpMode,0x80);           // LoRa mode, high frequency

    SPIwriteRegister(LR_RegFrMsb,0xE4);
    SPIwriteRegister(LR_RegFrMid,0xC0);
    SPIwriteRegister(LR_RegFrLsb,0x00);           // frequency : 915 MHz

    SPIwriteRegister(LR_RegPaConfig,0xFF); // max output power PA_BOOST enabled

    SPIwriteRegister(LR_RegOcp,0x0B);             // close over current protection (ocp)
    SPIwriteRegister(LR_RegLna,0x23);             // Enable LNA

    SPIwriteRegister(LR_RegModemConfig1,0x72); // signal bandwidth : 125kHz,error coding= 4/5, explicit header mode

    SPIwriteRegister(LR_RegModemConfig2,0xC7);    // spreading factor : 12

    SPIwriteRegister(LR_RegModemConfig3,0x08);    // LNA? optimized for low data rate

    SPIwriteRegister(LR_RegSymbTimeoutLsb,0xFF); // max receiving timeout

    SPIwriteRegister(LR_RegPreambleMsb,0x00);
    SPIwriteRegister(LR_RegPreambleLsb,16);      // preamble 16 bytes

    SPIwriteRegister(REG_LR_PADAC,0x87);         // transmission power 20dBm
    SPIwriteRegister(LR_RegHopPeriod,0x00);      // no frequency hopping

    SPIwriteRegister(REG_LR_DIOMAPPING2,0x01);   // DIO5=ModeReady,DIO4=CadDetected
    SPIwriteRegister(LR_RegOpMode,0x01);         // standby mode, high frequency
}

void mode_tx(void)
{
    unsigned char addr,temp;

    digitalWrite(TXEN,HIGH);                     // open tx antenna switch
    digitalWrite(RXEN,LOW);

    SPIwriteRegister(REG_LR_DIOMAPPING1,0x41);    // DIO0=TxDone,DIO1=RxTimeout,DIO3=ValidHeader

    SPIwriteRegister(LR_RegIrqFlags,0xff);        // clearing interrupt
    SPIwriteRegister(LR_RegIrqFlagsMask,0xf7);    // enabling txdone
}

```

```

SPIwriteRegister(LR_RegPayloadLength,payload_length); // payload length

addr = SPIreadRegister(LR_RegFifoTxBaseAddr); // read TxBaseAddr
SPIwriteRegister(LR_RegFifoAddrPtr,addr); // TxBaseAddr->FifoAddrPtr

SPIwriteBurst(0x00,txbuf,payload_length); // write data in fifo
SPIwriteRegister(LR_RegOpMode,0x03); // mode tx, high frequency

digitalWrite(LED1, !digitalRead(LED1));

temp=SPIreadRegister(LR_RegIrqFlags); // read interput flag
while(!(temp&0x08)) // wait for txdone flag
{
    temp=SPIreadRegister(LR_RegIrqFlags);
}

digitalWrite(TXEN,LOW); // close tx antenna switch
digitalWrite(RXEN,LOW);

SPIwriteRegister(LR_RegIrqFlags,0xff); // clearing interupt
SPIwriteRegister(LR_RegOpMode,0x01); // standby mode, high frequency
}

void init_rx(void)
{
    unsigned char addr;

    digitalWrite(TXEN,LOW); // open rx antenna switch
    digitalWrite(RXEN,HIGH);

    SPIwriteRegister(REG_LR_DIOMAPPING1,0x01); //DIO0=00, DIO1=00, DIO2=00, DIO3=01 DIO0=00--RXDONE

    SPIwriteRegister(LR_RegIrqFlagsMask,0x3f); // enable rxdone and rxtimeout
    SPIwriteRegister(LR_RegIrqFlags,0xff); // clearing interupt

    addr = SPIreadRegister(LR_RegFifoRxBaseAddr); // read RxBaseAddr
    SPIwriteRegister(LR_RegFifoAddrPtr,addr); // RxBaseAddr->FifoAddrPtr
    SPIwriteRegister(LR_RegOpMode,0x05); // rx mode continuous high frequency
}

```

ARDUINO SOFTWARE RX

LORA1276RX.ino

```
/*
NiceRF LoRa1276 Module Arduino NANO Clone V3

NANO   LoRa1276
D11 MOSI 6 MOSI
D12 MISO 5 MISO
D13 SCK  4 SCK
D10     7 NSS

by absolutelyautomation.com

*/

// using SPI library:
#include <SPI.h>

// Digital pins definition
#define MOSI 11
#define MISO 12
#define SCK  13
#define SS   10

#define NRESET 7
#define TXEN   9
#define RXEN   8
#define LED1  A4
#define LED2  A5

// register definition

#define LR_RegFifo           0x00
#define LR_RegOpMode        0x01
#define LR_RegBitrateMsb    0x02
#define LR_RegBitrateLsb    0x03
#define LR_RegFdevMsb       0x04
#define LR_RegFdMsb         0x05
#define LR_RegFrMsb         0x06
#define LR_RegFrMid         0x07
#define LR_RegFrLsb         0x08
#define LR_RegPaConfig      0x09
#define LR_RegPaRamp        0x0A
#define LR_RegOcp           0x0B
#define LR_RegLna           0x0C
#define LR_RegFifoAddrPtr   0x0D
#define LR_RegFifoTxBaseAddr 0x0E
#define LR_RegFifoRxBaseAddr 0x0F
#define LR_RegFifoRxCurrentaddr 0x10
#define LR_RegIrqFlagsMask  0x11
#define LR_RegIrqFlags      0x12
#define LR_RegRxNbBytes     0x13
#define LR_RegRxHeaderCntValueMsb 0x14
#define LR_RegRxHeaderCntValueLsb 0x15
#define LR_RegRxPacketCntValueMsb 0x16
#define LR_RegRxPacketCntValueLsb 0x17
#define LR_RegModemStat     0x18
#define LR_RegPktSnrValue   0x19
#define LR_RegPktRssiValue  0x1A
#define LR_RegRssiValue     0x1B
#define LR_RegHopChannel    0x1C
#define LR_RegModemConfig1  0x1D
#define LR_RegModemConfig2  0x1E
#define LR_RegSymbTimeoutLsb 0x1F
#define LR_RegPreambleMsb   0x20
```

More info:

Absolutelyautomation.com

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```

#define LR_RegPreambleLsb      0x21
#define LR_RegPayloadLength    0x22
#define LR_RegMaxPayloadLength 0x23
#define LR_RegHopPeriod        0x24
#define LR_RegFifoRxByteAddr   0x25
#define LR_RegModemConfig3     0x26
#define REG_LR_DIOMAPPING1     0x40
#define REG_LR_DIOMAPPING2     0x41
#define REG_LR_VERSION         0x42
#define REG_LR_PLLHOP          0x44
#define REG_LR_TCXO            0x4B
#define REG_LR_PADAC           0x4D
#define REG_LR_FORMERTEMP      0x5B
#define REG_LR_AGCREF          0x61
#define REG_LR_AGCTHRESH1      0x62
#define REG_LR_AGCTHRESH2      0x63
#define REG_LR_AGCTHRESH3      0x64

// payload length
#define payload_length 7

// tx packet
unsigned char txbuf[payload_length]={'t','e','s','t','i','n','g'};
// rx packet
unsigned char rxbuf[30];

// Initialization
void setup() {
  byte temp = 0;

  // Initializing serial port, usefull for debugging
  Serial.begin(9600);

  // Initializing SPI pins

  pinMode(MOSI, OUTPUT);
  pinMode(MISO, INPUT);
  pinMode(SCK,OUTPUT);
  pinMode(SS,OUTPUT);
  digitalWrite(SS,HIGH); //disabling LoRa module

  // Initializing other I/O pins
  pinMode(NRESET, OUTPUT);
  pinMode(TXEN, OUTPUT);
  pinMode(RXEN, OUTPUT);
  pinMode(LED1, OUTPUT);
  pinMode(LED2, OUTPUT);

  digitalWrite(NRESET,HIGH); // Deassert reset
  digitalWrite(TXEN,LOW); // Disabling tx antenna
  digitalWrite(RXEN,LOW); // Disabling rx antenna
  digitalWrite(LED1,LOW);
  digitalWrite(LED2,LOW);

  /* Initializing SPI registers
  description of every SPCR register bits
  | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
  | SPIE | SPE | DORD | MSTR | CPOL | CPHA | SPR1 | SPR0 |

  SPIE - Enable SPI interrupt (logic 1)
  SPE - Enable SPI (logic 1)
  DORD - Send Least Significant Bit (LSB) first (logic 1) , Send Most Significant Bit (MSB) first (logic 0)
  MSTR - Enable SPI master mode (logic 1), slave mode (logic 0)
  CPOL - Setup clock signal inactive in high (logic 1), inactive in low (logic 0)
  CPHA - Read data on Falling Clock Edge (logic 1), Rising edge (logic 0)
  SPR1 y SPR0 - Setup SPI data rate: 00 Fastest (4MHz), 11 Slowest (250KHz)

```

```

// SPCR = 01010011
//interrupt disabled,spi enabled,most significant bit (msb) first,SPI master,clock inactive low,
data fech rising clock edge, slowest data rate*/

SPCR = (1<<SPE)|(1<<MSTR)|(1<<SPR1)|(1<<SPR0);
temp=SPSR; //Reading and discarding previous data
temp=SPDR; //Reading and discarding previous data
delay(10);

}

void loop() {

unsigned char temp,payload_size;

digitalWrite(LED1,LOW);
digitalWrite(LED2,LOW);

reset_sx1276();
Config_SX1276();          // initialize RF module

init_rx();                // rx mode

while(1){
temp=SPIreadRegister(LR_RegIrqFlags);          // read interupt
if(temp & 0x40){                               // wait for rxdone flag
SPIwriteRegister(LR_RegIrqFlags,0xff);        // clear interupt
temp = SPIreadRegister(LR_RegFifoRxCurrentaddr); // read RxCurrentaddr
SPIwriteRegister(LR_RegFifoAddrPtr,temp);      // RxCurrentaddr -> FiFoAddrPtr

payload_size = SPIreadRegister(LR_RegRxNbBytes); // read packet size
SPIreadBurst(0x00, rxbuf, payload_size);       // read from fifo

//"testing"
if( (rxbuf[0] == 'r') && (rxbuf[6] == 'g') )    // simple packet verification, please! use CRC flag for more robustness
{
digitalWrite(LED2, !digitalRead(LED2));        // Data OK toggle LED2
init_rx();
}
else
{
digitalWrite(LED1, !digitalRead(LED1));        // Data WRONG toggle LED1
init_rx();                                     // reinitialize rx when fail
}
}
}

}

byte SPIreadRegister(byte addr) {

byte result;

digitalWrite(SS, LOW);    // Select LoRa module

SPDR = addr;              // Send address & Start transmission. In READ mode bit 7 of address is always 0! for sx1276
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR;           // Discard first reading

SPDR = 0x0;              // Sending dummy byte to get the result
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
}
}
}

```

```

};
result = SPDR;          // Reading register value

digitalWrite(SS, HIGH); // Deselect LoRa module

return (result);

}

byte SPIwriteRegister(byte addr,byte value) {

byte result;

digitalWrite(SS, LOW); // Select LoRa module

SPDR = addr | 0x80;    // Send address & Start transmission. In WRITE mode bit 7 of address is always 1! for sx1276
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR;        // Discard first reading

SPDR = value;         // Sending byte
while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
{
};
result = SPDR;        // Discard second reading

digitalWrite(SS, HIGH); // Deselect LoRa module

}

void SPIwriteBurst(unsigned char addr, unsigned char *ptr, unsigned char len)
{
    unsigned char i;
    unsigned char result;

    digitalWrite(SS, LOW); // Select LoRa module

    SPDR = addr | 0x80;    // Send address & Start transmission. In WRITE mode bit 7 of address is always 1! for sx1276
    while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
    {
};
    result = SPDR;        // Discard first reading

    for (i=0; i <= len; i++){

        SPDR = *ptr;      // Sending bytes
        while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
        {
};
        result = SPDR;    // Discard second reading

        //DEBUG DEBUG DEBUG
        Serial.print(*ptr, HEX);
        //DEBUG DEBUG DEBUG

        ptr++;
    }

    //DEBUG DEBUG DEBUG
    Serial.print("\n");
    // DEBUG DEBUG DEBUG

    digitalWrite(SS, HIGH); // Deselect LoRa module

}

void SPIreadBurst(unsigned char addr, unsigned char *ptr, unsigned char len)
{
    unsigned char i;

```

```

    unsigned char result;

    digitalWrite(SS, LOW);    // Select LoRa module

    SPDR = addr;            // Send address & Start transmission. In READ mode bit 7 of address is always 0! for sx1276
    while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
    {
    };
    result = SPDR;        // Discard first reading

    for (i=0; i <= len; i++){

        SPDR = 0;        // Sending dummy byte to get the result
        while (!(SPSR & (1<<SPIF))) // Wait for transmission to finish
        {
        };
        *ptr = SPDR;    // move pointer

        ptr++;
    }

    //DEBUG DEBUG DEBUG
    Serial.print("\n");
    // DEBUG DEBUG DEBUG

    digitalWrite(SS, HIGH);    // Deselect LoRa module
}

void reset_sx1276(void)
{
    digitalWrite(TXEN, LOW);
    digitalWrite(RXEN, LOW);

    digitalWrite(NRESET, LOW);
    delay(10);
    digitalWrite(NRESET, HIGH);
    delay(20);
}

void Config_SX1276(void)
{
    // put in sleep mode to configure

    SPIwriteRegister(LR_RegOpMode,0x00);    // sleep mode, high frequency
    delay(10);

    SPIwriteRegister(REG_LR_TCXO,0x09);    // external crystal
    SPIwriteRegister(LR_RegOpMode,0x80);    // LoRa mode, high frequency

    SPIwriteRegister(LR_RegFrMsb,0xE4);
    SPIwriteRegister(LR_RegFrMid,0xC0);
    SPIwriteRegister(LR_RegFrLsb,0x00);    // frequency : 915 MHz

    SPIwriteRegister(LR_RegPaConfig,0xFF); // max output power PA_BOOST enabled

    SPIwriteRegister(LR_RegOcp,0x0B);    // close over current protection (ocp)
    SPIwriteRegister(LR_RegLna,0x23);    // Enable LNA

    SPIwriteRegister(LR_RegModemConfig1,0x72); // signal bandwidth : 125kHz,error coding= 4/5, explicit header mode

    SPIwriteRegister(LR_RegModemConfig2,0xC7);    // spreading factor : 12

    SPIwriteRegister(LR_RegModemConfig3,0x08);    // LNA? optimized for low data rate

    SPIwriteRegister(LR_RegSymbTimeoutLsb,0xFF); // max receiving timeout

```



```

    SPIwriteRegister(LR_RegPreambleMsb,0x00);
    SPIwriteRegister(LR_RegPreambleLsb,16);    // preamble 16 bytes

    SPIwriteRegister(REG_LR_PADAC,0x87);      // transmission power 20dBm
    SPIwriteRegister(LR_RegHopPeriod,0x00);   // no frequency hopping

    SPIwriteRegister(REG_LR_DIOMAPPING2,0x01); // DIO5=ModeReady,DIO4=CadDetected
    SPIwriteRegister(LR_RegOpMode,0x01);     // standby mode, high frequency
}

void mode_tx(void)
{
    unsigned char addr,temp;

    digitalWrite(TXEN,HIGH);                  // open tx antenna switch
    digitalWrite(RXEN,LOW);

    SPIwriteRegister(REG_LR_DIOMAPPING1,0x41); // DIO0=TxDone,DIO1=RxTimeout,DIO3=ValidHeader

    SPIwriteRegister(LR_RegIrqFlags,0xff);    // clearing interrupt
    SPIwriteRegister(LR_RegIrqFlagsMask,0xf7); // enabling txdone
    SPIwriteRegister(LR_RegPayloadLength,payload_length); // payload length

    addr = SPIreadRegister(LR_RegFifoTxBaseAddr); // read TxBaseAddr
    SPIwriteRegister(LR_RegFifoAddrPtr,addr);    // TxBaseAddr->FifoAddrPtr

    SPIwriteBurst(0x00,txbuf,payload_length); // write data in fifo
    SPIwriteRegister(LR_RegOpMode,0x03);       // mode tx, high frequency

    digitalWrite(LED1, !digitalRead(LED1));

    temp=SPIreadRegister(LR_RegIrqFlags);      // read interrupt flag
    while(!(temp&0x08))                        // wait for txdone flag
    {
        temp=SPIreadRegister(LR_RegIrqFlags);
    }

    digitalWrite(TXEN,LOW);                    // close tx antenna switch
    digitalWrite(RXEN,LOW);

    SPIwriteRegister(LR_RegIrqFlags,0xff);    // clearing interrupt
    SPIwriteRegister(LR_RegOpMode,0x01);     // standby mode, high frequency
}

void init_rx(void)
{
    unsigned char addr;

    digitalWrite(TXEN,LOW);                    // open rx antenna switch
    digitalWrite(RXEN,HIGH);

    SPIwriteRegister(REG_LR_DIOMAPPING1,0x01); //DIO0=00, DIO1=00, DIO2=00, DIO3=01 DIO0=00--RXDONE

    SPIwriteRegister(LR_RegIrqFlagsMask,0x3f); // enable rxdone and rxtimeout
    SPIwriteRegister(LR_RegIrqFlags,0xff);    // clearing interrupt

    addr = SPIreadRegister(LR_RegFifoRxBaseAddr); // read RxBaseAddr
    SPIwriteRegister(LR_RegFifoAddrPtr,addr);  // RxBaseAddr->FifoAddrPtr
    SPIwriteRegister(LR_RegOpMode,0x05);     // rx mode continuous high frequency
}

```